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# Numerik partieller Differentialgleichungen 2. Übungsblatt

# Exercise 4

(4 Points)

We consider the discretization of the partial differential equation

$$(Lu)(x,y) = f(x,y)$$
 for all  $(x,y) \in \Omega = (0,1) \times (0,1)$  (1a)

where

$$(Lu)(x,y) = -\Delta u(x,y) + a(x,y)u_x(x,y) + b(x,y)u_y(x,y) + c(x,y)u(x,y)$$

for all (x, y) on the unit square  $\Omega = (0, 1) \times (0, 1)$  with homogeneous Dirichlet boundary conditions

$$u(x,0) = u(x,1) = u(0,y) = u(1,y) = 0$$
 for  $x, y \in [0,1].$  (1b)

For general coefficients  $a, b, c, f \in C(\overline{\Omega})$  and  $c \ge 0$  in  $\Omega$ , the operator L is not self-adjoint and its discretization is not symmetric.

Discretize (1a) by a five-point centered difference scheme for  $\Delta$  with  $n^2$  points and mesh width  $h = \frac{1}{n+1}$ . and by centered difference schemes for the partial derivatives  $u_x$  and  $u_y$ .

The unknowns are denoted by

 $u_{ij} \approx u(x_i, y_j)$ 

where  $x_i = ih$  for  $i = 1, \ldots, n$ .

Compute the coefficient matrix  $A \in \mathbb{R}^{n^2 \times n^2}$  and the right-hand side  $b \in \mathbb{R}^{n^2}$  so that the discretization of (1) can be formulated as a linear system of the form

$$Au = b.$$

Formulate conditions such that is the matrix A is an  $L_0$ -matrix, i.e.  $a_{kl} \leq 0$  for all  $k \neq l$ .

**Remark:** The  $L_0$  condition is important in the stability analysis for numerical solution methods.

### Exercise 5

Consider the interval (a, b) and  $f \in \mathcal{C}^4((a, b), \mathbb{R})$ . Let  $n \in \mathbb{N}$ ,  $h = \frac{b-a}{n-1}$  and  $x_i = a + (i-1)h$  for  $i = 1, \ldots, n$ .

Show that for the discretization formulae

$$D_{x}^{+}f(x_{i}) = \frac{f(x_{i+1}) - f(x_{i})}{h}; \qquad D_{x}^{0}f(x_{i}) = \frac{f(x_{i+1}) - f(x_{i-1})}{2h}; \qquad (2)$$
  

$$D_{x}^{-}f(x_{i}) = \frac{f(x_{i}) - f(x_{i-1})}{h}; \qquad D_{xx}f(x_{i}) = \frac{f(x_{i+1}) - 2f(x_{i}) + f(x_{i-1})}{h^{2}}; \qquad (2)$$
  
one has  $D_{x}^{+}f - f' = \mathcal{O}(h), D_{x}^{-}f - f' = \mathcal{O}(h), D_{x}^{0}f - f' = \mathcal{O}(h^{2}) \text{ and } D_{xx}f - f'' = \mathcal{O}(h^{2}).$ 

## Exercise 6

(4 Points)

Let A be a block-tridiagonal matrix of the form

$$A = \begin{pmatrix} A_1 & C_1 & 0 & \dots & 0 \\ B_2 & A_2 & C_2 & & \\ & \ddots & \ddots & \ddots & \\ & & B_{n-1} & A_{n-1} & C_{n-1} \\ 0 & \dots & 0 & B_n & A_n \end{pmatrix},$$

where the  $A_l$ s  $(1 \le l \le n)$  are quadratic matrices of the size  $m_l$ . Further,  $B_l \in \mathbb{R}^{m_l \times m_{l-1}}$  for  $l = 2, \ldots, n$  and  $C_l \in \mathbb{R}^{m_l \times m_{l+1}}$  for  $l = 1, \ldots, n-1$  hold.

• Derive an algorithm which realizes the factorization

$$A = \begin{pmatrix} D_1 & 0 & 0 & \dots & 0 \\ B_2 & D_2 & & & \\ & \ddots & \ddots & & \\ & & B_{n-1} & D_{n-1} & 0 \\ 0 & \dots & 0 & B_n & D_n \end{pmatrix} \begin{pmatrix} E_1 & F_1 & 0 & \dots & 0 \\ 0 & E_2 & F_2 & & \\ & & \ddots & \ddots & \\ & & & E_{n-1} & F_{n-1} \\ 0 & \dots & 0 & 0 & E_n \end{pmatrix} =: LU,$$

where  $E_l \in \mathbb{R}^{m_l \times m_l}$  denote identity matrices.

If it is necessary, suppose the invertibility of certain matrices.

• Assume that the matrices

$$A^{(l)} = \begin{pmatrix} A_1 & C_1 & 0 & \dots & 0 \\ B_2 & A_2 & C_2 & & \\ & \ddots & \ddots & \ddots & \\ & & B_{l-1} & A_{l-1} & C_{l-1} \\ 0 & \dots & 0 & B_l & A_l \end{pmatrix}, \qquad l = 1, \dots, n-1,$$

are non-singular. Show that  $D_l^{-1}$  exist for  $l = 1, \ldots, n-1$ .

**Remark:** The LU-block decomposition is useful for the iterative solution of Au = b.

(4 Points)