The iterated square root ideal ${ }^{1}$ and the sums of squares dual of a semidefinite program ${ }^{2}$

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Solving Polynomial Equations<br>Algebraic Geometry with a view towards applications Institut Mittag-Leffler Kungliga Tekniska högskolan, Stockholm February 21-25, 2011

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By Hilbert's Nullstellensatz (1893), $\sqrt{1}$ is the set of all polynomials vanishing on $V_{\mathbb{C}}(I)=\left\{x \in \mathbb{C}^{n} \mid \forall g \in I: g(x)=0\right\}$.

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To see this, let $a, b \in A$ and $s, t \in \sum A^{2}$ such that $a^{2}+s, b^{2}+t \in I$. Then $(a+b)^{2}+(a-b)^{2}+s+s+t+t=2\left(a^{2}+s\right)+2\left(b^{2}+t\right) \in I$.

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in particular

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\sqrt[r]{I}=\bigcup_{k \in \mathbb{N}} \sqrt[2^{k}]{I}
$$

and

$$
\sqrt[f]{I}=\sqrt[2^{k}]{l}
$$

for some $k \in \mathbb{N}$ if $A$ is noetherian.

A semidefinite characterization of the square root ideal

For each $k \in \mathbb{N}$, let $\overrightarrow{x_{k}}$ denote the column vector of the first $k$ monomials in $\mathbb{R}[\underline{X}]$ with respect to an arbitrary but fixed numbering of the monomials.

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If $I \subseteq \mathbb{R}[\underline{X}]$ is an ideal, then

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\begin{aligned}
\sqrt[2]{I}=\left\{\operatorname{pol}(W) \mid k, m \in \mathbb{N}, U \in S \mathbb{R}^{m \times m},\right. & W \in \mathbb{R}^{k \times m}, \\
& \left.\operatorname{pol}(U) \in I, U \succeq W^{*} W\right\} .
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Note that here $U \succeq W^{*} W \Longleftrightarrow\left(\begin{array}{cc}U & W^{*} \\ W & I_{k}\end{array}\right) \succeq 0$.

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$(P) \quad$ minimize $\quad c_{1} x_{1}+\cdots+c_{n} x_{n}$ subject to $\quad x \in \mathbb{R}^{n}$

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(D) maximize $-\operatorname{tr}\left(A_{0} S\right)$ subject to $\quad S \in S \mathbb{R}^{m \times m}$

$$
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\operatorname{tr}\left(A_{1} S\right)=c_{1}, \ldots, \operatorname{tr}\left(A_{n} S\right)=c_{n}
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$$
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$$

$$
c_{0}-a+c_{1} X_{1}+\cdots+c_{n} X_{n}=
$$

$$
\operatorname{tr}\left(A_{0} S\right)+X_{1} \operatorname{tr}\left(A_{1} S\right)+\cdots+X_{n} \operatorname{tr}\left(A_{n} S\right)
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$$
c_{0}+c_{1} X_{1}+\cdots+c_{n} X_{n}-a=
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$(P) \quad$ minimize $\ell(x)$
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$(P) \quad$ minimize $\quad \ell(x)$ subject to $\quad x \in \mathbb{R}^{n}$ $L(x) \succeq 0$
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$$
\begin{array}{cl}
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\text { subject to } & x \in \mathbb{R}^{n} \\
& L(x) \succeq 0
\end{array}
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(D) maximize a subject to $S \in S \mathbb{R}^{m \times m}, a \in \mathbb{R}$ $S \succeq 0$

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We call a polynomial $\ell \in \mathbb{R}[\underline{X}]$ linear if it is of degree at most 1, i.e., there are $c_{0}, c_{1}, \ldots, c_{n} \in \mathbb{R}$ such that $\ell=c_{0} X_{1}+c_{1} X_{1}+\cdots+c_{n} X_{n}$. We call a matrix polynomial $L \in \mathbb{R}[\underline{X}]^{m \times m}$ a pencil if it is symmetric and linear,

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We call a polynomial $\ell \in \mathbb{R}[\underline{X}]$ linear if it is of degree at most 1, i.e., there are $c_{0}, c_{1}, \ldots, c_{n} \in \mathbb{R}$ such that $\ell=c_{0} X_{1}+c_{1} X_{1}+\cdots+c_{n} X_{n}$.

We call a matrix polynomial $L \in \mathbb{R}[\underline{X}]^{m \times m}$ a pencil if it is symmetric and linear, i.e., there are $A_{0}, A_{1}, \ldots, A_{n} \in S \mathbb{R}^{m \times m}$ such that $L=A_{0}+X_{1} A_{1}+\cdots+X_{n} A_{n}$.

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A semidefinite program (P) and its standard dual (D) is given by a pencil $L \in \mathbb{R}[\underline{X}]^{m \times m}$ and a linear polynomial $\ell \in \mathbb{R}[\underline{X}]$ as follows:
$(P) \quad$ minimize $\quad \ell(x)$ subject to $\quad x \in \mathbb{R}^{n}$ $L(x) \succeq 0$
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(ii) $S=\sum_{i=1}^{r} Q_{i}^{*} Q_{i}$ for some $r \in \mathbb{N}_{0}$ and $Q_{i} \in \mathbb{R}[\underline{X}]^{m \times m}$,
(iii) $S=\sum_{i=1}^{t} w_{i} w_{i}^{*}$ for some $t \in \mathbb{N}_{0}$ and $w_{i} \in \mathbb{R}[\underline{X}]^{m}$.

Remark: The convex cone of sos-matrices of degree at most $2 d$ is semidefinitely representable, i.e., a projection of a spectrahedron. This is just a generalization of the well known Gram matrix method for $\mathbb{R}[\underline{X}]=\mathbb{R}[\underline{X}]^{1 \times 1}$ due to Kojima and Hol \& Scherer. In other words, being an sos-matrix of degree at most $2 d$ can be expressed as a constraint of a semidefinite program by means of additional variables. The size of the semidefinite description (of this constraint) depends polynomially on $n$ for fixed $d$.

A naive sos Farkas' lemma for semidefinite programming Observation: If $L \in \mathbb{R}[X]^{m \times m}$ is a pencil and $S \in \mathbb{R}[X]^{m \times m}$ is an sos-matrix, then $\operatorname{tr}(L S)$ is obviously a polynomial nonnegative on $S_{L}$.

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Problems: This gives a way of expressing infeasibility of an SDP by feasibility of another SDP whose size is however exponential. Moreover this is not yet strong duality.

## How to control the complexity?

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Now set $\vec{x}:=\left(\begin{array}{lllll}1 & X_{1} & X_{2} & \ldots & X_{n}\end{array}\right)^{*} \in \mathbb{R}[X]^{m}$ und

$$
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Lemma: Let $\ell_{1}, \ldots, \ell_{t} \in \mathbb{R}[\underline{X}]$ be linear and $q_{1}, \ldots, q_{t} \in \mathbb{R}[\underline{X}]$ be quadratic. Let $U \in \mathbb{R}^{m \times m}$ be such that

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Then there exists $\lambda>0$ and $W \in \mathbb{R}^{k \times m}$ such that $\lambda U \succeq W^{*} W$ and

$$
\vec{y}^{*} W \vec{x}=\ell_{1} q_{1}+\cdots+\ell_{t} q_{t}
$$

The sums of squares dual of a semidefinite program It can now be shown that the following provides a duality theory for semidefinite programming where strong duality (zero gap \& dual attainment) always holds. Note that the size of the dual (which we do not explicit) is polynomial in the size of the primal.

Theorem: Let $L \in \mathbb{R}[\underline{X}]^{m \times m}$ be a pencil and $\ell \in \mathbb{R}[\underline{X}]$ be linear. Then $\ell \geq 0$ on $S_{L}$ if and only if there exist

- quadratic sos-matrices $S_{1}, \ldots, S_{n} \in \mathbb{R}[\underline{X}]^{m \times m}$,
- matrices $U_{1}, \ldots, U_{n} \in S \mathbb{R}^{m \times m}, W_{1}, \ldots, W_{n} \in \mathbb{R}^{k \times m}$, $S \in S \mathbb{R}_{\succeq 0}^{m \times m}$ and
- a real number $a \geq 0$
such that

$$
\begin{array}{ll}
\vec{x}^{*} U_{i} \vec{x}+\vec{y}^{*} W_{i-1} \vec{x}+\operatorname{tr}\left(L S_{i}\right)=0 & (i \in\{1, \ldots, n\}), \\
U_{i} \succeq W_{i}^{*} W_{i} & (i \in\{1, \ldots, n\}), \\
\ell+\vec{y}^{*} W_{n} \vec{x}=a+\operatorname{tr}(L S) &
\end{array}
$$

where $W_{0}:=0$.

Based on other ideas, such a duality theory has also been given by Matt Ramana:
M. Ramana: An exact duality theory for semidefinite programming and its complexity implications
Math. Programming 77 (1997), no. 2, Ser. B, 129-162
http://citeseerx.ist.psu.edu/viewdoc/download?doi=10.1.1.
47.8540\&rep=rep1\&type=pdf
http://dx.doi.org/10.1007/BF02614433
See also:
Ramana \& Tunçel \& Wolkowicz: Strong duality for semidefinite programming
SIAM J. Optim. 7 (1997), Issue 3, 641-662 (1997)
http://www.math.uwaterloo.ca/~ltuncel/publications/
strong-duality.pdf
http://dx.doi.org/10.1137/S1052623495288350


[^0]:    ${ }^{1}$ joint work with Tim Netzer
    ${ }^{2}$ joint work with Igor Klep

