# Asymptotic Investigation of the Lattice-Boltzmann Method and Grid Coupling



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## Introduction

**Project:** *Consistent* grid coupling algorithms for LB methods

Motivation: A priori grid refinement

**Problem:** Standard LB-algorithm: only on uniform grids !







#### **Strategy:**

- understand simple cases
- generalize to complicated problems



# Domain<sub>P</sub>Breacherpheentents



**Remark:** Any *smooth* solution is a *weak* solution.  $v_1, v_2$  smooth: When  $\tilde{v}$  is a *global weak* solution, i.e.  $\forall \phi \in \mathcal{C}_c^{\infty}(\mathcal{I} \times \mathcal{U})$ :

$$-\int_{\mathcal{I}\times\mathcal{U}} (\tilde{v}\partial_t\phi + \nu\nabla\tilde{v}\cdot\nabla\phi) \stackrel{!}{=} \sum_{i=1}^2 \int_{\mathcal{I}\times\mathcal{U}_i} (\partial_t v_i - \nu\Delta v_i)\phi = \int_{\mathcal{I}\times\mathcal{U}} g\phi$$

 $\Leftrightarrow$  Interface conditions:

$$v_1|_{\Gamma} \stackrel{!}{=} v_2|_{\Gamma} \wedge \mathbf{n} \cdot \nabla v_1|_{\Gamma} \stackrel{!}{=} \mathbf{n} \cdot \nabla v_2|_{\Gamma}$$

Physical meaning: equality of v and its normal flux (heat flow through  $\Gamma$ ) 1D model problem: Coupling conditions:  $v_1(t,\xi) = v_2(t,\xi) \wedge \partial_x v_1(t,\xi) = \partial_x v_2(t,\xi)$ 

## **D1P2-Model for the Heat Equation**



#### **Discrete LBE** with diffusive scaling:

 $P(t + h^{2}, x + sh, s) - P(t, x, s) = \frac{1}{\tau} \left( \frac{1}{2} U(t, x) - P(t, x, s) \right) + \frac{1}{2} h^{2} g(t, x)$  **Remark:**  $U \approx v |_{\mathcal{T}(h^{2}) \times \mathcal{G}(h)}$  with  $\partial_{t} v - \nu \partial_{x}^{2} v = g$   $\nu = \tau - \frac{1}{2}$  **Working hypothesis:**   $\exists$  smooth functions  $p^{(l)} : \mathbb{R}_{0}^{+} \times [0, L] \times S \to \mathbb{R}$   $0 \le l \le 4$  $\exists$  bounded grid function  $R : \mathcal{H} \times \mathcal{T}(h^{2}) \times \mathcal{G}(h) \times S \to \mathbb{R}$ 

$$P = p^{(0)} + h p^{(1)} + \dots + h^4 p^{(4)} + h^5 R \quad (ansatz)$$

## **Formal Asymptotic Analysis**

- $u^{(l)} := p_1^{(l)} + p^{(l)_2}$ , plug ansatz into discrete LBE: assume equation valid  $\forall (t, x) \in \mathbb{R}_0^+ \times [0, L], h > 0$
- Finite difference  $\rightarrow$  Taylor  $\sum_{l=0}^{4} h^{l} \left[ h^{2} \partial_{t} \mathbf{p}^{(l)} + h \operatorname{s} \partial_{x} \mathbf{p}^{(l)} + \frac{1}{2} h^{2} \partial_{x}^{2} \mathbf{p}^{(l)} \right] + O(h^{3}) = \frac{1}{\tau} \sum_{l=0}^{4} h^{l} \left[ \frac{1}{2} u^{(l)} - \mathbf{p}^{(l)} \right] + \frac{1}{2} h^{2} g$
- Collect terms of equal order in h

$$h^{0}: p^{(0)} = \frac{1}{2}u^{(0)}$$

$$h^{1}: p^{(1)} = \frac{1}{2}u^{(1)} - \tau s\partial_{x}p^{(0)}$$

$$h^{2}: p^{(2)} = \frac{1}{2}u^{(2)} - \tau s\partial_{x}p^{(1)} - \frac{1}{2}\tau\partial_{x}^{2}p^{(0)} - \tau\partial_{t}p^{(0)} + \frac{1}{2}\tau g \quad \text{sum over s}$$

$$\Rightarrow \quad \partial_{t} u^{(0)} - (\tau - \frac{1}{2}) \quad \partial_{x}^{2} u^{(0)} = g$$

• **Observation:** Since  $u^{(0)} = v$ :  $U = v + h u^{(1)} + O(h^2)$ 

## Formal Asymptotic Analysis (cont.)

- $3^{rd}$  order:  $\partial_t u^{(1)} (\tau \frac{1}{2}) \partial_x^2 u^{(1)} = 0$
- Therefore:  $u^{(1)} \equiv 0$  if  $U(0, \cdot) = v(0, \cdot) + 0 \frac{h}{h} + \dots$
- 4<sup>th</sup> order:  $\partial_t u^{(2)} (\tau \frac{1}{2}) \partial_x^2 u^{(2)} = \text{RHS}$ RHS =  $-(\tau^3 - 2\tau^2 + \frac{2}{3}\tau - \frac{1}{3}) \partial_x^4 u^{(0)} - (\tau^2 - \frac{3}{2}\tau + \frac{1}{4}) \partial_x^2 g - \frac{1}{2} \partial_t g$
- **Observation:** Discrete LBE: 2<sup>nd</sup> order consistent to heat equation.

 $U = v + h^2 u^{(2)} + O(h^3)$ 

- Relation between v and  $P = p^{(0)} + h p^{(1)} + h^2 p^{(2)} + O(h^3)$ :  $p^{(0)} = \frac{1}{2}v$   $p^{(1)} = -\frac{1}{2}\tau s \partial_x v$   $p^{(2)} = u^{(2)}$  $p^{(3)} = u^{(3)} - \frac{1}{2}\tau s \partial_x u^{(2)} + \frac{1}{2}\tau (\tau - 1) s \partial_x \partial_t v + \frac{1}{12}\tau s (3\tau - 1) \partial_x^3 v$
- $F := h^{-1} (P_2 P_1) = -\tau \partial_x v + O(h^2)$



- Translate: macroscopic condition  $\rightarrow$  mesoscopic LB level
- Refinement factor:  $N \in \mathbb{N}$ :  $h_f = h$ ,  $h_c = N h$   $v_{\text{left}} \stackrel{!}{=} v_{\text{right}} \Rightarrow P_{c,1} + P_{c,2} = P_{f,1} + P_{f,2}$  $\partial_x v_{\text{left}} \stackrel{!}{=} \partial_x v_{\text{right}} \Rightarrow P_{c,1} - P_{c,2} = N (P_{f,1} - P_{f,2})$ (\*)
- solve for empty pops:  $P_{c,1}$ ,  $P_{f,2}$

#### Analysis of the Coupling Condition:

- Separate asymptotic ansatz for coarse and fine grid with  $h_c$ ,  $h_f$  as above
- Plug into (\*)  $\rightarrow$  equate terms of equal order w.r.t. h
- Extract interface conditions for  $u^{(0)}, u^{(1)}, u^{(2)}$



## D1P2 Model: Numeric Test - Snapshot t = 0.8

Example:  $\nu = 0.001 \Rightarrow \tau = 0.501$  domain:  $\mathbb{T}^1$   $v(t, x) = J(t) \cos(2\pi x), \quad f := -\tau \partial_x v(t, x) = J(t) 2\pi\tau \sin(2\pi x)$   $g(t, x) = J(t) 4\pi^2 \nu \cos(2\pi x) + J'(t) \cos(2\pi x)$ Uniform coarse grid: 20 nodes, interface nodes: 5 (left), 15 (right), N = 2







Setting: nu=0.001, M=10, West=3, East=8, N=2, maxIt=200, Step=10, InitMode=1, InitPhase=0.5, Frequency=1, smoothStart with source



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## **LB-Models**

	D1P2	DAR 1D	$\nu = \tau$	$Q(u, s) = \frac{1}{2}u \left(1 + \epsilon sa - \epsilon^2 \tau c\right)$	$\mathrm{k}=\tfrac{1}{2}g$
$1 \qquad 3 \qquad 2$ $1 \qquad 1 \qquad 1 \qquad 1$ $\frac{1}{2n} \qquad \frac{n-1}{n} \qquad \frac{1}{2n}$	D1P3	11	$\nu = \frac{\tau}{n}$	$Q(u, s) = w_s u \left(1 + \epsilon n s a - \epsilon^2 \tau c\right)$	$\mathrm{k}=\mathrm{w_{s}}~g$
$3 \qquad 1 \\ 4 \qquad 4$	D2P4	DAR 2D	$\nu = \frac{\tau}{2}$	$Q(u, \mathbf{s}) = \frac{1}{4}u \left(1 + 2\boldsymbol{\epsilon} \mathbf{s} \cdot \mathbf{a} - \boldsymbol{\epsilon}^2 \tau c\right)$	$\mathbf{k}=\tfrac{1}{4}g$
	D2P4X	71	u =  au	$Q(u, \mathbf{s}) = \frac{1}{4}u \left(1 + \boldsymbol{\epsilon} \mathbf{s} \cdot \mathbf{a} - \boldsymbol{\epsilon}^2 \tau c\right)$	$\mathbf{k}=\tfrac{1}{4}g$
	D2P9	Stokes- Oseen	$\nu = \frac{\tau}{3}$	$Q(p, \mathbf{u}, \mathbf{s}) = 3 \mathbf{w}_{\mathbf{s}}(p + \mathbf{s} \cdot \mathbf{u}) \dots + 9 \mathbf{w}_{\mathbf{s}} \epsilon [3(\mathbf{s} \cdot \mathbf{a}) (\mathbf{s} \cdot \mathbf{u}) - \mathbf{a} \cdot \mathbf{u}]$	$k = 3w_s s \cdot g$

Limit equations: i)  $\partial_t u + \partial_x (au - \nu \partial_x u) + cu = g$  (DAR 1D) ii)  $\partial_t u + \nabla \cdot (au - \nu \nabla u) + cu = g$  (DAR 2D) iii)  $\partial_t u + \mathbf{a} \cdot \nabla \mathbf{u} - \nu \Delta \mathbf{u} = -\nabla p + \mathbf{g}$   $\nabla \cdot \mathbf{u} = 0$ 

**Remark:** 2D LB-models reduce to 1D LB-models in case of translational invariance.

## **Coupling for other LB Models**

#### D1P2:

 $\#\{\text{macroscopic coupling cond.}\} = \#\{\text{empty interface pops}\} = \#\{\text{pops per node}\}$ 

## **Challenges:**

- i) #{macroscopic coupling conditions} < #{empty interface pops} too much LB interface-conditions → contradictive w.r.t. macroscopic level
- ii) 2D: hanging nodes  $\rightarrow$  spatial interpolation
- iii) 2D: corner nodes  $\leftarrow$  boundary not smooth (!)
- iv) Generally: initial layers  $\Rightarrow$  working assumption violated

## **Possible problems:**

- i) loss of  $2^{nd}$  order consistency for moments of  $1^{st}$  and higher order
- ii) reduction of stability

#### **D2P9 Model: Numeric Test - Snapshot** t = 0.5Benchmark: domain $\mathbb{T}^2$ , $\nu = 0.01$ $\tau = 0.53$

Stationary eigenmode of Stokes operator with smooth initialization ( $\mathbf{u} = J(t)\mathbf{e}$ )



Grid Coupling for LB Methods



Setting: nu=0.01, M=10, SWx=3, SWy=3, NEx=8, NEy=8, N=2, maxIt=150, Step=5, InitMode=1, InitPhase=0.5, Frequency=1, smoothStart with forcing, Method=v5cubic(Coupling)/spline(Overlapping)



**D2P9 Model:** Numeric Test -  $L^{\infty}$  Error of *P* versus *ds* 

Setting: nu=0.01, M=10, SWx=3, SWy=3, NEx=8, NEy=8, N=2, maxIt=150, Step=5, InitMode=1, InitPhase=0.5, Frequency=1, smoothStart with forcing, Method=v5cubic(Coupling)/spline(Overlapping)