

Moment Closure - A Brief Review

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Motivation

Consider a **general evolution equation**:

$$\partial_t u = F(u), \quad u = u(t) \in \mathcal{X}.$$

Could be a **ODE, PDE, IDE, DDE, SODE, network**, etc.

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Key problem in (applied) mathematics:

- ▶ dimension **reduction** (if $\dim(\mathcal{X}) = \infty$ or $\dim(\mathcal{X}) \gg 1$)
- ▶ many methods “**work well in practice**”
- ▶ only few methods have been **proven** to be accurate

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MOMENT CLOSURE falls into this scheme

Moment Closure - Three Concrete Examples

(I) Stochastic differential equations

- ▶ Kolmogorov equation ($\dim(\mathcal{X}) = \infty$)
- ▶ moments \leftrightarrow moments of a probability density

(II) Kinetic theory

- ▶ Boltzmann-type mesoscopic models ($\dim(\mathcal{X}) = \infty$)
- ▶ moments \leftrightarrow certain integrals

(III) Network dynamics

- ▶ dynamics of graph, nodes, edges ($\dim(\mathcal{X}) \gg 1$)
- ▶ moments \leftrightarrow graph motives

(I) Stochastic Ordinary Differential Equations (SODEs)

Standard SODE ($x \in \mathbb{R}$ for simplicity) on $(\Omega, \mathcal{F}, \mathbb{P})$

$$x' = f(x) + \sigma \xi, \quad ' = \frac{d}{dt}.$$

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$$f(x) := a_2 x^2 + a_1 x + a_0.$$

- ▶ x depends upon the random input space \Rightarrow **random variable**
- ▶ define **expectation/mean/averaging** $\mathbb{E}[\cdot] := \langle \cdot \rangle$
- ▶ might want to know **moments**: $m_j := \langle x^j \rangle$

Calculating moment equations...

Just **average**:

$$m_1' = \langle x' \rangle = a_2 \langle x^2 \rangle + a_1 \langle x \rangle + a_0 = a_2 m_2 + a_1 m_1 + a_0.$$

⇒ Need **second moment equation**!

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⇒ Need **second moment equation**!

Using Itô's formula one finds

$$(x^2)' = [2xf(x) + \sigma^2] + 2x\sigma \xi'.$$

Just **average**:

$$\begin{aligned} m_2' &= 2\langle a_2 x^3 + a_1 x^2 + a_0 x \rangle + \sigma^2 + \sigma \langle 2x\xi \rangle \\ &= 2(a_2 m_3 + a_1 m_2 + a_0 m_1) + \sigma^2, \end{aligned}$$

(where $\langle 2x\xi \rangle = 0$ as $\int_0^t 2x(s) dW_s$ is a martingale)

Main Steps

First steps:

(S0) **moment space:** select the space $\mathbb{M} = \{m_j\}$.

(S1) **moment equations:** derive evolution equations for m_j .

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- ▶ system in (S1) is frequently **infinite**
- ▶ infinite system not a desirable **reduction**
- ▶ **nonlinearity** is crucial
- ▶ **hierarchical structure**

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Next steps:

- (S2) **moment closure:** “higher moments from lower moments”
- (S3) **verification:** does the closed system **approximate** dynamics?

Kolmogorov Equation / Fokker-Planck Equation

Probability density $p = p(x, t | x_0, t_0)$ of x at time t

$$\frac{\partial p}{\partial t} = -\frac{\partial}{\partial x}[(a_2 x^2 + a_1 x + a_0)p] + \frac{\sigma^2}{2} \frac{\partial^2 p}{\partial x^2}.$$

Step (S1) to derive the moment equation:

- ▶ note: $m_j = \int_{\mathbb{R}} x^j p(x, t) dx$
- ▶ multiply Fokker-Planck by x^j and average

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For example, we have

$$\begin{aligned} m_1' &= \langle x' \rangle = \int_{\mathbb{R}} x \frac{\partial p}{\partial t} dx \\ &= \int_{\mathbb{R}} -x \frac{\partial}{\partial x} [(a_2 x^2 + a_1 x + a_0)p] dx + \int_{\mathbb{R}} x \frac{\sigma^2}{2} \frac{\partial^2 p}{\partial x^2} dx. \end{aligned}$$

If p and its derivatives vanish at infinity then

$$m_1' = \int_{\mathbb{R}} [(a_2 x^2 + a_1 x + a_0)p] dx = a_2 m_2 + a_1 m_1 + a_0$$

(II) Kinetic Equations

Basics:

- ▶ spatial variable $x \in \Omega \subset \mathbb{R}^N$
- ▶ momentum variable $v \in \mathbb{R}^N$
- ▶ gas via a single-particle density $\varrho = \varrho(x, v, t)$

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Kinetic equation (mesoscopic dynamics)

$$\frac{\partial \varrho}{\partial t} + v \cdot \nabla_x \varrho = Q(\varrho),$$

where

- ▶ $\nabla_x = \left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_N} \right)^\top$
- ▶ suitable boundary conditions are assumed
- ▶ $\varrho \mapsto Q(\varrho)$ is the **collision operator**

Moment Equations for Kinetic Equation

Instead of probabilistic average, take **velocity average**

$$\langle G \rangle := \int_{\mathbb{R}^N} G(x, v, t) dv$$

Same (similar) procedure:

- ▶ pick polynomial space \mathbb{M} with $\{m_j = m_j(v)\}$
- ▶ multiply the kinetic equation by basis elements
- ▶ **average**, using velocity averaging
- ▶ get (infinite!) hierarchy of moment equations

Remark: classical closure is **Grad's 13 moment system** (in 1949)

(III) Network Dynamics - SIS Model

Basics:

- ▶ goal: model epidemics on a network/graph
- ▶ **graph** with nodes in states S and I
- ▶ SI -link: **infection** at rate τ
- ▶ I -node: **recovery** at rate γ
- ▶ $m_I := \langle I \rangle = \langle I \rangle(t)$ average number of infected
- ▶ $m_S = \langle S \rangle = \langle S \rangle(t)$ average number of susceptibles

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Formal (statistical physics) derivation yields

$$\begin{aligned}\frac{dm_S}{dt} &= \gamma m_I - \tau \langle SI \rangle, \\ \frac{dm_I}{dt} &= \tau \langle SI \rangle - m_I,\end{aligned}$$

where $\langle SI \rangle =: m_{SI}$ = average number of SI -links.

Second-order equations (Keeling; Rand; Taylor et al.):

$$\frac{dm_{SI}}{dt} = \gamma(m_{II} - m_{SI}) + \tau(m_{SSI} - m_{ISI} - m_{SI}),$$

$$\frac{dm_{II}}{dt} = -2\gamma m_{II} + 2\tau(m_{ISI} + m_{SI}),$$

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Observations:

- ▶ different derivation strategies
- ▶ typical **moment closure** problem
- ▶ number of equations **grows rapidly**

Abstract Moment Closure Problem

Infinite-dimensional moment system

$$\begin{aligned}\frac{dm_1}{dt} &= h_1(m_1, m_2, \dots), \\ \frac{dm_2}{dt} &= h_2(m_2, m_3, \dots), \\ \frac{dm_3}{dt} &= \dots, \end{aligned} \tag{1}$$

Moment closure: “high-order moments via lower-order moments”

$$H(m_1, \dots, m_\kappa) = (m_{\kappa+1}, m_{\kappa+2}, \dots).$$

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Final result:

$$\begin{aligned}\frac{dm_1}{dt} &= h_1(m_1, m_2, \dots, m_\kappa, H(m_1, \dots, m_\kappa)), \\ \frac{dm_2}{dt} &= h_2(m_1, m_2, \dots, m_\kappa, H(m_1, \dots, m_\kappa)), \\ \vdots &= \vdots \\ \frac{dm_\kappa}{dt} &= h_\kappa(m_1, m_2, \dots, m_\kappa, H(m_1, \dots, m_\kappa)).\end{aligned}\tag{2}$$

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(Q1) How to **find/select** the mapping H ?

(Q2) How well does (2) **approximate** (1)?

Some Classical Closures

(I) Probability theory closures, e.g., consider SODE case

$$m_j = 0 \quad \text{if } j \geq 3 \text{ and } j \text{ is odd,}$$

$$m_j = (m_2)^{j/2} (j-1)(j-3)\cdots 2 \quad \text{if } j \geq 4 \text{ and } j \text{ is even.}$$

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(II) Physical principle closures, e.g., consider kinetic case

$$\min_{\varrho} \{ \langle \varrho \ln \varrho - \varrho \rangle : \langle M \varrho \rangle = \eta \} = H(\eta),$$

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(III) **Microscopic closures**, e.g., consider **network case**

$$m_{SI} = \langle SI \rangle \approx \langle S \rangle \langle I \rangle = m_S m_I,$$

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$$m_{SI} = \langle SI \rangle \approx \langle S \rangle \langle I \rangle = m_S m_I,$$

de-correlation closure!

Lots of (applied) mathematics work...

Stochastic systems:

- ▶ SODEs: Arnold, Bobryk, Bolotin, Grigoriu, Nasell, Singer, ...
- ▶ Discrete models: Baake, Gower, Leslie, ...

Kinetic equations:

- ▶ max-ent & theory: Devilettes, Grad, Levermore, Torrilhon, ...
- ▶ applications: Christen, Kassubek, Klar, Struchtrup, ...

Networks:

- ▶ stat-phys: Gleeson, Gross, Kirkwood, Kiss, Shaw, Schwartz, ...
- ▶ epidemiology: Dieckmann, Eames, House, Keeling, ...
- ▶ ecology: Bolker, Pacala, Matis, Rand, Volz, ...

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→ “Moment closure - a brief review”, **CK**, arXiv:1505.02190

Conjecture(s) / Direction(s)

- ▶ Closures work only on **restricted assumptions**.
- ▶ **Dynamical systems** view has to be (re-)introduced.
- ▶ Proofs will need **algebraic** and **analytical** tools.

Motivation: Fast-Slow Systems

Fast variables $x \in \mathbb{R}^m$, slow variables $y \in \mathbb{R}^n$, time scale separation $0 < \varepsilon \ll 1$.

$$\begin{cases} x' &= f(x, y) \\ y' &= \varepsilon g(x, y) \end{cases} \quad \xleftrightarrow{\varepsilon t = s} \quad \begin{cases} \varepsilon \dot{x} &= f(x, y) \\ \dot{y} &= g(x, y) \end{cases}$$

$$\downarrow \varepsilon = 0$$

$$\begin{cases} x' &= f(x, y) \\ y' &= 0 \end{cases}$$

fast subsystem

$$\downarrow \varepsilon = 0$$

$$\begin{cases} 0 &= f(x, y) \\ \dot{y} &= g(x, y) \end{cases}$$

slow subsystem

- ▶ Think: x = higher-order moments, y = lower-order moments!

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fast subsystem

$$\downarrow \varepsilon = 0$$

$$\begin{cases} 0 = f(x, y) \\ \dot{y} = g(x, y) \end{cases}$$

slow subsystem

- ▶ Think: x = higher-order moments, y = lower-order moments!
- ▶ $C_0 := \{f = 0\}$ = **critical manifold** = equil. of fast subsystem.
- ▶ C_0 is **normally hyperbolic** if $D_x f$ has no zero-real-part eigenvalues.
- ▶ **Fenichel's Thm:** Normal hyperbolicity \Rightarrow "nice" perturbation C_ε .

The Last Slide...

Summary & Outlook:

- ▶ many open problems...
- ▶ **combinatorial**: How many equations? Structures?
- ▶ **algebraic**: Symmetries/invariants? Normal forms?
- ▶ **probabilistic**: Stochastic closures? Microscopic closures?
- ▶ **analytical**: Error estimates? Entropy closure validity?
- ▶ **geometric**: Slow manifolds? Geometry of moment space?
- ▶ **dynamical**: Capturing bifurcations? Phase-space dissection?

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Papers, preprints, etc all available from:

- ▶ www.asc.tuwien.ac.at/~ckuehn and **arXiv**
- ▶ “Moment closure - a brief review”, Christian Kuehn, arXiv:1505.02190
- ▶ “Multiple Time Scale Dynamics”, Christian Kuehn, Springer, 2015

Thank you very much for your attention!