Exercises for

Theory and Numerics of Partial Differential Equations

http://www.math.uni-konstanz.de/numerik/personen/mechelli/teaching.html

Exercise Sheet 8

Submission¹: 11th January at 10:00

Exercise 1. (Theory, 4 points)

Let $\Omega \subset \mathbb{R}^n$, $n \in \mathbb{N}$, be a bounded domain with C^1 -Boundary $\partial \Omega$. The scalar product between two functions $u, v \in C^0(\overline{\Omega})$ is defined as:

$$\langle u, v \rangle = \int_{\Omega} uv \, \mathrm{d}x$$

For a function $\psi \in C(\partial \Omega)$, let

$$D_{\psi} = \left\{ u \in C^1(\overline{\Omega}) \text{ s.t. } u(x) = \psi(x) \text{ for } x \in \partial \Omega \right\}$$

and consider the Differential Operator L:

$$L: C^2(\Omega) \cap D_0 \to C(\Omega)$$
, $Lu = -\Delta u$.

Prove that:

- i) $\langle Lu, v \rangle = \langle u, Lv \rangle$ for all $u, v \in C^2(\Omega) \cap D_0$,
- ii) L is a positive-definite operator.

Exercise 2. (Theory, 6 points)

We consider a one-dimensional stationary advection-diffusion-reaction equation:

$$-\underbrace{u''(x)}_{\text{Diffusion}} + \underbrace{b(x)u'(x)}_{\text{Advection}} + \underbrace{c(x)u(x)}_{\text{Reaction}} = \underbrace{f(x)}_{\text{Source term}} \quad \text{for all } x \in (0,1)$$

$$u(0) = u(1) = 0 \quad (1)$$

with c(x) > 0 and b(x) > 0 for all $x \in (0, 1)$. u describes the steady state of a substance contained in a flowing medium. The diffusion term describes the local spreading of the substance, the advection term represents the transport from the medium flow, the reaction term accounts for the reaction between substance and medium and the source term allows for external injection or extraction of the substance.

- 1. Discretize (1) by introducing an equidistant grid of [0,1], i.e. $\{x_0, x_1, \ldots, x_N\}$ with $x_i = ih = iN^{-1}$. $N \in \mathbb{N}$, and considering the Discrete Laplacian for the diffusion term and the central difference scheme² for the advection term. Write the discretized version of (1) as a linear problem $A\tilde{u} = r$.
- 2. A matrix $B = (B_{ij})_{i,j=1,\dots,N} \in \mathbb{R}^{N \times N}$ is called *strictly diagonally dominant* if $|B_{ii}| > \sum_{i=1}^{N} |B_{ij}|$ holds

for i = 1, ..., N. It can be shown that a strictly diagonally dominant matrix is always regular. Which assumption is required on h to be sure that the matrix A from above is strictly diagonally dominant and thus the discretization performed in 1. is well-defined?

3. In 2., you should have realized that the advection velocity field b(x) in (1) may cause problems for the discretization. Now, repeat 1. by using - instead of the central difference scheme - a so-called upwind $difference \ scheme^3$ for the discretization of the advection part.

$$2u'(x) \approx \frac{u(x+h) - u(x-h)}{u(x-h)}$$

 ${}^{2}u'(x) \approx \frac{u(x+h)-u(x-h)}{2h}$ ${}^{3}u'(x) \approx \frac{u(x)-u(x-h)}{h}$

¹The Theory Exercises will be collected at the begin of the lecture. The Programming Exercises has to be sent by email to luca.mechelli@uni-konstanz.de (group of Tuesday) and to hai.nguyen-pham@uni-konstanz.de (group of Wednesday) before the submission's deadline.

4. If we denote the problem resulting from 3. by $A^{SU}\tilde{u} = r^{SU}$, check again the diagonal dominance of A^{SU} as in 2. What do you observe?

Exercise 3. (Programming, 6 points)

Let $u \in C^2([0, L], \mathbb{R})$ with L > 0 and consider the following one-dimensional Poisson Problem:

$$\begin{cases} -u''(x) = f(x) & \text{for } x \in (0, L) \\ u(0) = u(L) = 0 \end{cases}$$
(2)

with $f \in C^0([0, L], \mathbb{R})$. In the main file main_8_3, solve (2) numerically with finite difference method following these instructions:

- 1. Choose the number of nodes N + 1 and generate finite difference grid of [0, L] corresponding to the N + 1 nodes x_0, \ldots, x_N .
- 2. Build the matrix A which represents the *Discrete Laplacian* operator on the grid and the right hand side b which represents the values of f(x) on the grid. Solve the linear system with the MATLAB backslash command \setminus for different f(x):
 - i. $f_1(x) = \frac{p(x)}{T}$, where p(x) = 5 x(x L) represents the magnitude of a transverse distributed load, to which a string of length L under constant tension T = 10 is subjected. The solution $u_1(x)$ represent the transverse displacement at point x.
 - ii. $f_2(x) = \frac{q(x)}{k}$, where $q(x) = \frac{100}{\sqrt{2\pi}}e^{-16(2x-L)^2}$ represents a distributed volumetric heat source applied to a homogeneous heat conducting bar of length L, where the bar's temperature $u_2(x)$ is maintained at zero at the end points. k = 80 is the constant heat conductivity of the iron at ambient temperature. (To be precise, in the model we have assumed that the transversal section of the rectangular parallelepiped bar is a square.)
- 3. Plot the solution $u_1(x)$ and $u_2(x)$.

Exercise 4. (Programming, 4 points)

Write a program which generates a two-dimensional finite differences grid of a set $\Omega \subset \mathbb{R}^2$. This is supposed to be done by calling a function

whose output is a variable of the type struct, taking two input arguments:

- 1. box is a variable of the type struct and contains information about a rectangle $[a_1, b_1] \times [a_2, b_2] \subset \mathbb{R}^2$, which is a superset of the original set: $\Omega \subset [a_1, b_1] \times [a_2, b_2]$. The variable box contains the corner points of the rectangle in a matrix range= $[a_1, b_1; a_2, b_2]$ and a 2x1 vector Nx, for the creation of the $(Nx(1)+1) \times (Nx(2)+1)$ rectangular grid.
- 2. indFunc stands for a function $\mathbb{1}_{\Omega} : \mathbb{R}^2 \to \{0, 1\}$ which indicates for every point $x \in \mathbb{R}^2$ if it is contained in Ω or not, meaning that it holds for all $x \in \mathbb{R}^2$: $\mathbb{1}_{\Omega}(x) = 1 \Leftrightarrow x \in \Omega$. indFunc is of the class function_handle and has the form ind = indFunc(x1,x2), expecting two vectors x1, x2 of same length and returning a logical vector ind of same size such that ind(i) indicates if the point with the coordinates x1(i) and x2(i) lies in Ω .

In function compute_fd_grid you have to:

- i. Create the vector box.x1 and box.x2 containing the discretization nodes of each interval $[a_1, b_1]$ and $[a_2, b_2]$;
- ii. Generate the rectangular grid with the MATLAB command ndgrid, which gave in output the grid points coordinates as two matrices grid.X1 grid.X2;
- iii. Build a coordinate list grid.Nodes_List such that grid.Nodes_List(:,i) contains the (x_1, x_2) -coordinates of the *i*-th grid point and save the number of grid points in to grid.Num_Nodes;
- iv. According to indFunc, walk over grid.Nodes_List and remove⁴ all the points of the rectangle which are outside of the domain Ω . (Change also grid.Num_Nodes)

To resume: The output variable grid should contain box, X1, X2, Nodes_List and Num_Nodes. Test your generated function by calling the script main_8_4, downloadable by the above url.

⁴Hint: By iterating over the points in grid.Nodes_List in reverse order - i.e. from grid.Nodes_List(:,end) to grid.Nodes_List(:,1) - you can eliminate the appropriate columns directly by the command grid.Nodes_List(:,i) = []. This would not be possible in forward order (why?).