

Numerische Verfahren der restringierten Optimierung

<http://www.math.uni-konstanz.de/numerik/personen/volkwein/teaching/>

Sheet 6

Deadline for hand-in: 29.01.2015 at lecture

Exercise 16

(2 Points)

Given the problem

$$\min_{x \in \mathbb{R}^2} f(x) := -x_1 - x_2 \quad \text{s.t.} \quad g(x) := -x \leq 0, \quad e(x) := x_1^2 + x_2^2 - 1 = 0. \quad (1)$$

- Sketch the admissible set and the cost function (use contour lines for the cost function).
- Calculate the solution of (1) and the corresponding Lagrange multipliers.
- Let $x^k = (-1/2, -1/2)^\top$ be given. Sketch the constraints of the SQP subproblem and show that the corresponding admissible set is empty.

Exercise 17

Given the problem

$$\min f(x) \quad \text{subject to} \quad e(x) = 0, \quad (2)$$

where f and e are C^2 functions. The *augmented Lagrange function* for (2) is defined as

$$L_\alpha(x, \lambda) := f(x) + \lambda^\top e(x) + \frac{\alpha}{2} \|e(x)\|^2$$

with $\alpha \geq 0$.

- Show that all KKT pairs (x, λ) satisfy

$$\nabla L_\alpha(x, \lambda) = 0.$$

- Let (x^*, λ^*) be a KKT pair that satisfies the second order sufficient optimality condition. Show that the Hessian matrix $\nabla_{xx} L_\alpha(x^*, \lambda^*)$ is positive definite for sufficiently large α . Hence, x^* is a local minimum of $L_\alpha(\cdot, \lambda^*)$ provided that α is sufficiently large.

Exercise 18

Given the problem

$$\min -x_1 x_2^2 \quad \text{subject to} \quad x_1^2 + x_2^2 = 1. \quad (3)$$

Show that $x^* = \left(\sqrt{\frac{1}{3}}, \pm\sqrt{\frac{2}{3}}\right)^\top$ are the solutions of (3), with Lagrange multiplier $\lambda^* = \sqrt{\frac{1}{3}}$.

We consider the Hessian matrix $\nabla_{xx} L_\alpha(x^*, \lambda^*)$ of the augmented Lagrange function from Exercise 17. Visualize (Matlab) the contour lines of $L_\alpha(x, \lambda^*)$ for different values α (e.g. $\alpha = 0, 0.6$). For which values of α is $\nabla_{xx} L_\alpha(x^*, \lambda^*)$ positive definite?