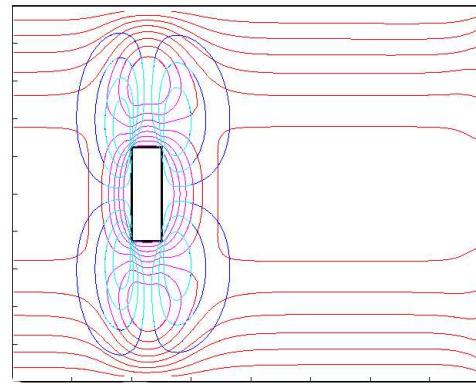


A Consistent Grid Coupling Method for Lattice-Boltzmann Schemes



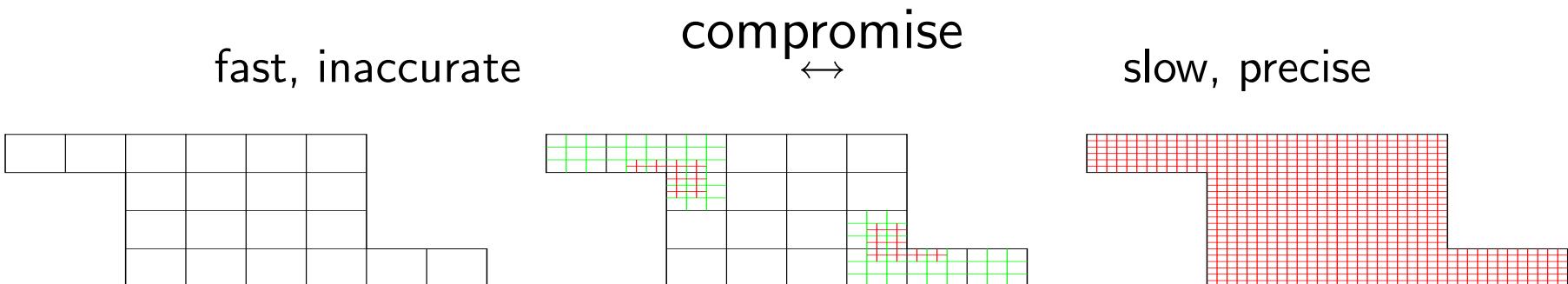
Martin Rheinländer
Fraunhofer ITWM, Kaiserslautern
Fachbereich Mathematik, TU Kaiserslautern

ICMMES, Braunschweig
July 26-29, 2004

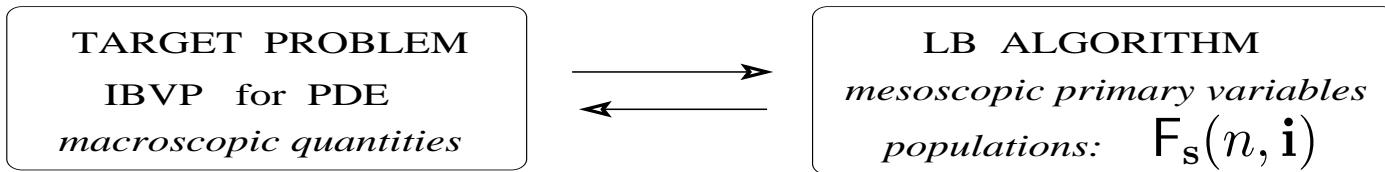
Overview

- Introduction to LB schemes and their analysis
- Paradigmatic model: D1P3 (advection-diffusion)
- Coupling condition & Coupling algorithm
- Numerical tests (convergence study, error snapshots)
- Grid coupling for the D2P9 model (Stokes flow)

Why grid coupling ?



Lattice-Boltzmann Schemes



- Velocity space: $\mathcal{S} \subset \{-1, 0, 1\}^d$ (DdPb model on cubic grid $b := \#\mathcal{S}$)
- Moments: $M := \sum_{\mathbf{s} \in \mathcal{S}} \mu(\mathbf{s}) F_s \rightarrow \text{macroscopic quantities}$
- LBGK equation on a cubic space grid with mesh size h :

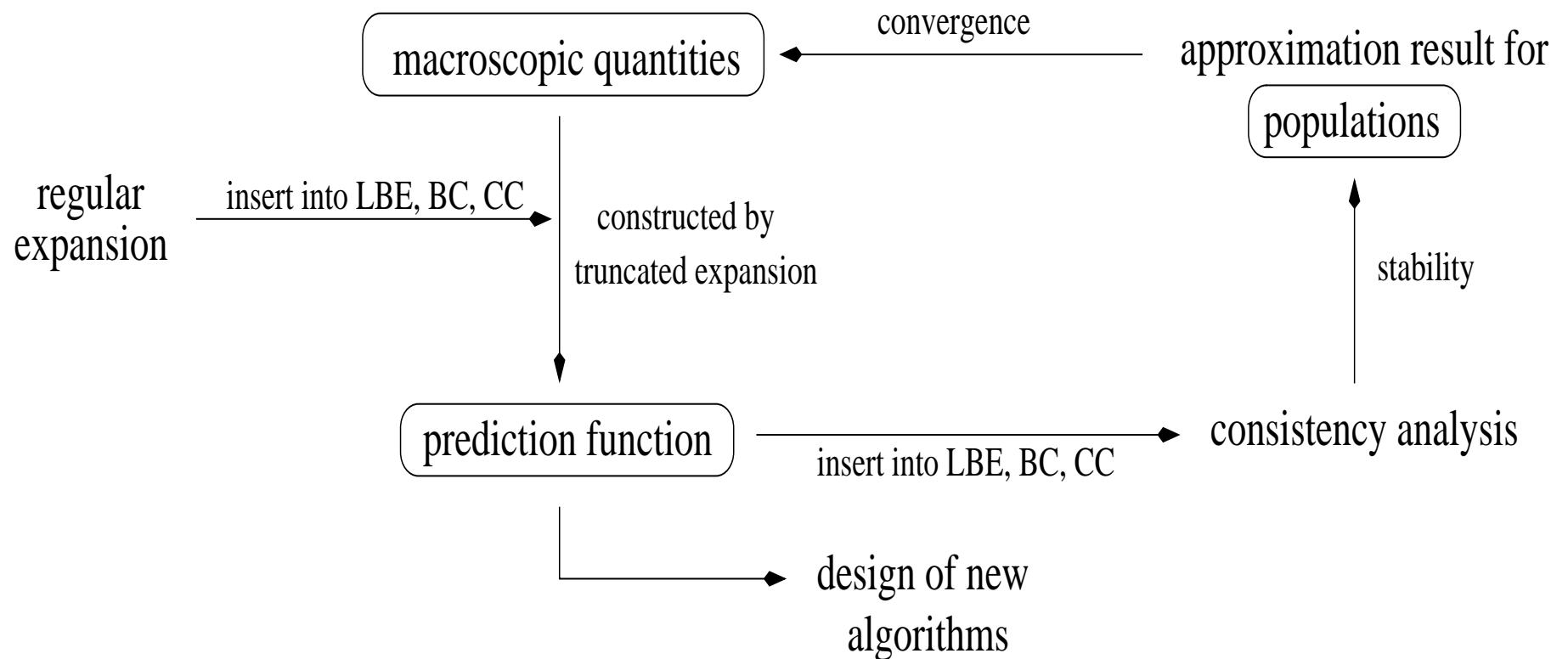
$$F_s(n+1, \mathbf{i} + \mathbf{s}) = (1 - \omega) F_s(n, \mathbf{i}) + \omega E_s(n, \mathbf{i}) + h^2 Q_s(n, \mathbf{i})$$

- Equilibrium $E_s = \mathcal{E}_s(M_0(n, \mathbf{i}), \dots)$
- Indices: $t_n = nh^2$, $x_{\mathbf{i}} = \mathbf{i}h$ (diffusive scaling)

Analysis of LB Algorithms

Regular expansion w.r.t. to mesh size h (*Junk et al.*):

$$F_s(n, \mathbf{i}) = f_s^{(0)}(nh^2, \mathbf{i}h) + h f_s^{(1)}(nh^2, \mathbf{i}h) + h^2 f_s^{(2)}(nh^2, \mathbf{i}h) + \dots$$



An Exemplary LB Model: D1P3

$$\left. \begin{array}{l} u(0, \cdot) = u_0 \\ \partial_t u + a \partial_x u - \nu \partial_x^2 u = q \end{array} \right\} \quad \leftrightarrow \quad \left\{ \begin{array}{l} \mathcal{S} = \{-1, 0, 1\} \equiv \{\ominus, 0, \oplus\} \\ \mathcal{E}_s(U) = w_s U + h \theta s w_s a U \\ \nu = \frac{1}{\theta} \left(\frac{1}{\omega} - \frac{1}{2} \right) \end{array} \right.$$

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- Macroscopic quantities: $u(t, x)$, $f(t, x) := [a - (\nu + \frac{1}{2\theta})\partial_x] u(t, x)$
- 0th & 1st asymptotic order: $f_s^{(0)} := w_s u$, $f_s^{(1)} := \theta w_s s f$

An Exemplary LB Model: D1P3

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- Prediction function: $\mathbf{f}_s(t, x) := \mathbf{f}_s^{(0)}(t, x) + h \mathbf{f}_s^{(1)}(t, x)$
- Approximation result: $\mathbf{F}_s(n, i) = \mathbf{f}_s(nh^2, ih) + O(h^2)$

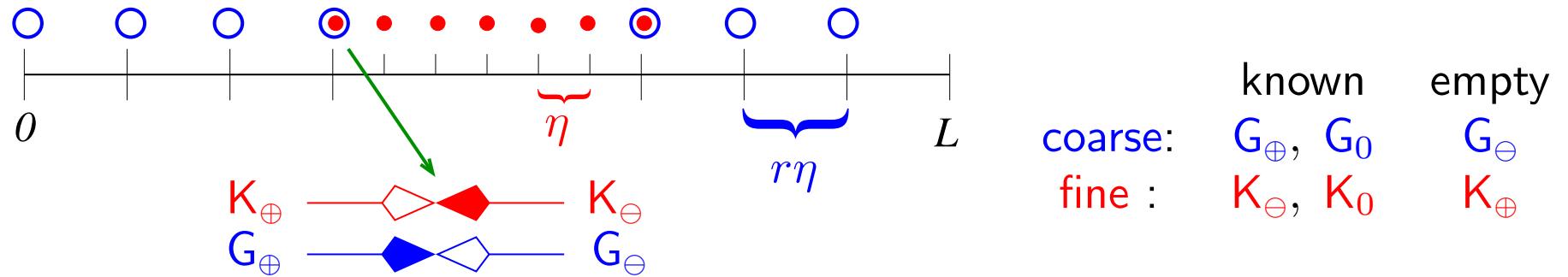
An Exemplary LB Model: D1P3

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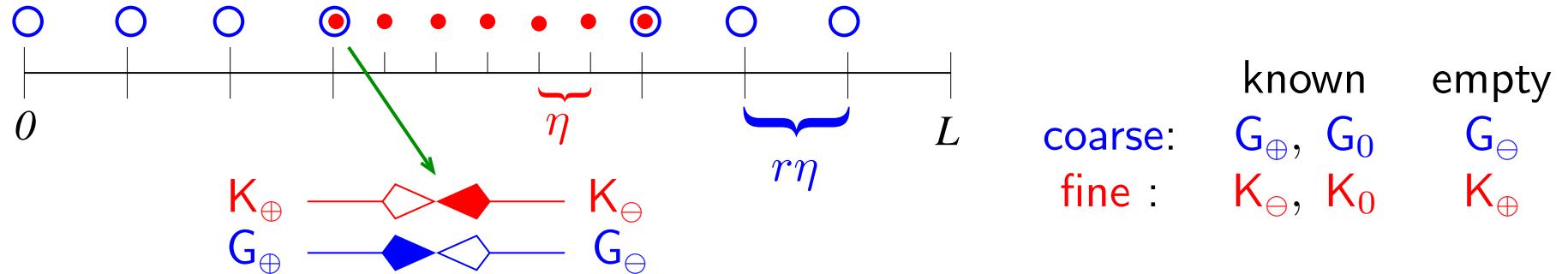
- Macroscopic quantities: $u(t, x)$, $f(t, x) := [a - (\nu + \frac{1}{2\theta})\partial_x] u(t, x)$
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- Approximation result: $F_s(n, i) = f_s(nh^2, ih) + O(h^2)$

$$\implies \left\{ \begin{array}{l} U(n, i) := \sum_{s \in \mathcal{S}} F_s(n, i) = u(nh^2, ih) + O(h^2) \quad 0^{\text{th}} \text{ moment} \\ F(n, i) := h^{-1} \sum_{s \in \mathcal{S}} s F_s(n, i) = f(nh^2, ih) + O(h^2) \quad 1^{\text{st}} \text{ moment} \end{array} \right.$$

The Coupling Condition



The Coupling Condition

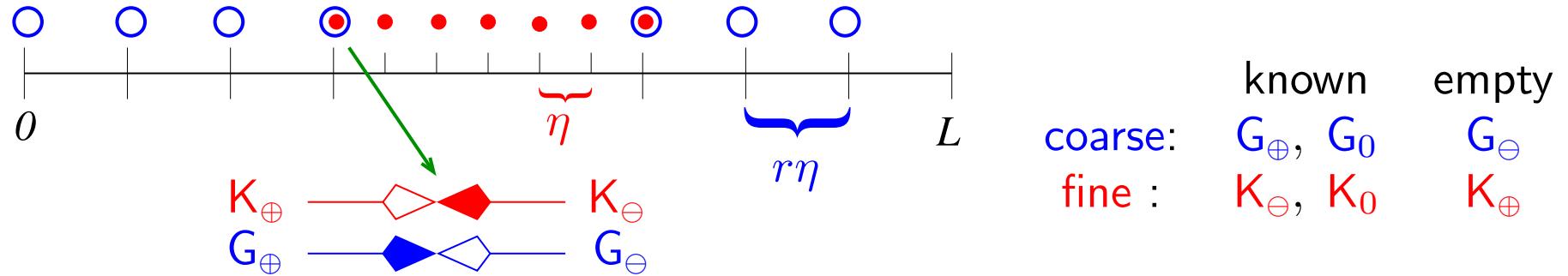


Direct exchange of populations ? \rightarrow vary with $h \Rightarrow \text{@: 1}^{\text{st}}$ order CC

Grid transformation of populations \rightarrow overlap of subgrids

- i) equilibrium/non-equilibrium part: (*Filippova, Hänel, Krafczyk, Chopard*)
- ii) preservation of moments (not yet published)

The Coupling Condition



Direct exchange of populations ? \rightarrow vary with h \Rightarrow \circlearrowleft : 1st order CC

Grid transformation of populations \rightarrow overlap of subgrids

- i) equilibrium/non-equilibrium part: (*Filippova, Hänel, Krafczyk, Chopard*)
- ii) preservation of moments (not yet published)

Idea: equate quantities varying with h^2 (moments) \leftarrow continuity of u, f

implicit cond.: $\sum_{s \in S} G_s = \sum_{s \in S} K_s , \quad \frac{1}{r\eta} \sum_{s \in S} s G_s = \frac{1}{\eta} \sum_{s \in S} s K_s$

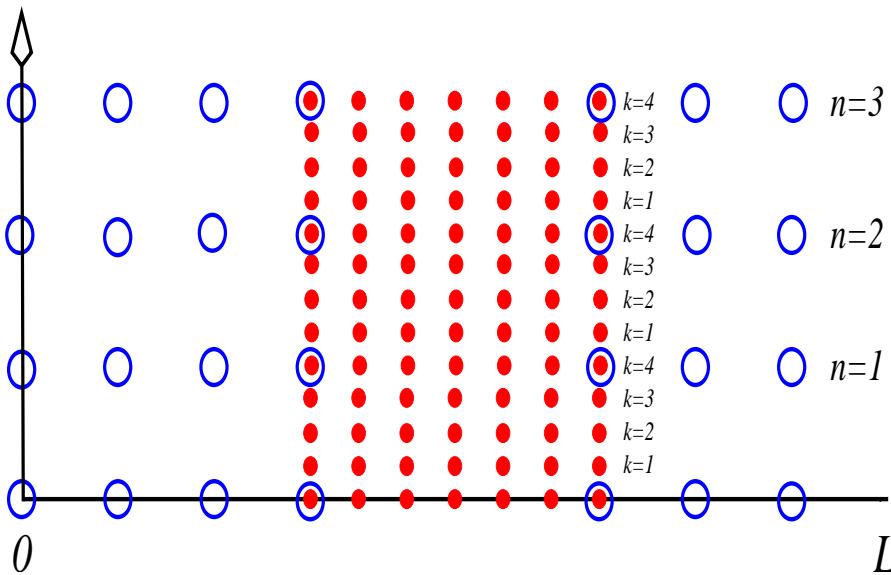
explicit cond.:
$$\begin{aligned} G_- - K_+ &= K_0 + K_- - G_0 - G_+ \\ G_- + rK_+ &= rK_- + G_+ \end{aligned} \Rightarrow \begin{pmatrix} 1 & -1 \\ 1 & r \end{pmatrix}$$

The Coupling Algorithm

refinement factor $r \in \mathbb{N}$

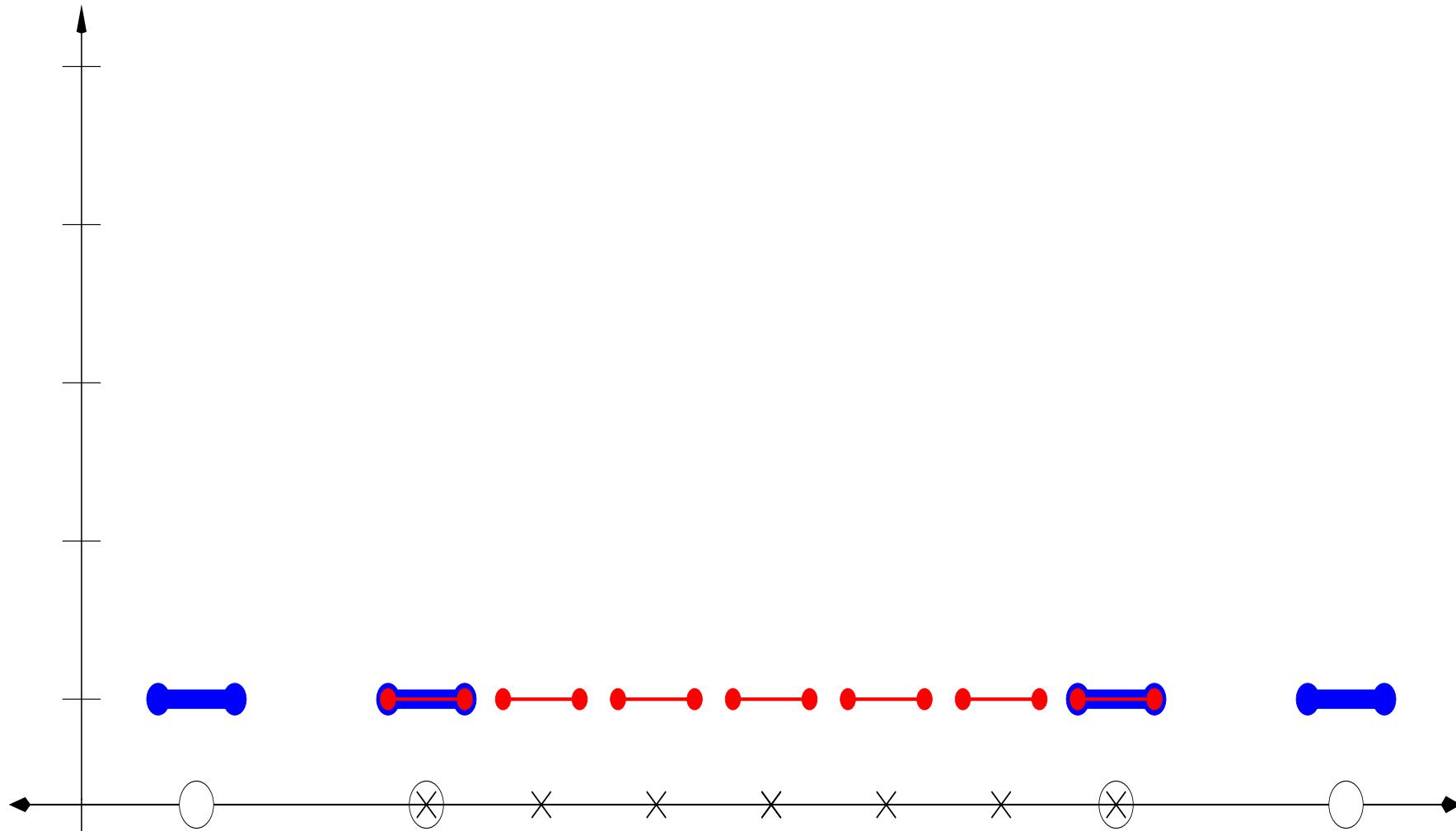
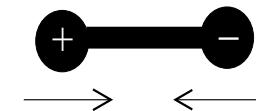
$$\begin{array}{ll} \text{fine grid-size: } & \eta \Rightarrow \text{coarse grid-size: } r\eta \\ \text{fine time-step: } & \eta^2 \Rightarrow \text{coarse time-step: } r^2\eta^2 \end{array} \Rightarrow$$

linear interpolation in time at coarse grid interface for intermediate time steps

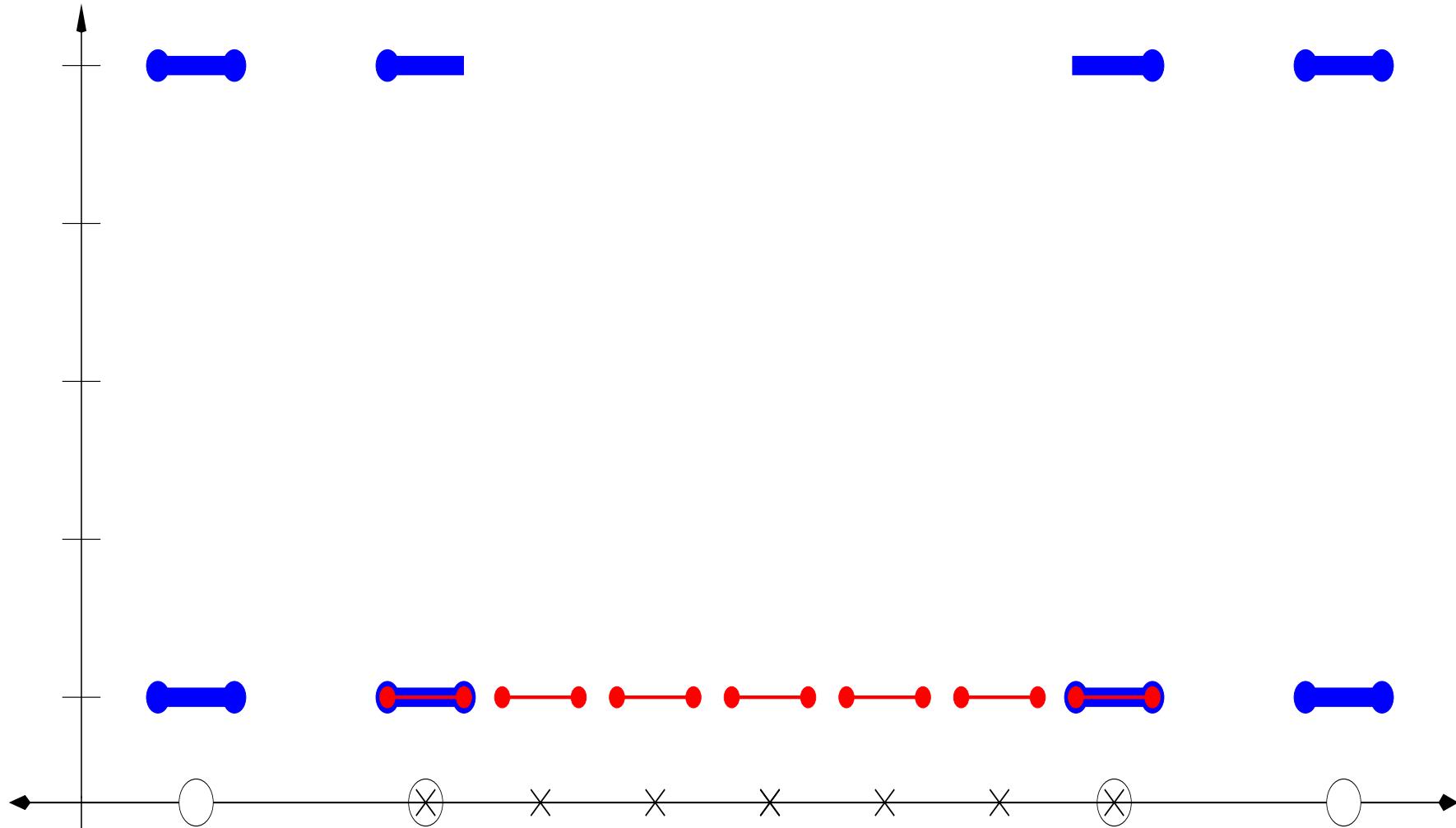


```
global TimeStep:  
    collide & propagate on coarse-grid  
    interpolate known coarse-grid interface-pops  
    repeat  $r^2$  times  
        collide & propagate on fine-grid  
        fill empty fine-grid interface-pops  
    end  
    fill empty coarse-grid interface-pops
```

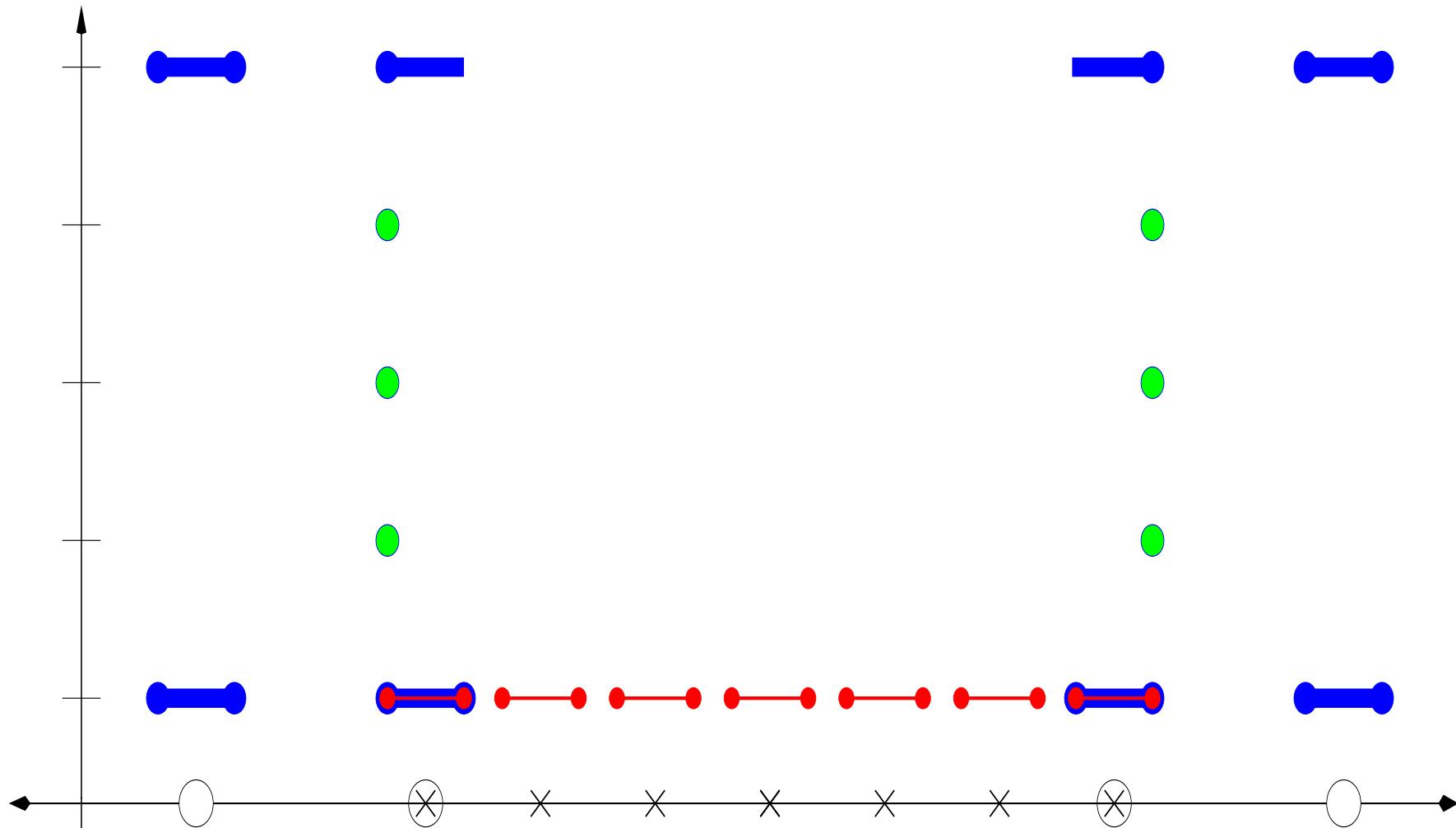
00/11) start: all populations known



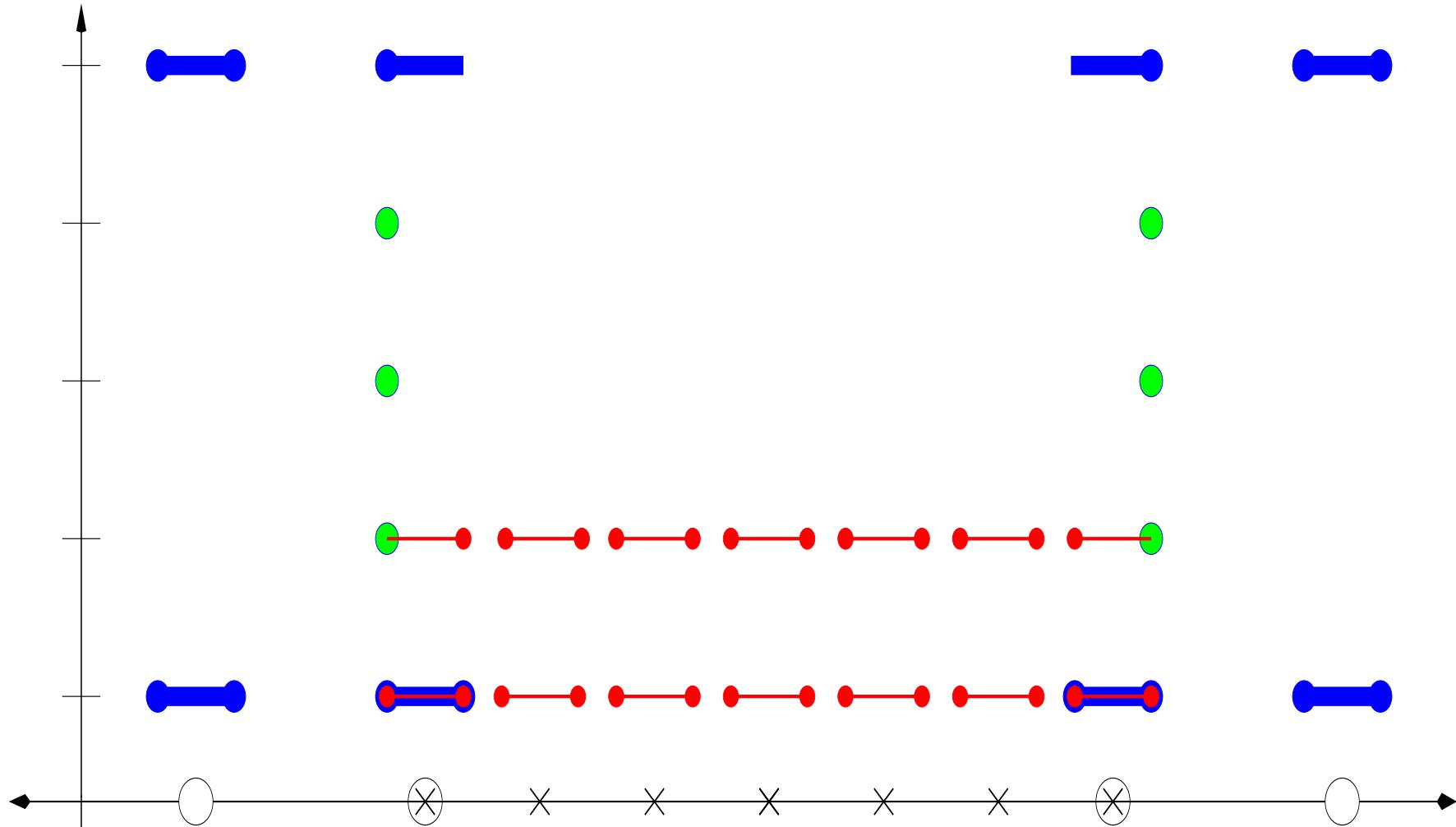
01/11) collide & propagate on coarse-grid



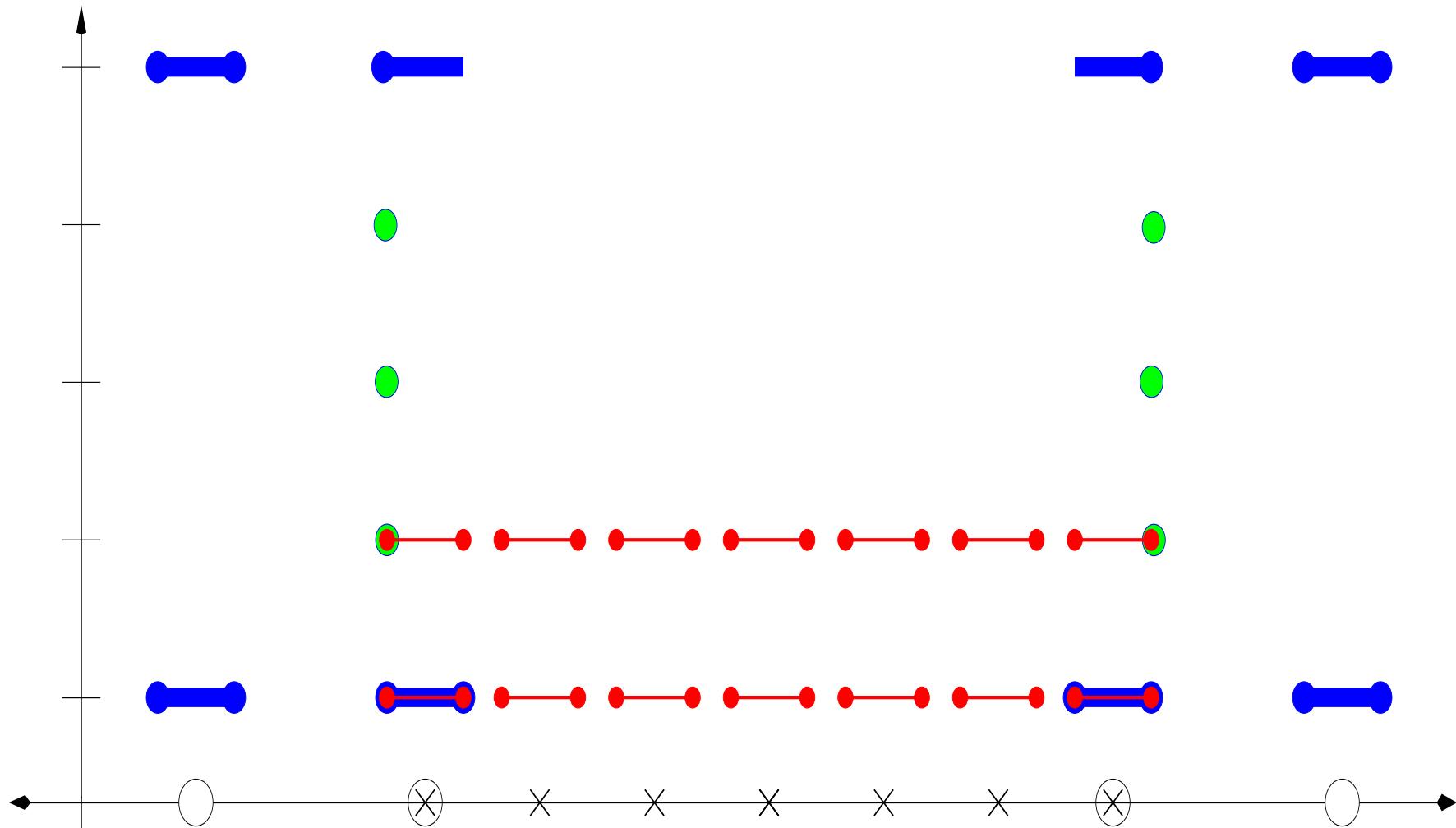
02/11) interpolate known coarse-grid interface-pops



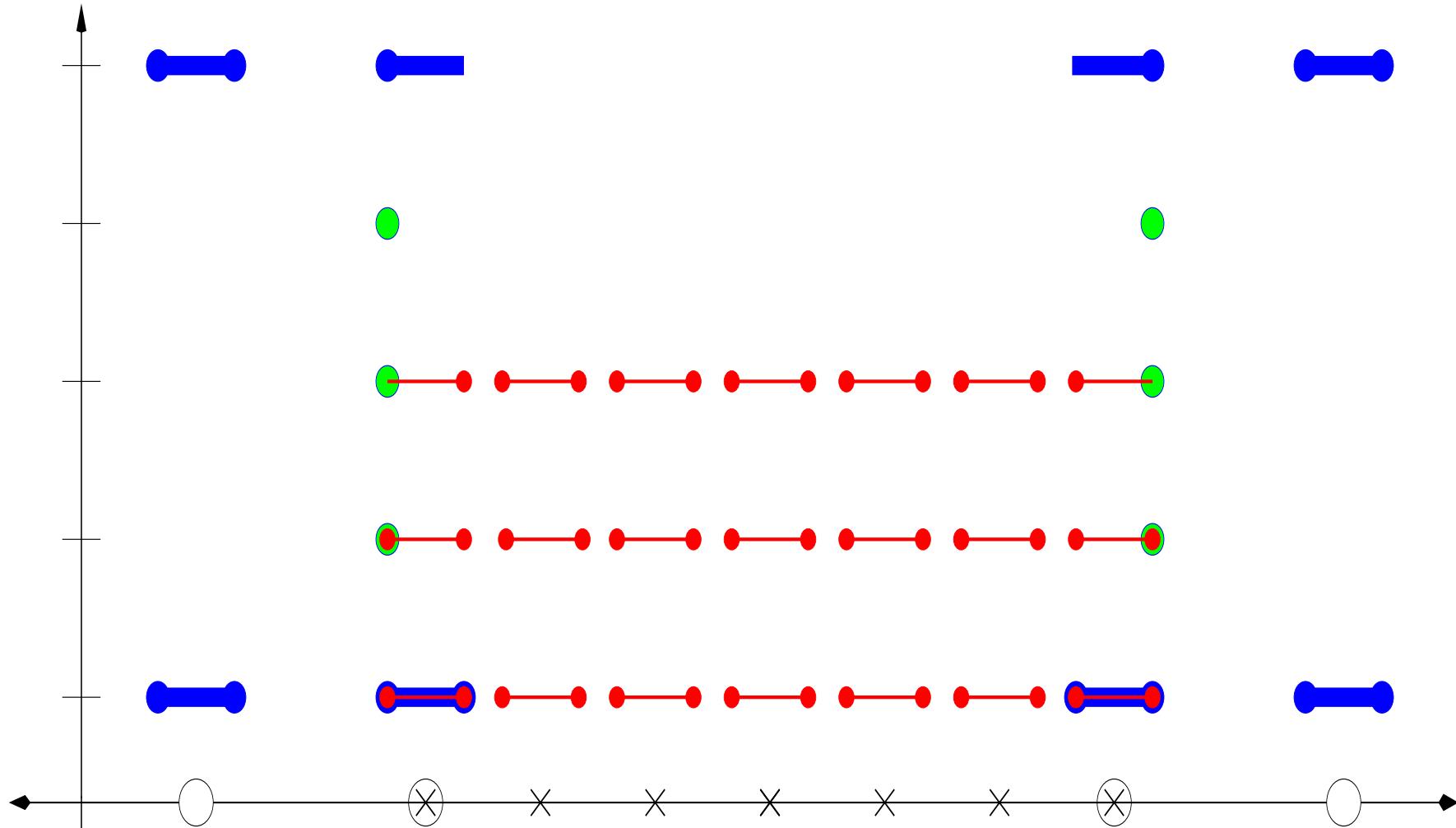
03/11) 1: collide & propagate on fine-grid



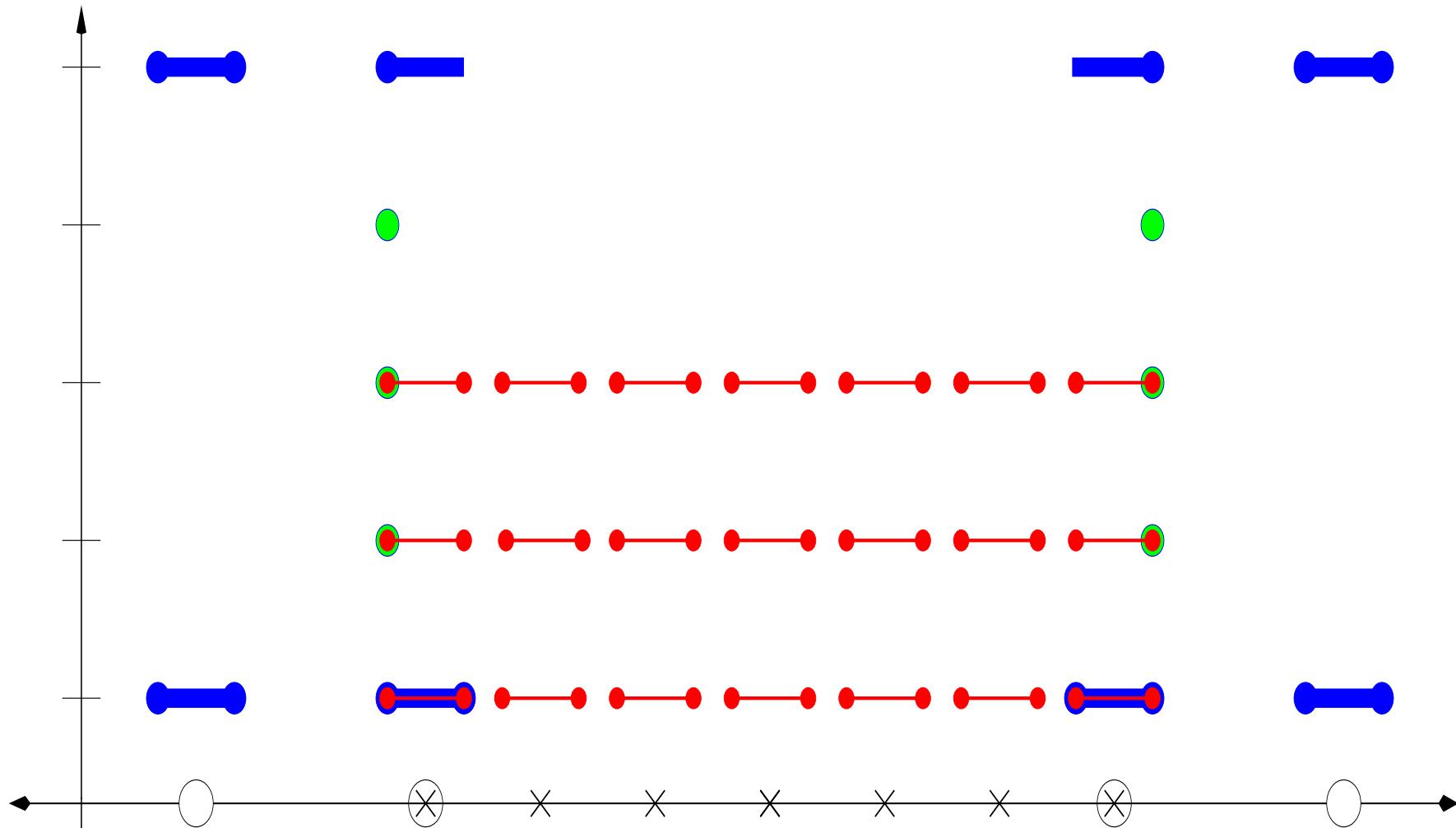
04/11) 1: fill empty fine-grid interface-pops



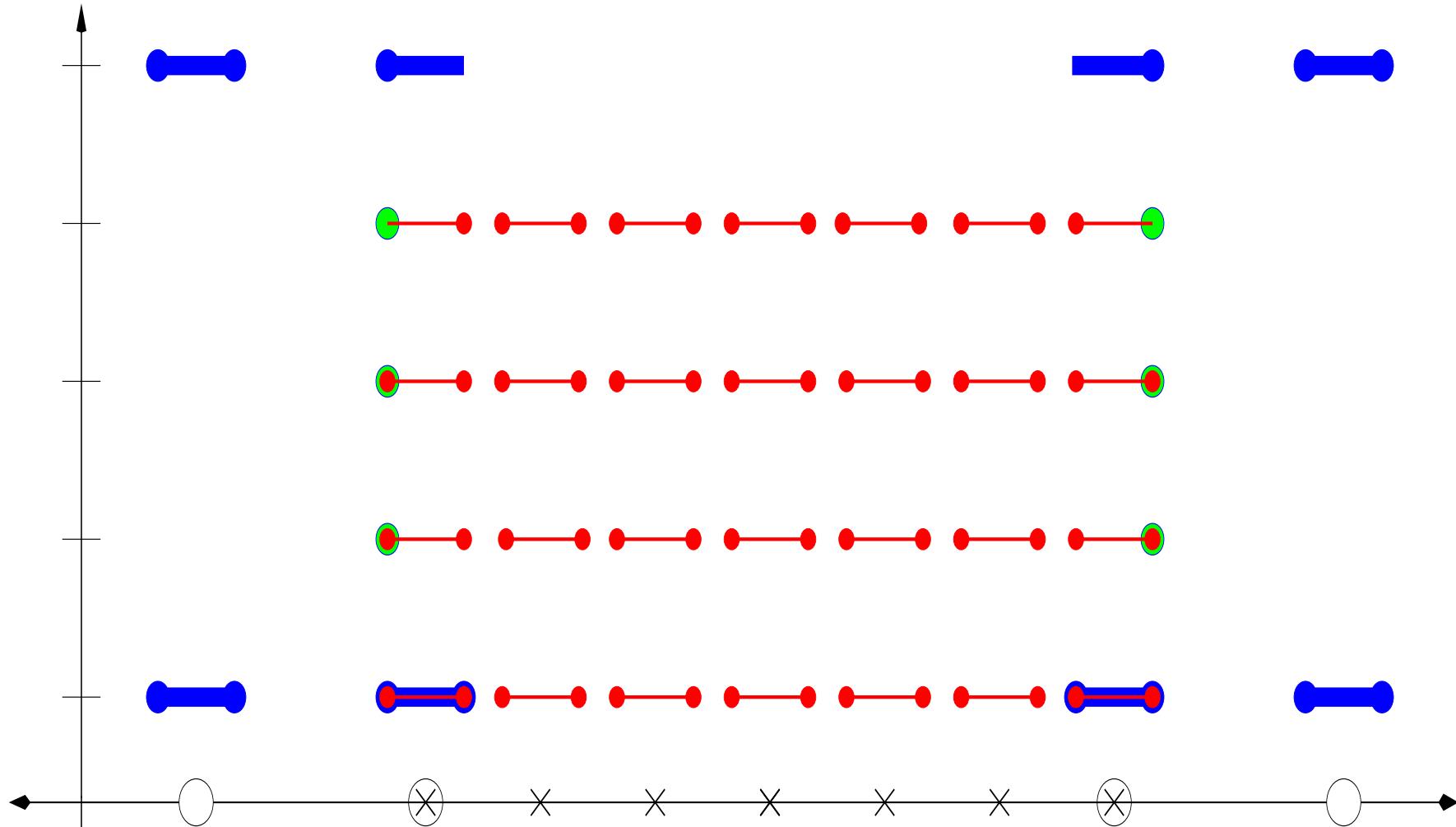
05/11) 2: collide & propagate on fine-grid



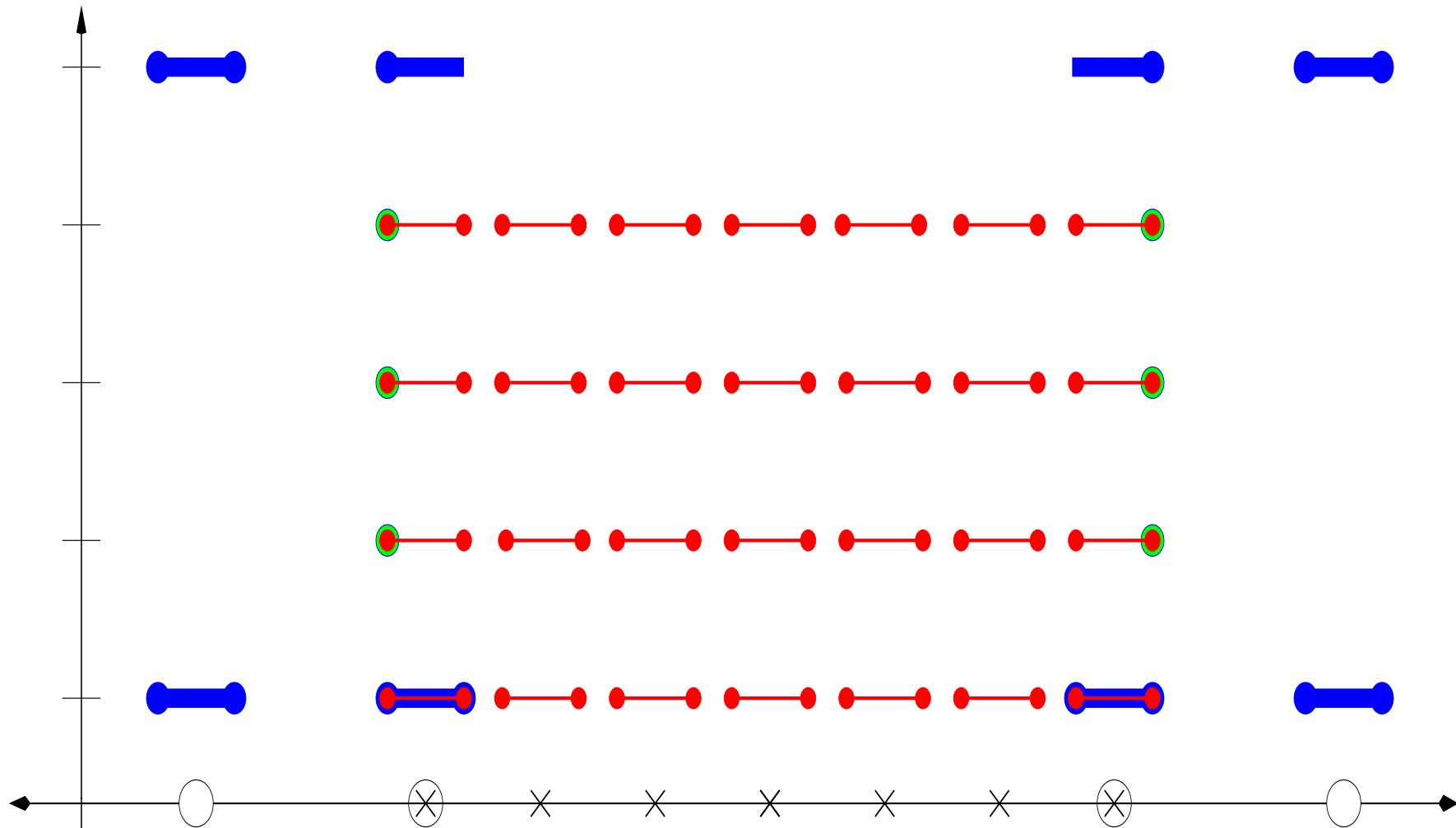
08/11) 2: fill empty fine-grid interface-pops



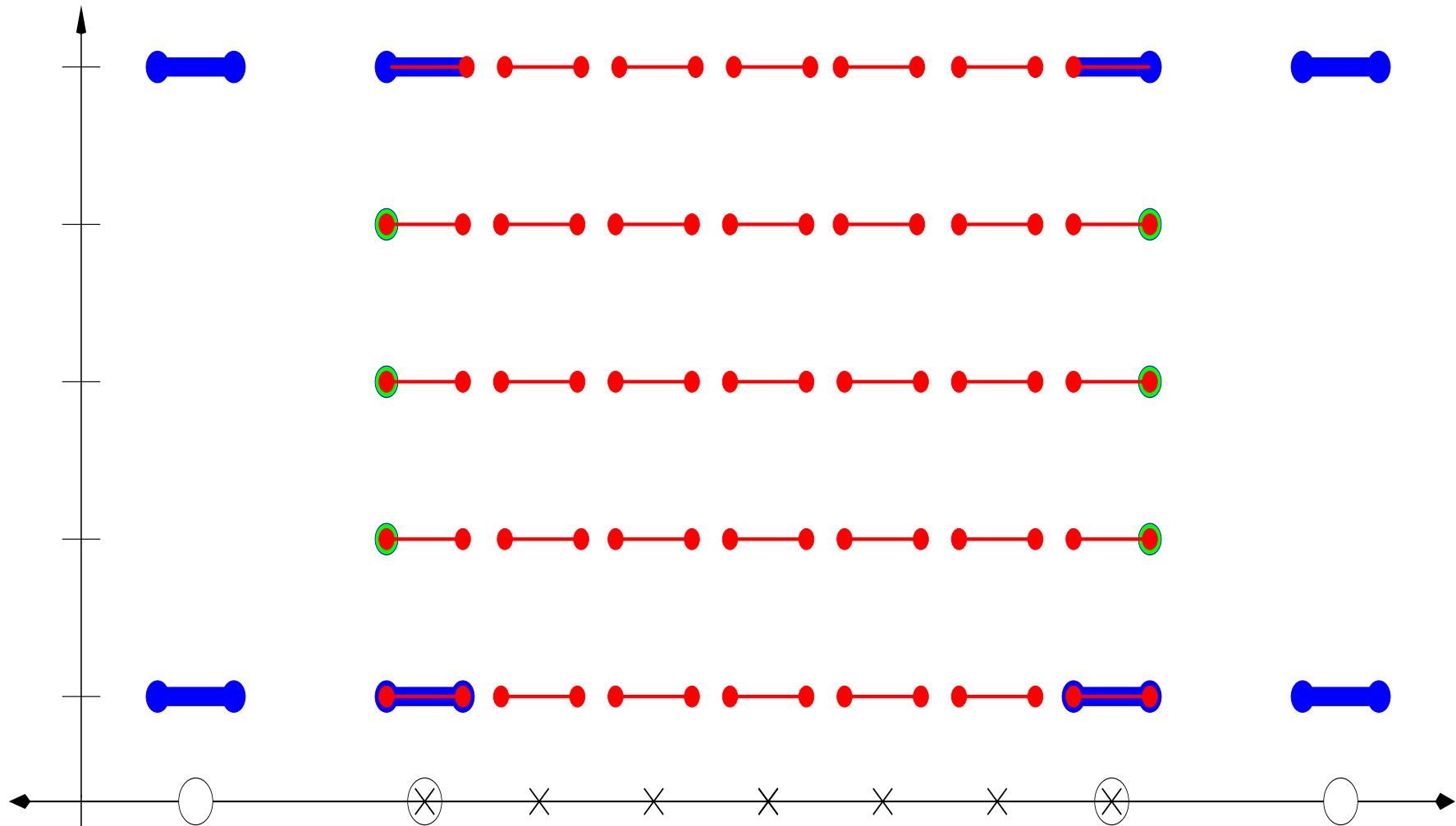
07/11) 3: collide & propagate on fine-grid



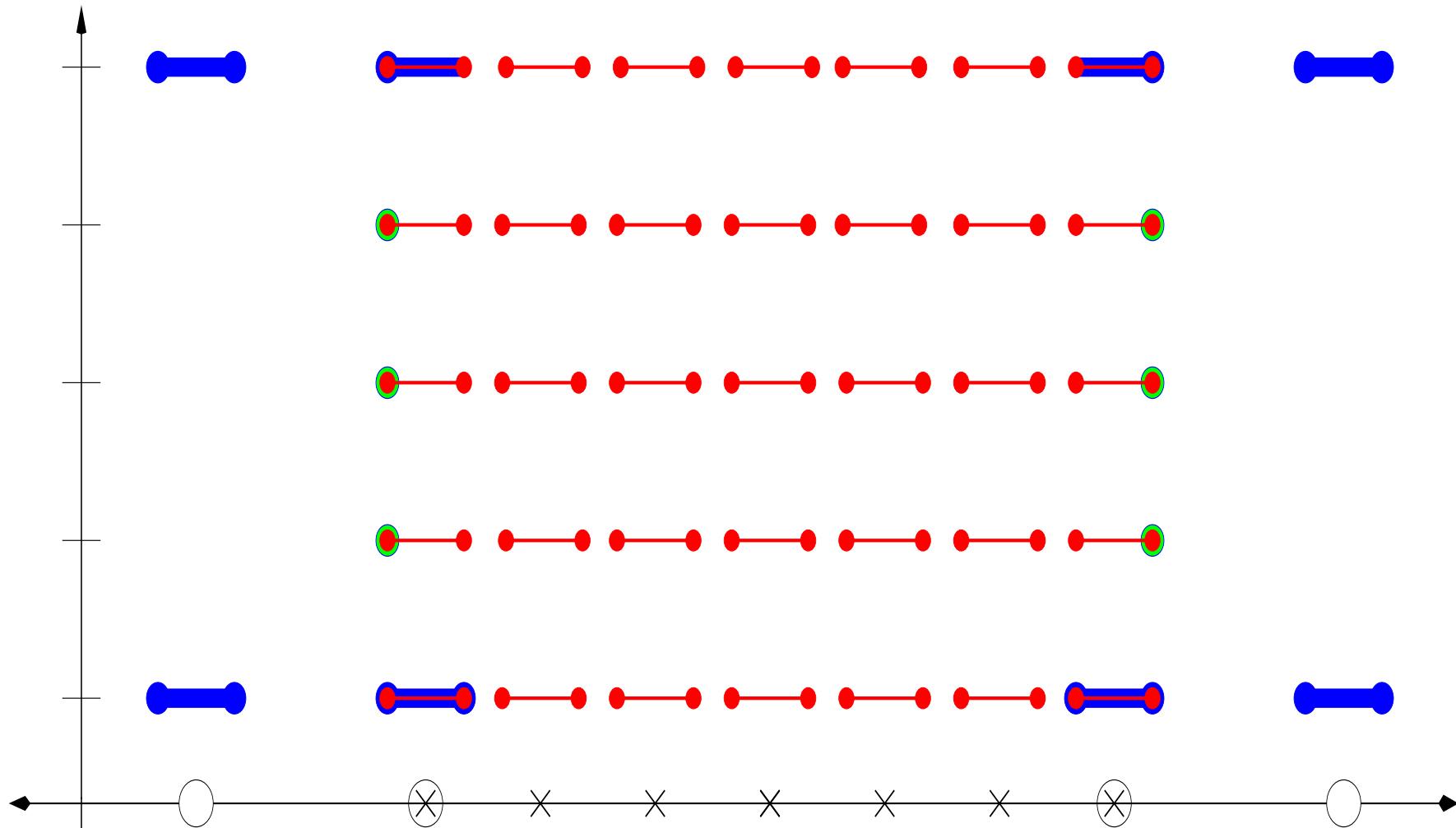
08/11) 3: fill empty fine-grid interface-pops



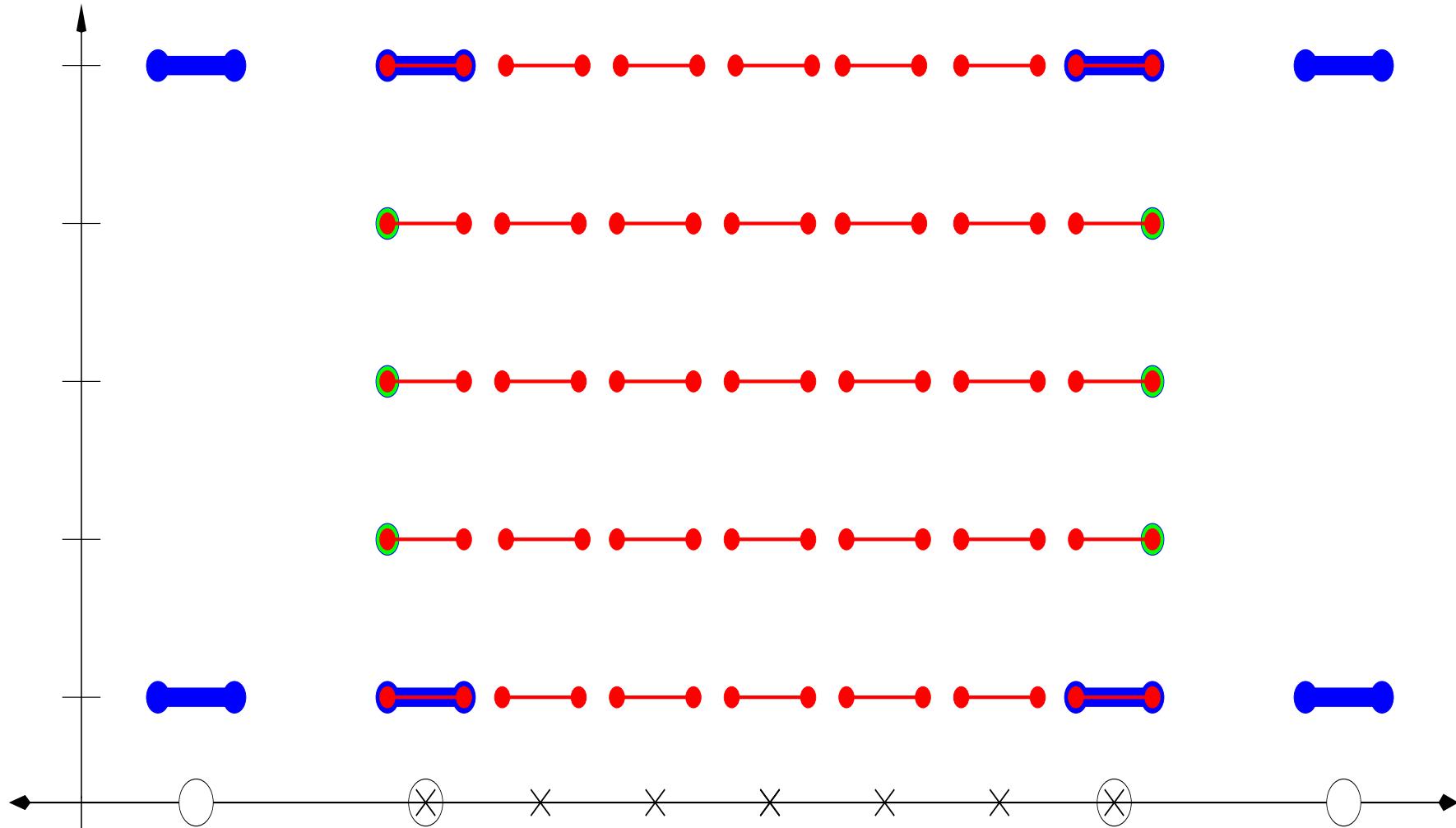
09/11) 4: collide & propagate on fine-grid



10/11) 4: fill empty fine-grid interface-pops



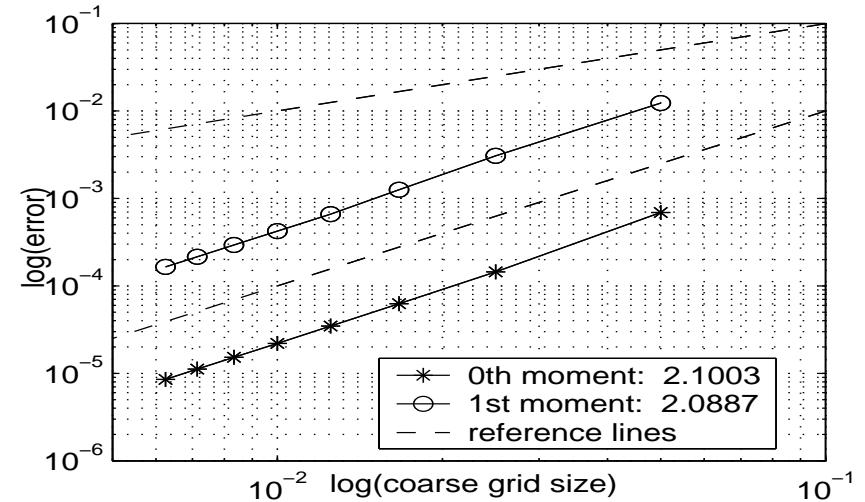
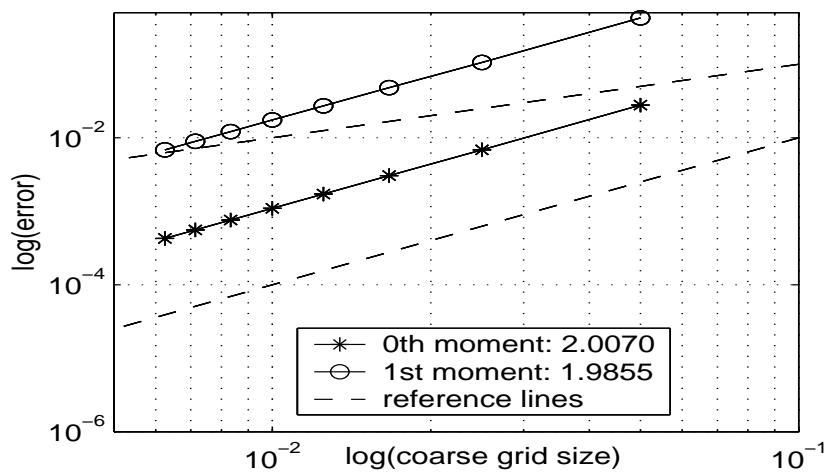
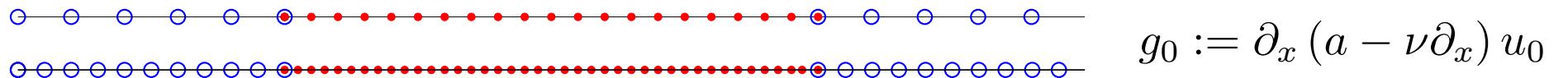
11/11) fill empty coarse-grid interface-pops



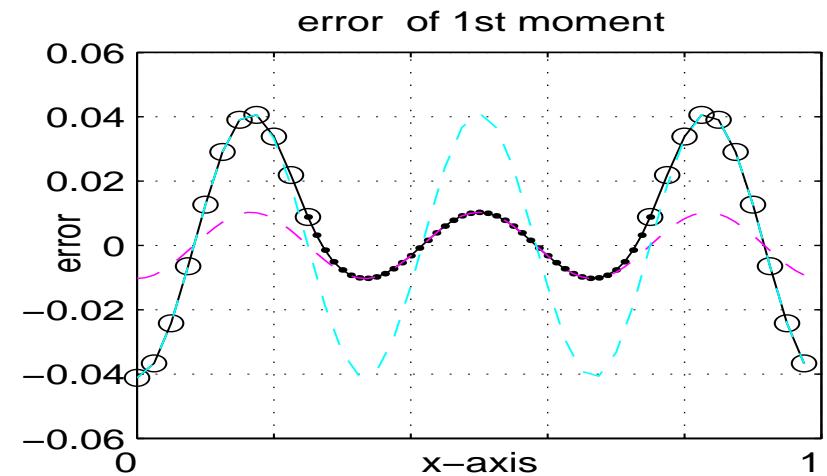
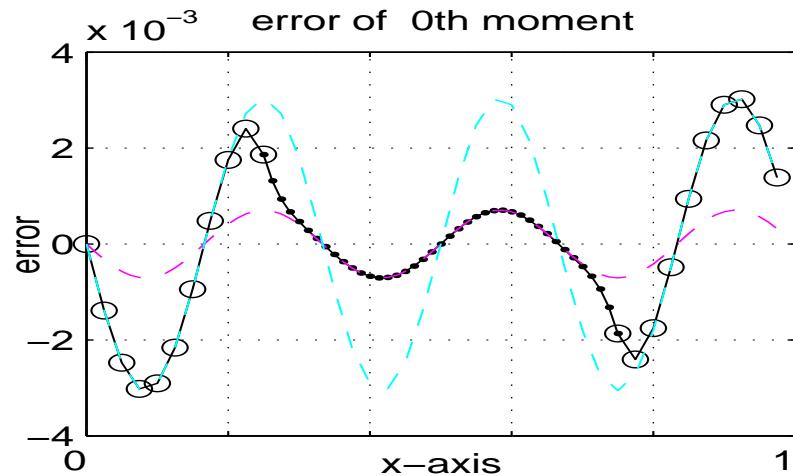
D1P3 Model: Numerical Tests

$$(I) \quad \begin{cases} u(t, x) = e^{-36\pi^2\nu t} \sin(6\pi x) \\ (t, x) \in [0; 2] \times [0; 1], \quad \text{same for (II)} \\ \nu = 0.005 \end{cases} \quad (II) \quad \begin{cases} u(t, x) = \cos(2\pi(x - at)) \\ q(t, x) = 4\pi^2\nu \cos(2\pi(x - at)) \\ \nu = 0.001, \quad a = 1.333 \end{cases}$$

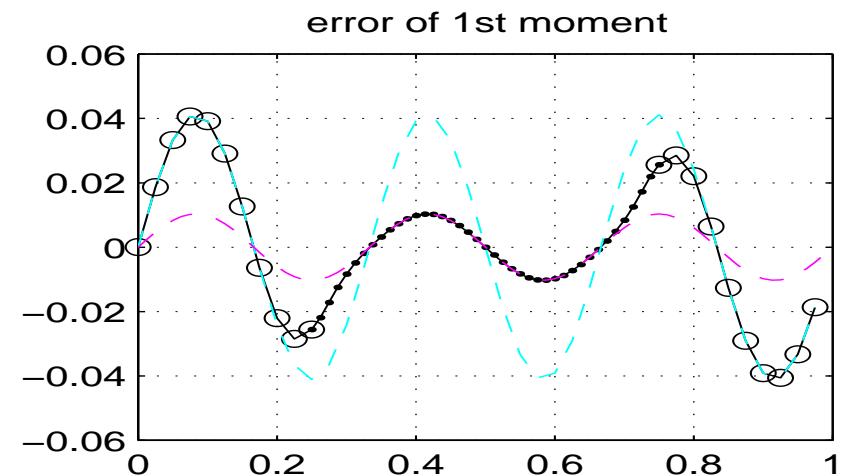
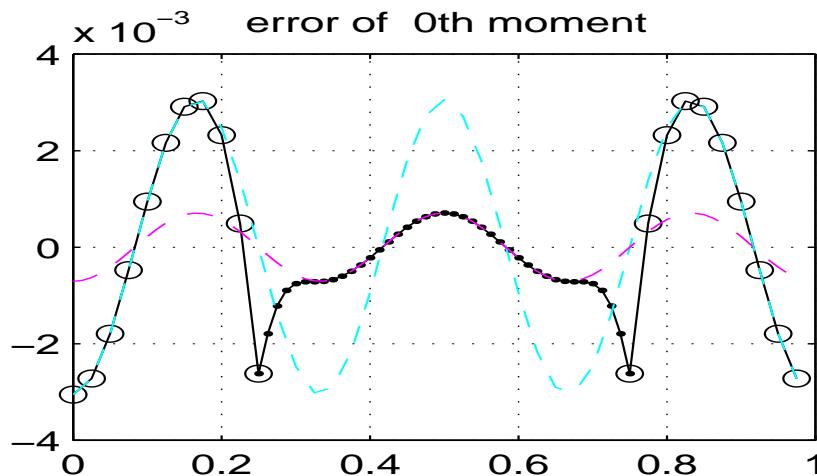
Init.: $F_s(0, i) = \underbrace{w_s u_0(ih)}_{w_s u_0(ih)} + \underbrace{h \theta_s w_s f_0(ih)}_{h \theta_s w_s f_0(ih)} + \underbrace{h^2 \tau (1 - \theta s^2) w_s g_0(ih)}_{h^2 \tau (1 - \theta s^2) w_s g_0(ih)}$



D1P3 Model: Error Snapshots for (I) ($t=0.1$, 160 It.)



\cos instead of \sin :

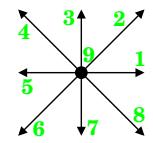


D2P9 Model for Stokes Flow: Macroscopic Quantities

$$\begin{aligned}\partial_t \mathbf{v} - \nu \Delta \mathbf{v} &= -\nabla p \\ \nabla \cdot \mathbf{v} &= 0 \quad \mathbf{v}(0, \cdot) = \mathbf{v}_0\end{aligned}$$

$$\mathcal{E}_{\mathbf{s}}(p, \mathbf{v}) = 3 w_s (p + 3 \mathbf{s} \cdot \mathbf{v})$$

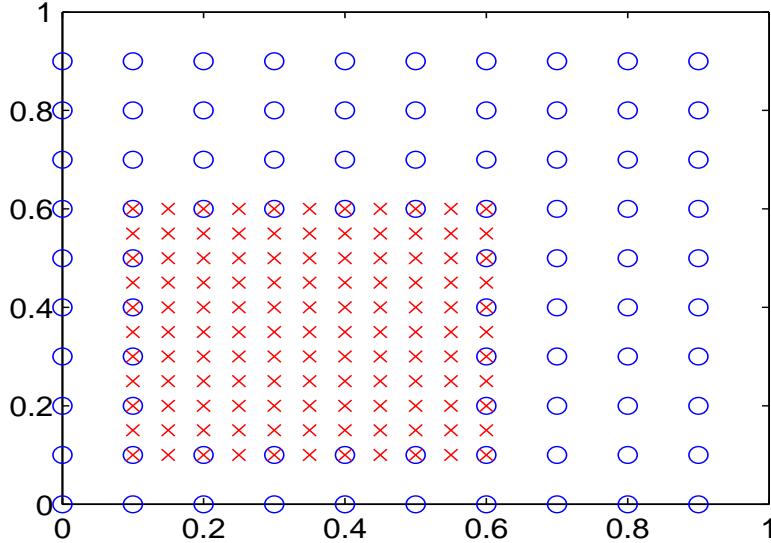
$$\nu = \frac{1}{3} \left(\frac{1}{\omega} - \frac{1}{2} \right)$$



p	$\mu_p := \frac{1}{3} h^{-1}$
v_x	$\mu_{v_x} := s_x$
v_y	$\mu_{v_y} := s_y$
$\sigma_x := p - \frac{2}{3} \tau \partial_x v_x$	$\mu_{\sigma_x} := s_x^2 h^{-1}$
$\sigma_y := p - \frac{2}{3} \tau \partial_y v_y$	$\mu_{\sigma_y} := s_y^2 h^{-1}$
$\sigma_{xy} := -\frac{1}{3} \tau (\partial_y v_x + \partial_x v_y)$	$\mu_{\sigma_{xy}} := s_x s_y h^{-1}$
$\phi_x := \frac{2}{9} \tau (\tau - \frac{1}{2}) (\partial_x^2 v_y + 2 \partial_x \partial_y v_x)$	$\mu_{\phi_x} := (s_x s_y^2 - \frac{1}{3} s_x) h^{-2}$
$\phi_y := \frac{2}{9} \tau (\tau - \frac{1}{2}) (\partial_y^2 v_x + 2 \partial_x \partial_y v_y)$	$\mu_{\phi_y} := (s_x^2 s_y - \frac{1}{3} s_y) h^{-2}$
$\psi := -\frac{4}{9} \tau (\tau^2 - \tau + \frac{1}{6}) \partial_x \partial_y (\partial_x v_y + \partial_y v_x)$	$\mu_{\psi} := (s_x^2 s_y^2 - \frac{1}{3} (s_x^2 + s_y^2) + \frac{1}{9}) h^{-3}$

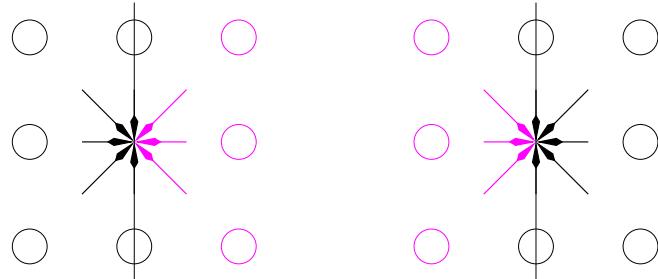
D2P9 Model: Grid Coupling

New features: 1) hanging interface nodes of fine grid, 2) corner nodes

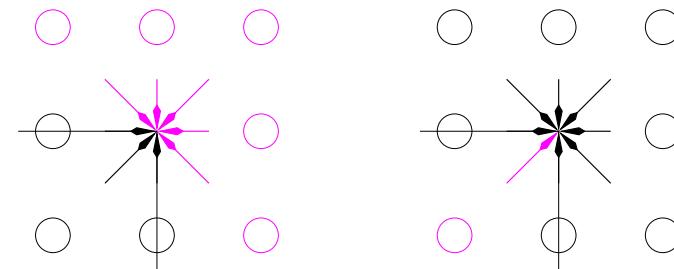


type of interface node	equalized moments
horizontal ($\parallel x\text{-axis}$)	$V_x, V_y, \Sigma_y, \Sigma_{xy}, \Phi_y, \Psi$
vertical ($\parallel y\text{-axis}$)	$V_x, V_y, \Sigma_x, \Sigma_{xy}, \Phi_x, \Psi$
corner	$V_x, V_y, \Sigma_x, \Sigma_y, \Sigma_{xy}, \Psi$

regular interface nodes:

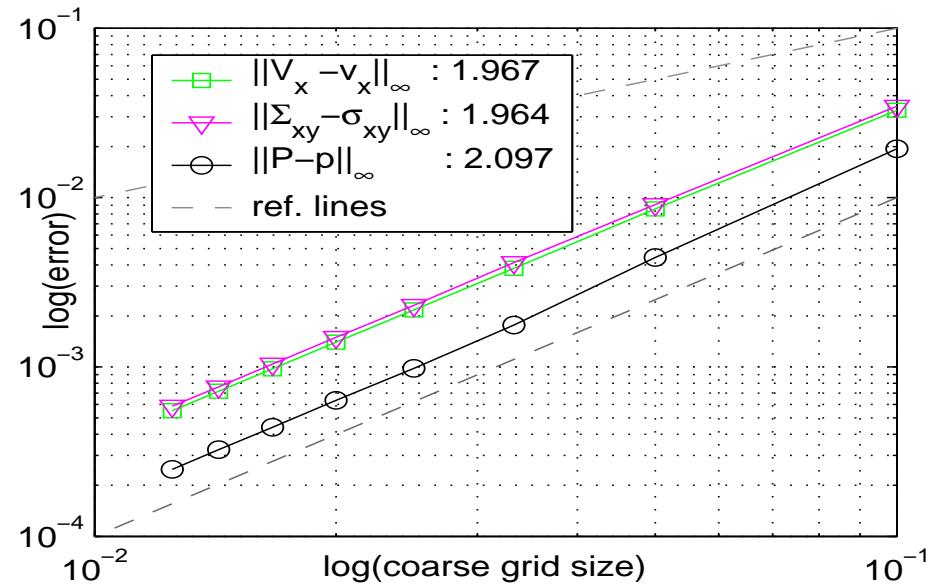
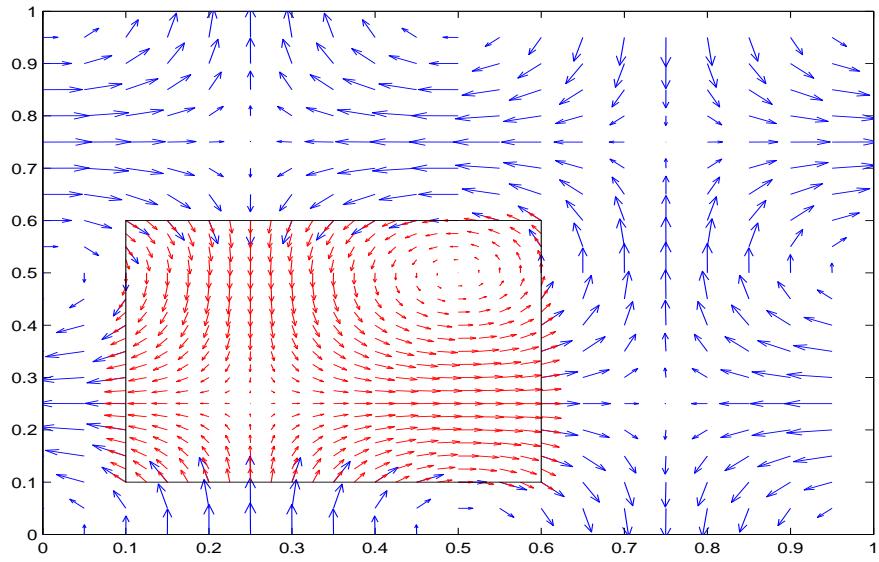


convex/concave corner:



6 empty (unknown) populations \Rightarrow 6 conditions (physically only 4 for Stokes !)

D2P9 Model: Numeric Test



$$\left. \begin{array}{l} v_x(t, x, y) = -e^{-8\pi^2\nu t} \cos(2\pi x) \sin(2\pi y) \\ v_y(t, x, y) = e^{-8\pi^2\nu t} \sin(2\pi x) \cos(2\pi y) \\ p(t, x, y) = 0 \end{array} \right\} \begin{array}{l} \text{damped eigenmode of Stokes operator} \\ \nu = 0.01, (t, x, y) \in [0; 2] \times [0; 1]^2 \end{array}$$

$$\text{Init.: } F_s(0, i, j) = \underbrace{3w_s s \cdot v_0(ih, jh)}_{3w_s} + \underbrace{h \left[p_0(ih, jh) + \frac{1}{\omega} (s \cdot \nabla)(s \cdot v_0(ih, jh)) \right]}_{h}$$