Outline	Linear evolution problems	Numerical example	Snapshot POD	Numerical example

Error estimates for POD Galerkin schemes

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DISC Summerschool 2005



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Outline of the talk

- Continuous POD
- Numerical example: heat equation
- Snapshot POD
- Numerical example: Laser surface hardening of steel



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Abstract linear evolution problem

- ▶ *H*, *V* Hilbert spaces, $V \hookrightarrow H = H' \hookrightarrow V'$ (e.g., $H = L^2$, $V = H^1$)
- ▶ Symmetric bilinear form $a(\varphi, \psi) = \langle \varphi, \psi \rangle_V$ for $\varphi, \psi \in V$
- Evolution problem:

$$\frac{\mathrm{d}}{\mathrm{d}t} \langle y(t), \varphi \rangle_{H} + a(y(t), \varphi) = \langle f(t), \varphi \rangle_{H} \quad \text{for } t \in [0, T], \ \varphi \in V$$
$$\langle y(0), \varphi \rangle_{H} = \langle y_{\circ}, \varphi \rangle_{H} \quad \text{for } \varphi \in V$$

with $y_{\circ} \in H$ and $f \in L^2(0, T; H)$

• Unique solution y with $||y|| \leq C(||y_0|| + ||f||)$

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Outline	Linear evolution problems	Numerical example	Snapshot POD	Numerical example
Continuou	s POD			

- Topology: X = H or X = V
- ▶ Snapshot ensemble: $\mathcal{V} = \{y(t) \mid t \in [0, T]\} \subset X$, $d = \dim \mathcal{V} \le \infty$
- EVD for linear and symmetric \mathcal{R} in X:

$$\mathcal{R}u_i = \int_0^T \langle u_i, y(t) \rangle_X y(t) \, \mathrm{d}t = \sigma_i^2 u_i \qquad (YY^T u_i = \sigma_i^2 u_i)$$

and set $\lambda_i^\infty = \sigma_i^2$, $\psi_i^\infty = u_i$, $1 \le i \le \ell$

• Error formula for the POD basis of rank ℓ :

$$\int_0^T \left\| y(t) - \sum_{i=1}^{\ell} \langle y(t), \psi_i^{\infty} \rangle_X \psi_i^{\infty} \right\|_X^2 \mathrm{d}t = \sum_{i=\ell+1}^{\infty} \lambda_i^{\infty}$$



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POD Galerkin scheme for the state equation

- ▶ POD ansatz space: $V^{\ell} = \text{span} \{\psi_1, \dots, \psi_{\ell}\} \subset V$
- ► POD Galerkin scheme:

$$\begin{split} \frac{\mathrm{d}}{\mathrm{d}t} \langle y^{\ell}(t), \psi \rangle_{H} + \mathbf{a}(y^{\ell}(t), \psi) &= \langle f(t), \psi \rangle_{H} \quad \text{for } t \in [0, T], \ \psi \in V^{\ell} \\ \langle y^{\ell}(0), \psi \rangle_{H} &= \langle y_{\circ}, \psi \rangle_{H} \quad \text{ for } \psi \in V^{\ell} \end{split}$$

- Unique solution y^{ℓ} with $||y^{\ell}|| \leq C(||y_{\circ}|| + ||f||)$
- Goal: Estimation of

$$\sup_{t \in [0,T]} \|y^{\ell}(t) - y(t)\|_{H} + \int_{0}^{T} \|y^{\ell}(t) - y(t)\|_{V}^{2} dt$$

in terms of
$$\sum_{i=\ell+1}^{\infty} \lambda_i^{\infty}$$

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Error estimates for POD Galerkin schemes

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Outline	Linear evolution problems	Numerical example	Snapshot POD	Numerical example	
Estimatio	n of POD error (Part 1)			
• Orthogonal projection: $\mathcal{P}^{\ell}\varphi = \sum_{i=1}^{\ell} \langle \varphi, \psi_i^{\infty} \rangle_V \psi_i^{\infty}$ for $\varphi \in V$					
	$\Rightarrow \mathbf{a}(\mathcal{P}^{\ell}\varphi,\psi) = \mathbf{a}(\varphi,\psi)$) for $arphi \in {\it V}$, $\psi \in$	V^{ℓ} (Ritz	projector)	
	$\Rightarrow y(t) - \sum_{i=1}^{\ell} \langle y(t), \psi_i^{\alpha} \rangle$	$\langle \psi_i^{\infty} = y(t) - \eta$	$\mathcal{P}^{\ell}y(t)$ for $t\in [0,$	<i>T</i>]	
		~			

$$\Rightarrow \int_0^T \left\| y(t) - \mathcal{P}^{\ell} y(t) \right\|_V^2 \mathrm{d}t = \sum_{i=\ell+1}^\infty \lambda_i^\infty$$

► Set
$$\vartheta(t) = \mathcal{P}^{\ell} y(t) - y^{\ell}(t) \in V^{\ell}$$
, $\varrho(t) = y(t) - \mathcal{P}^{\ell} y(t) \in (V^{\ell})^{\perp}$
 $y(t) - y^{\ell}(t) = y(t) - \mathcal{P}^{\ell} y(t) + \mathcal{P}^{\ell} y(t) - y^{\ell}(t) = \varrho(t) + \vartheta(t)$

Error formula:

$$\int_0^T \|\varrho(t)\|_X^2 \, \mathrm{d}t = \sum_{i=\ell+1}^\infty \lambda_i^\infty$$

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• Topology:
$$X = V$$
, at least

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Estimation of POD error (Part 2)

•
$$\vartheta(t) = \mathcal{P}^{\ell} y(t) - y^{\ell}(t)$$
 and $a(\mathcal{P}^{\ell} \varphi, \psi) = a(\varphi, \psi)$

$$\frac{\mathrm{d}}{\mathrm{d}t} \left\langle \vartheta^{\ell}(t), \psi \right\rangle_{H} + \mathsf{a}(\vartheta^{\ell}(t), \psi) = \left\langle y_{t}(t) - \mathcal{P}^{\ell} y_{t}(t), \psi \right\rangle_{H} \quad \text{for } \psi \in V^{\ell}$$

•
$$\psi = \vartheta(t) \in V^{\ell}$$
 and $a(\varphi, \varphi) = \|\varphi\|_V^2$ for $\varphi \in V$

$$\frac{\mathrm{d}}{\mathrm{d}t} \left\| \vartheta(t) \right\|_{H}^{2} + \left\| \vartheta(t) \right\|_{V}^{2} \leq C \left\| y_{t}(t) - \mathcal{P}^{\ell} y_{t}(t) \right\|_{H}^{2}$$

• Integrating over
$$(0, t)$$
, $t \in [0, T]$

$$\|\vartheta(t)\|_{H}^{2}+\int_{0}^{t}\|\vartheta(s)\|_{V}^{2}\mathrm{d}s\leq\|\vartheta(0)\|_{H}^{2}+\int_{0}^{T}\|\underbrace{y_{t}(s)-\mathcal{P}^{\ell}y_{t}(s)}_{=\varrho(s)}\|_{H}^{2}\mathrm{d}s$$

• Recall:
$$y(t) - y^{\ell}(t) = \varrho(t) + \vartheta(t)$$

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Outline	Linear evolution problems	Numerical example	Snapshot POD	Numerical example
Estimatio	on of POD error (Part 3	3)		
•	New ansatz for POD:	$X = V, \mathcal{P}^{\ell} \varphi = \sum_{i=1}^{\ell}$	$\sum_{i} \langle \varphi, \psi_i^{\infty} \rangle_V \psi_i^{\infty}$	
	$\min\int_0^T \ y(t)-\mathcal{P}^\ell y(t)-\mathcal{P}^\ell y(t)\ $	$\left\ \right\ _{V}^{2} + \left\ y_{t}(t) - \mathcal{P}^{\ell} y \right\ $	$\left\ t_{t}(t) \right\ _{V}^{2} \mathrm{d}t \mathrm{s.t.}$	$\left\langle \psi_{i},\psi_{j} ight angle _{V}=\delta_{ij}$
•	Error formula: $\varrho(t) =$	$y(t) - \mathcal{P}^\ell y(t)$		
	$\int_0^T \ \varrho(t)\ _V^2 + \ $	$ \varrho_t(t)\ _V^2 \mathrm{d}t = \ \varrho(t)\ _V$	$\ ^{2}_{H^{1}(0,T;V)} = \sum_{i=\ell}^{\infty}$	$\sum_{\ell=1}^{2}\lambda_{i}^{\infty}$
•	Consequences: $\vartheta(t) =$	$= \mathcal{P}^\ell y(t) - y^\ell(t)$		
	$\sup_{t\in [0,T]} \left\ \varrho(t) \right\ _{H}^{2} +$	$+\int_0^T \ \varrho(t)\ _V^2 \mathrm{d}t \leq$	$C\sum_{i=\ell+1}^{\infty}\lambda_i^\infty$	_
	$\sup_{t\in[0,T]}\left\ \vartheta(t)\right\ _{H}^{2}+$	$\int_0^T \left\ \vartheta(t)\right\ _V^2 \mathrm{d}t \leq$	$\left\ \vartheta(0)\right\ _{H}^{2}+C\sum_{i=1}^{\infty}$	$\sum_{\ell=1}^{\infty} \lambda_i^{\infty} \qquad \qquad$
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Outline	Linear evolution problems	Numerical example	Snapshot POD	Numerical example

Estimation of POD error (Part 4)

• Recall $y(t) - y^{\ell}(t) = \varrho(t) + \vartheta(t)$ and triangle inequality

$$\sup_{t \in [0,T]} \left\| y^{\ell}(t) - y(t) \right\|_{H}^{2} + \int_{0}^{T} \left\| y^{\ell}(t) - y(t) \right\|_{V}^{2} \mathrm{d}t$$
$$\leq \underbrace{\left\| y^{\ell}(0) - \mathcal{P}^{\ell} y_{\circ} \right\|_{H}^{2}}_{\text{error in initial data}} + \underbrace{C \sum_{i=\ell+1}^{\infty} \lambda_{i}^{\infty}}_{\text{error in POD}}$$

- Assumptions: POD with topology X = V and time derivatives
- ► FE: estimates for function classes, e.g., $V = H^1(\Omega)$ ⇒ $||y_t(t) - R^h y_t(t)|| \sim h^p$ for any $y_t(t) \in V$, $t \in [0, T]$
- POD: estimates only for included snapshots

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Error estimates for POD Galerkin schemes

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Empirical order of decay (EOD) [Hinze/V.]

POD error: $y_{\circ} = 0$

$$\sup_{t \in [0,T]} \|y^{\ell}(t) - y(t)\|_{H}^{2} + \int_{0}^{T} \|y^{\ell}(t) - y(t)\|_{V}^{2} dt \sim \sum_{i=\ell+1}^{\infty} \lambda_{i}^{\infty}$$

• Ansatz for the eigenvalues: $\lambda_i^{\infty} = \lambda_1^{\infty} e^{-\alpha(i-1)}$ for $i \ge 1$

• Goal: estimation of α based on the POD error

$$\begin{array}{l} \left\| \frac{y^{\ell} - y \right\|^2}{\|y^{\ell+1} - y\|^2} \sim \frac{\sum\limits_{i=\ell+1}^{\infty} \lambda_i}{\sum\limits_{i=\ell+2}^{\infty} \lambda_i} = \frac{\sum\limits_{i=\ell+1}^{\infty} e^{-\alpha(i-1)}}{\sum\limits_{i=\ell+2}^{\infty} e^{-\alpha(i-1)}} = \frac{\sum\limits_{i=0}^{\infty} \left(e^{-\alpha} \right)^i}{\sum\limits_{i=0}^{\infty} \left(e^{-\alpha} \right)^i - 1} = e^{\alpha} \\ \end{array} \\ \begin{array}{l} \text{Set: } Q(\ell) = \ln \frac{\|y^{\ell} - y\|^2}{\|y^{\ell+1} - y\|^2} \sim \alpha \\ \end{array} \\ \begin{array}{l} \text{EOD} = \frac{1}{\ell_{\max}} \sum\limits_{\ell=1}^{\ell_{\max}} Q(\ell) \text{ so that } EOD \approx \alpha \end{array} \end{array}$$

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Numerical example (Part 1)

$$y_t - \Delta y = 0 \qquad \text{in } Q = (0, 1) \times \Omega$$
$$\frac{\partial y}{\partial n} = 0 \qquad \text{on } \Sigma_1 = (0, 1) \times \Gamma_1$$
$$\frac{\partial y}{\partial n} = q \qquad \text{on } \Sigma_2 = (0, 1) \times \Gamma_2$$
$$y(0) = 0 \qquad \text{on } \Omega \subset \mathbb{R}^2$$

•
$$\Gamma_1 = \{ \mathbf{x} = (x, y) \in \partial\Omega \mid ||\mathbf{x}|| = 1 \}, \Gamma_2 = \partial\Omega \setminus \Gamma_1$$

• $q(t, \mathbf{x}) = e^{-(x-0.7\cos(2\pi t))^2 - (y-0.7\sin(2\pi t))^2}$

•
$$m = 868$$
 finite elements, $\delta t = 1/499$

•
$$y^m$$
 FE solution, $\overline{\partial}_t y^m(t_j) = (y^m(t_j) - y^m(t_{j-1}))/\delta t$



- Snapshot ensemble: $\mathcal{V} = \operatorname{span}\left\{\{y^m(t_j)\}_{j=1}^n, \{\overline{\partial}_t y^m(t_j)\}_{j=2}^n\right\}$
- EVD for linear and symmetric \mathcal{R}^n in X:

$$\mathcal{R}^{n}u_{i} = \sum_{j=1}^{n} \alpha_{j} \langle u_{i}, y^{m}(t_{j}) \rangle_{X} y^{m}(t_{j}) + \sum_{j=2}^{n} \alpha_{j} \langle u_{i}, \overline{\partial}_{t} y^{m}(t_{j}) \rangle_{X} \overline{\partial}_{t} y^{m}(t_{j}) = \sigma_{i}^{2} u_{i}$$

and set
$$\lambda_i = \sigma_i^2$$
, $\psi_i = u_i$

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Numerical example (Part 2)

CPU times: 2GHz desktop PC (Linux)

Computing the FE mesh and matrices	18.0 seconds
FE solve	5.0 seconds
Computing 15 POD basis functions	36.9 seconds
Computing the reduced-order model, $\ell=15$	< 0.1 seconds
POD solve, $\ell=15$	< 0.1 seconds

Firror:
$$\|\varphi\|_{L^2(0,T;X)} = \sqrt{\int_0^T \|\varphi(t)\|_X^2} \mathrm{d}t$$

X	ensemble	$\ y^h - y^\ell\ _{L^2(0,T;H^1(\Omega))}$	$\ y^h - y^\ell\ _{L^2(0,T;L^2(\Omega))}$
L ²	no DQ	0.0104	0.0012
H^1	no DQ	0.0064	0.0007
L ²	DQ	0.0064	0.0007
H^1	DQ	0.0060	0.0006

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Numerical example (Part 3)



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Snapshot POD for dynamical systems

► Dynamical system (e.g., Navier Stokes) in a Hilbert space *H*:

 $\dot{y}(t) + Ay(t) + B(y(t)) = f(t) ext{ for } t \in (0, T) ext{ and } y(0) = y_{\circ}$

• $V \subset H$ Hilbert space with $V \hookrightarrow H = H' \hookrightarrow V'$, X = H or X = V

- ► Time grid: $0 \le t_1 < t_2 < \ldots t_n \le T$, $\delta t_j = t_j t_{j-1}$ for $2 \le j \le n$
- ► Snapshots: $y_j = y(t_j)$, $1 \le j \le n$ and $\overline{\partial}_t y_j = \frac{y_j y_{j-1}}{\delta t_j}$, $2 \le j \le n$

► Snapshot ensemble: $\mathcal{V} = \text{span} \{y_1, \dots, y_n, \overline{\partial}_t y_2, \dots, \overline{\partial}_t y_n\},\ d = \dim \mathcal{V}$

- Orthogonal decomposition in X: $\mathcal{P}^{\ell}\varphi = \sum_{i=1}^{\ell} \langle \varphi, \psi_i \rangle_X \psi_i$ for $\varphi \in X$
- ▶ POD basis of rank $\ell < d$: with weights $\alpha_j \ge 0$

$$\min \sum_{j=1}^{n} \alpha_{j} \| y_{j} - \mathcal{P}^{\ell} y_{j} \|_{X}^{2} + \sum_{j=2}^{n} \alpha_{j} \| \overline{\partial}_{t} y_{j} - \mathcal{P}^{\ell} \overline{\partial}_{t} y_{j} \|_{X}^{2} \text{ s.t. } \langle \psi_{i}, \psi_{j} \rangle_{X} = \delta_{ij}$$

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Computation of the POD basis

• EVD for linear and symmetric \mathcal{R}^n in X:

$$\mathcal{R}^{n}u_{i} = \sum_{j=1}^{n} \alpha_{j} \langle u_{i}, y_{j} \rangle_{X} y_{j} + \sum_{j=2}^{n} \alpha_{j} \langle u_{i}, \overline{\partial}_{t} y_{j} \rangle_{X} \overline{\partial}_{t} y_{j} = \sigma_{i}^{2} u_{i}$$

and set $\lambda_i = \sigma_i^2$, $\psi_i = u_i$

• Error formula for the POD basis of rank ℓ :

$$\sum_{j=1}^{n} \alpha_{j} \left\| y_{j} - \mathcal{P}^{\ell} y_{j} \right\|_{X}^{2} + \sum_{j=2}^{n} \alpha_{j} \left\| \overline{\partial}_{t} y_{j} - \mathcal{P}^{\ell} \overline{\partial}_{t} y_{j} \right\|_{X}^{2} = \sum_{i=\ell+1}^{d} \lambda_{i}$$

► Trapezoidal weights: $\alpha_1 = \frac{\delta t_1}{2}$, $\alpha_j = \frac{\delta t_j + \delta t_{j+1}}{2}$, 1 < j < n, $\alpha_n = \frac{\delta t_n}{2}$ ⇒ Convergence to $\int_0^T \|y(t) - \mathcal{P}^\ell y(t)\|_X^2 + \|y_t(t) - \mathcal{P}^\ell y_t(t)\|_X^2 dt$



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Outline	Linear evolution problems	Numerical example	Snapshot POD	Numerical example

POD Galerkin scheme

- Time grid: $0 = \tau_0 < \ldots < \tau_N = T$ and $\delta \tau_j = \tau_j \tau_{j-1}$, $1 \le j \le N$
- Assumptions: $\Delta \tau / \delta \tau$ bounded, $\Delta t = O(\delta \tau)$ and $\Delta \tau = O(\delta t)$ with $\Delta \tau = \max \delta \tau_j$, $\delta \tau = \min \delta \tau_j$, $\Delta t = \max \delta t_j$, $\delta t = \min \delta t_j$

• Goal: Find
$$\{Y_j\}_{j=0}^N$$
 in $V^{\ell} = \text{span } \{\psi_1, \dots, \psi_{\ell}\}$

$$\begin{split} \langle \overline{\partial}_{\tau} Y_j + AY_j + B(Y_j), \psi \rangle_H &= \langle f(\tau_j), \psi \rangle_H \quad \text{for } \psi \in V^{\ell}, \ j = 1, \dots, N \\ \langle Y_0, \psi \rangle_H &= \langle y_o, \psi \rangle_H \quad \text{for } \psi \in V^{\ell} \end{split}$$

with $\overline{\partial}_{\tau} Y_j = \frac{Y_j - Y_{j-1}}{\Delta \tau_j}$ \Rightarrow low dimensional system

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POD error estimate for Snapshot POD

► Goal: Estimation of

$$\sum_{j=0}^{N} \beta_{j} \|Y_{j} - y(\tau_{j})\|_{H}^{2} \approx \int_{0}^{T} \|Y(\tau) - y(\tau)\|_{H}^{2} d\tau$$

with
$$\beta_0 = \frac{\delta \tau_1}{2}$$
, $\beta_j = \frac{\delta \tau_j + \delta \tau_{j+1}}{2}$, $0 < j < N$, $\beta_N = \frac{\delta t_N}{2}$

• Theorem 1 [Kunisch/V.]: X = V, $\Delta \tau$ small, y sufficiently smooth

$$\sum_{j=0}^{N} \beta_{j} \left\| Y_{j} - y(\tau_{j}) \right\|_{H}^{2} \leq C \sum_{i=\ell+1}^{d} \left(\left| \langle \psi_{i}, y_{\circ} \rangle_{V} \right| + \lambda_{i} \right) + O\left(\Delta \tau \Delta t + (\Delta \tau)^{2} \right)$$

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with
$$\Delta \tau = \max \delta \tau_j$$
 and $\Delta t = \max \delta t_j$

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Outline	Linear evolution problems	Numerical example	Snapshot POD	Numerical example

Asymptotic error estimate

• Problem: $\lambda_i = \lambda_i^{(n)}, \ \psi_i = \psi_i^{(n)}$ depend on the snapshot grid $\{t_i\}_{j=1}^n$

$$\mathcal{R}^{n} = \sum_{j=1}^{n} \alpha_{j} \langle \bullet, y_{j} \rangle_{X} y_{j} + \sum_{j=2}^{n} \alpha_{j} \langle \bullet, \overline{\partial}_{t} y_{j} \rangle_{X} \overline{\partial}_{t} y_{j}$$

▶ Fix ℓ such that eigenvalues $\{\lambda_i^\infty\}_{i\in\mathbb{N}}$ and eigenfunctions $\{\psi_i^\infty\}_{i\in\mathbb{N}}$ of

$$\mathcal{R} = \int_0^T \langle \bullet, y(t) \rangle_V y(t) + \langle \bullet, y_t(t) \rangle_V y_t(t) \, \mathrm{d}t$$

satisfy $\lambda_\ell^\infty \neq \lambda_{\ell+1}^\infty$

Theorem 2 [Kunisch/V.]: X = V, $\Delta \tau$ small, y sufficiently smooth

$$\sum_{j=0}^{N} \beta_{j} \|Y_{j} - y(\tau_{j})\|_{H}^{2} \leq C \sum_{i=\ell+1}^{\infty} \left(|\langle \psi_{i}^{\infty}, y_{\circ} \rangle_{V}|^{2} + \lambda_{i}^{\infty} \right) + O((\Delta \tau)^{2})$$

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Outline	Linear evolution problems	Numerical example	Snapshot POD	Numerical example
Sketch	of the proof			

► Theorem 1:

$$\sum_{j=0}^{N} \beta_{j} \left\| Y_{j} - y(\tau_{j}) \right\|_{H}^{2} \leq C \sum_{i=\ell+1}^{d} \left(\left| \langle \psi_{i}, y_{\circ} \rangle_{V} \right| + \lambda_{i} \right) + O\left(\Delta \tau \Delta t + (\Delta \tau)^{2} \right)$$

- Weights and smoothness of $y \Rightarrow \lim_{n \to \infty} ||\mathcal{R}_n \mathcal{R}|| = 0$
- perturbation theory for eigenvalues [Kato]
- ▶ Choose $n_{\circ} \in \mathbb{N}$ such that for all $n \ge n_{\circ}$

$$\begin{split} \sum_{i=\ell+1}^{d(n)} \lambda_i^{(n)} &\leq 2 \sum_{i=\ell+1}^{\infty} \lambda_i^{\infty} \\ \sum_{i=\ell+1}^{d(n)} \left| \langle \psi_i^{(n)}, y_{\circ} \rangle_V \right|^2 &\leq 2 \sum_{i=\ell+1}^{\infty} \left| \langle \psi_i^{\infty}, y_{\circ} \rangle_V \end{split}$$



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Problem formulation

Laser surface hardening of steel [Hömberg/V.]:



Phase transition of steel:



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Outline	Linear evolution problems	Numerical example	Snapshot POD	Numerical example

Model equations

Energy balance and Fourier's law:

$$\begin{cases} \varrho c_{\rho} \theta_{t} - k \Delta \theta &= \alpha u - \varrho L a_{t} & \text{in } Q = (0, T) \times \Omega \\ \frac{\partial \theta}{\partial n} &= 0 & \text{auf } \Sigma = (0, T) \times \partial \Omega \\ \theta(0, \cdot) &= \theta_{\circ} & \text{in } \Omega \subset \mathbb{R}^{d} \end{cases}$$

Phase transition of austenite:

$$\begin{cases} a_t = f(\theta, a) & \text{in } Q \\ a(0, \cdot) = 0 & \text{in } \Omega \end{cases}$$

• Intensity of the laser: $u = u(t) \in L^2(0, T)$

► Nonlinearity:
$$f_+(\theta, a) = \max \{a_{eq}(\theta) - a, 0\} / \tau(\theta), \tau(\theta) > 0$$



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FE and POD temperatures at t = T



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Outline	Linear evolution problems	Numerical example	Snapshot POD	Numerical example

POD error

► Measures for the error:

$$\Psi^{i} = \frac{\underset{0 \leq j \leq N}{\max} \|\theta^{i}_{\ell} - \theta^{j}_{FE}\|_{L^{\infty}(\Omega)}}{\underset{0 \leq j \leq N}{\max} \|\theta^{i}_{FE}\|_{L^{\infty}(\Omega)}} \quad \text{with} \quad \begin{cases} i = 1 & \text{POD with DQ} \\ i = 2 & \text{POD without DQ} \end{cases}$$

	$X = L^2(\Omega)$		$X = H^1(\Omega)$	
ℓ	Ψ^1	Ψ^2	Ψ^1	Ψ^2
10	24.1%	40.6%	21.0%	40.1%
25	1.6%	26.9%	4.0%	24.6%

• Heuristic:
$$\mathcal{E}(\ell) = \sum_{i=1}^{\ell} \lambda_i \Big/ \sum_{i=1}^{d} \lambda_i \cdot 100\% \ge 94\%$$

	$\ell = 10$	$\ell = 15$	$\ell = 20$	$\ell = 25$
$\mathcal{E}(\ell), X = L^2(\Omega)$	94.3	98.4	99.5	99.8
$\mathcal{E}(\ell), X = H^1(\Omega)$	77.7	87.4	92.5	95.7



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Outline	Linear evolution problems	Numerical example	Snapshot POD	Numerical example
Reference	S			

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