

# NIP, O-minimality and Neural Networks

Lothar Sebastian Krapp

Universität Konstanz, Fachbereich Mathematik und Statistik

14 May 2018

Oberseminar mathematische Logik, Mengenlehre und Modelltheorie

1 NIP

2 O-minimality

3 Neural Networks

1 NIP

2 O-minimality

3 Neural Networks

# VC Dimension

## VC Dimension

Throughout this section we fix a language  $\mathcal{L}$ , a complete  $\mathcal{L}$ -theory  $T$  and a monster model  $\mathbb{M}$  of  $T$ . We abbreviate  $\mathbb{M} \models \varphi$  by  $\models \varphi$ .

## VC Dimension

Throughout this section we fix a language  $\mathcal{L}$ , a complete  $\mathcal{L}$ -theory  $T$  and a monster model  $\mathbb{M}$  of  $T$ . We abbreviate  $\mathbb{M} \models \varphi$  by  $\models \varphi$ .

### Definition

Let  $\varphi(\underline{x}, \underline{y})$  be a formula. The **Vapnik–Chervonenkis dimension (VC dimension)** of  $\varphi$  is defined as

$$\text{vc}(\varphi(\underline{x}; \underline{y})) := \max\{n < \omega \mid \exists(\underline{a}_i)_{i < n} \exists(\underline{b}_J)_{J \subseteq \{0, \dots, n-1\}} [\models \varphi(\underline{a}_i; \underline{b}_J) \text{ if and only if } i \in J]\}$$

if the maximum exists, and  $\infty$  otherwise.

# VC Dimension

## VC Dimension

### Example

Let  $\mathcal{T}_{\text{dlo}}$  be the theory of dense linear ordered without endpoints. Consider the formula  $\varphi(x; y)$  given by  $x < y$ .



## VC Dimension

### Example

Let  $T_{\text{dlo}}$  be the theory of dense linear ordered without endpoints. Consider the formula  $\varphi(x; y)$  given by  $x < y$ .

Let  $a_0 \in \mathbb{M}$  be arbitrary and set  $b_\emptyset = a_0$  and  $b_{\{0\}} > a_0$ . Then  $\not\models a_0 < b_\emptyset$  and  $\models a_0 < b_{\{0\}}$ . We obtain  $\text{vc}(x < y) \geq 1$ .

## VC Dimension

### Example

Let  $T_{\text{dlo}}$  be the theory of dense linear ordered without endpoints. Consider the formula  $\varphi(x; y)$  given by  $x < y$ .

Let  $a_0 \in \mathbb{M}$  be arbitrary and set  $b_\emptyset = a_0$  and  $b_{\{0\}} > a_0$ . Then  $\not\models a_0 < b_\emptyset$  and  $\models a_0 < b_{\{0\}}$ . We obtain  $\text{vc}(x < y) \geq 1$ .

Now let  $a_0, a_1 \in \mathbb{M}$  be arbitrary. Assume that there exist  $b_{\{0\}}, b_{\{1\}} \in \mathbb{M}$  such that  $a_i < b_j$  if and only if  $i \in J$  for  $(i, J) \in \{0, 1\} \times \{\{0\}, \{1\}\}$ . Then

$$a_0 < b_{\{0\}} \leq a_1 < b_{\{1\}} \leq a_0,$$

a contradiction. Hence,  $\text{vc}(x < y) \leq 1$ .

# NIP

# NIP

## Definition

A formula  $\varphi(\underline{x}; \underline{y})$  has the **independence property** (or is **IP**) if  $vc(\varphi) = \infty$ . If  $\varphi$  does not have the independence property, it is called **NIP**. A complete theory  $T$  in which every formula is NIP is also called NIP.

# NIP

## Definition

A formula  $\varphi(\underline{x}; \underline{y})$  has the **independence property** (or is **IP**) if  $vc(\varphi) = \infty$ . If  $\varphi$  does not have the independence property, it is called **NIP**. A complete theory  $T$  in which every formula is NIP is also called NIP.

**Examples of NIP theories:**

# NIP

## Definition

A formula  $\varphi(\underline{x}; \underline{y})$  has the **independence property** (or is **IP**) if  $vc(\varphi) = \infty$ . If  $\varphi$  does not have the independence property, it is called **NIP**. A complete theory  $T$  in which every formula is NIP is also called NIP.

## Examples of NIP theories:

- o-minimal theories
- weakly o-minimal theories
- C-minimal theories
- ...

# Alternation Number

## Alternation Number

A sequence  $(\underline{a}_i)_{i < \omega}$  is indiscernible if for every  $n < \omega$  and any  $i_1 < \dots < i_n < \omega$  and  $j_1 < \dots < j_n < \omega$  the tuples  $(\underline{a}_{i_1}, \dots, \underline{a}_{i_n})$  and  $(\underline{a}_{j_1}, \dots, \underline{a}_{j_n})$  have the same type, i.e.  $\varphi(\underline{a}_{i_1}, \dots, \underline{a}_{i_n})$  holds if and only if  $\varphi(\underline{a}_{j_1}, \dots, \underline{a}_{j_n})$ .



## Alternation Number

A sequence  $(\underline{a}_i)_{i < \omega}$  is indiscernible if for every  $n < \omega$  and any  $i_1 < \dots < i_n < \omega$  and  $j_1 < \dots < j_n < \omega$  the tuples  $(\underline{a}_{i_1}, \dots, \underline{a}_{i_n})$  and  $(\underline{a}_{j_1}, \dots, \underline{a}_{j_n})$  have the same type, i.e.  $\varphi(\underline{a}_{i_1}, \dots, \underline{a}_{i_n})$  holds if and only if  $\varphi(\underline{a}_{j_1}, \dots, \underline{a}_{j_n})$ .

### Definition

Let  $\varphi(\underline{x}; \underline{y})$  be a formula. Let  $X \subseteq \omega$  be the set of all  $n < \omega$  for which there are an indiscernible sequence  $(\underline{a}_i)_{i < \omega}$  and a tuple  $\underline{b}$  such that for any  $i < n - 1$  we have  $\models \varphi(\underline{a}_i; \underline{b}) \leftrightarrow \neg \varphi(\underline{a}_{i+1}; \underline{b})$ . The **alternation number**  $\text{alt}(\varphi)$  of  $\varphi$  is defined as the maximum of  $X$  if it exists, or  $\infty$  otherwise.

# Alternation Number and VC Dimension

# Alternation Number and VC Dimension

## Proposition

Let  $\varphi(\underline{x}; \underline{y})$  be a formula. Then  $\text{alt}(\varphi) \leq 2 \text{vc}(\varphi) + 1$ .

# Alternation Number and VC Dimension

## Proposition

Let  $\varphi(\underline{x}; \underline{y})$  be a formula. Then  $\text{alt}(\varphi) \leq 2 \text{vc}(\varphi) + 1$ .

## Corollary

- ①  $\varphi$  is NIP.
- ②  $\text{vc}(\varphi) < \infty$ .
- ③  $\text{alt}(\varphi) < \infty$ .
- ④ For every indiscernible sequence  $(\underline{a}_i)_{i < \omega}$  and every tuple  $\underline{b}$  the set of indices  $i < \omega$  such that  $\models \varphi(\underline{a}_i; \underline{b})$  holds is finite or cofinite.

# Further Tools

## Further Tools

### Proposition

The set of NIP formulas in  $\mathcal{T}$  is closed under boolean combinations.

## Further Tools

### Proposition

The set of NIP formulas in  $\mathcal{T}$  is closed under boolean combinations.

*Proof.*

Let  $\varphi(\underline{x}; \underline{y})$  and  $\psi(\underline{x}; \underline{y})$  be formulas with finite alternation number.

## Further Tools

### Proposition

The set of NIP formulas in  $\mathcal{T}$  is closed under boolean combinations.

*Proof.*

Let  $\varphi(\underline{x}; \underline{y})$  and  $\psi(\underline{x}; \underline{y})$  be formulas with finite alternation number. By the previous corollary, it suffices to show that  $\neg\varphi(\underline{x}; \underline{y})$  and  $\varphi(\underline{x}; \underline{y}) \wedge \psi(\underline{x}; \underline{y})$  have finite alternation number.



## Further Tools

### Proposition

The set of NIP formulas in  $\mathcal{T}$  is closed under boolean combinations.

*Proof.*

Let  $\varphi(\underline{x}; \underline{y})$  and  $\psi(\underline{x}; \underline{y})$  be formulas with finite alternation number. By the previous corollary, it suffices to show that  $\neg\varphi(\underline{x}; \underline{y})$  and  $\varphi(\underline{x}; \underline{y}) \wedge \psi(\underline{x}; \underline{y})$  have finite alternation number. Indeed,  $\text{alt}(\neg\varphi) = \text{alt}(\varphi)$  and  $\text{alt}(\varphi \wedge \psi) \leq \text{alt}(\varphi) + \text{alt}(\psi) - 1$ .

## Further Tools

### Proposition

The set of NIP formulas in  $T$  is closed under boolean combinations.

*Proof.*

Let  $\varphi(\underline{x}; \underline{y})$  and  $\psi(\underline{x}; \underline{y})$  be formulas with finite alternation number. By the previous corollary, it suffices to show that  $\neg\varphi(\underline{x}; \underline{y})$  and  $\varphi(\underline{x}; \underline{y}) \wedge \psi(\underline{x}; \underline{y})$  have finite alternation number. Indeed,  $\text{alt}(\neg\varphi) = \text{alt}(\varphi)$  and  $\text{alt}(\varphi \wedge \psi) \leq \text{alt}(\varphi) + \text{alt}(\psi) - 1$ .

### Theorem

*Let  $T$  be a complete theory. Suppose that every formula of the form  $\varphi(\underline{x}; \underline{y})$  is NIP in  $T$ . Then  $T$  is NIP.*

1 NIP

2 O-minimality

3 Neural Networks

# $T_0$ -minimality

## $T_0$ -minimality

### Definition

Let  $T_0$  be a theory in a language  $\mathcal{L}_0$ . A complete theory  $T \supseteq T_0$  in a language  $\mathcal{L} \supseteq \mathcal{L}_0$  is said to be  **$T_0$ -minimal** if for every  $\mathcal{L}$ -formula  $\varphi(x, y_1, \dots, y_m)$ , any model  $\mathcal{M} \models T$  and any parameters  $b_1, \dots, b_m \in M$ , there exist a quantifier-free  $\mathcal{L}_0$ -formula  $\psi(x, z_1, \dots, z_n)$  and parameters  $c_1, \dots, c_n \in M$  such that

$$\mathcal{M} \models \forall x (\varphi(x, b_1, \dots, b_m) \leftrightarrow \psi(x, c_1, \dots, c_n)).$$

If  $T_0$  is the theory of linear orders, then a  $T_0$ -minimal theory  $T$  is called **o-minimal**.

## $T_0$ -minimality

### Definition

Let  $T_0$  be a theory in a language  $\mathcal{L}_0$ . A complete theory  $T \supseteq T_0$  in a language  $\mathcal{L} \supseteq \mathcal{L}_0$  is said to be  **$T_0$ -minimal** if for every  $\mathcal{L}$ -formula  $\varphi(x, y_1, \dots, y_m)$ , any model  $\mathcal{M} \models T$  and any parameters  $b_1, \dots, b_m \in M$ , there exist a quantifier-free  $\mathcal{L}_0$ -formula  $\psi(x, z_1, \dots, z_n)$  and parameters  $c_1, \dots, c_n \in M$  such that

$$\mathcal{M} \models \forall x (\varphi(x, b_1, \dots, b_m) \leftrightarrow \psi(x, c_1, \dots, c_n)).$$

If  $T_0$  is the theory of linear orders, then a  $T_0$ -minimal theory  $T$  is called **o-minimal**.

### Example

## $T_0$ -minimality

### Definition

Let  $T_0$  be a theory in a language  $\mathcal{L}_0$ . A complete theory  $T \supseteq T_0$  in a language  $\mathcal{L} \supseteq \mathcal{L}_0$  is said to be  **$T_0$ -minimal** if for every  $\mathcal{L}$ -formula  $\varphi(x, y_1, \dots, y_m)$ , any model  $\mathcal{M} \models T$  and any parameters  $b_1, \dots, b_m \in M$ , there exist a quantifier-free  $\mathcal{L}_0$ -formula  $\psi(x, z_1, \dots, z_n)$  and parameters  $c_1, \dots, c_n \in M$  such that

$$\mathcal{M} \models \forall x (\varphi(x, b_1, \dots, b_m) \leftrightarrow \psi(x, c_1, \dots, c_n)).$$

If  $T_0$  is the theory of linear orders, then a  $T_0$ -minimal theory  $T$  is called **o-minimal**.

### Example

$T_{\text{rcf}}$ , the theory of real closed fields, is  $T_{\text{lo}}$ -minimal. E.g.  
 $(\mathbb{R}, +, \cdot, 0, 1, <) \models \forall x (x^2 < 2 \leftrightarrow (-\sqrt{2} < x \wedge x < \sqrt{2}))$ .

# O-minimality Implies NIP



## O-minimality Implies NIP

### Proposition

Let  $T_0$  be a theory. Suppose that for any complete theory  $T' \supseteq T_0$  every quantifier-free  $T_0$ -formula of the form  $\varphi(x; \underline{y})$  is NIP in  $T'$ . Then every  $T_0$ -minimal theory  $T$  is NIP.

## O-minimality Implies NIP

### Proposition

Let  $T_0$  be a theory. Suppose that for any complete theory  $T' \supseteq T_0$  every quantifier-free  $T_0$ -formula of the form  $\varphi(x; \underline{y})$  is NIP in  $T'$ . Then every  $T_0$ -minimal theory  $T$  is NIP.

### Theorem

Let  $T$  be an o-minimal theory. Then  $T$  is NIP.

## O-minimality Implies NIP

### Proposition

Let  $T_0$  be a theory. Suppose that for any complete theory  $T' \supseteq T_0$  every quantifier-free  $T_0$ -formula of the form  $\varphi(x; \underline{y})$  is NIP in  $T'$ . Then every  $T_0$ -minimal theory  $T$  is NIP.

### Theorem

Let  $T$  be an o-minimal theory. Then  $T$  is NIP.

*Proof.*

## O-minimality Implies NIP

### Proposition

Let  $T_0$  be a theory. Suppose that for any complete theory  $T' \supseteq T_0$  every quantifier-free  $T_0$ -formula of the form  $\varphi(x; \underline{y})$  is NIP in  $T'$ . Then every  $T_0$ -minimal theory  $T$  is NIP.

### Theorem

Let  $T$  be an o-minimal theory. Then  $T$  is NIP.

*Proof.*

Any quantifier-free formula is (equivalent to) a boolean combination of formulas of the form  $x < y$ .

## O-minimality Implies NIP

### Proposition

Let  $T_0$  be a theory. Suppose that for any complete theory  $T' \supseteq T_0$  every quantifier-free  $T_0$ -formula of the form  $\varphi(x; \underline{y})$  is NIP in  $T'$ . Then every  $T_0$ -minimal theory  $T$  is NIP.

### Theorem

Let  $T$  be an o-minimal theory. Then  $T$  is NIP.

*Proof.*

Any quantifier-free formula is (equivalent to) a boolean combination of formulas of the form  $x < y$ . Since  $\text{vc}(x < y) = 1$ , these are NIP.

1 NIP

2 O-minimality

3 Neural Networks

# Brief Historical Overview

## Brief Historical Overview

- **Vapnik, Chervonenkis, 1971:** paper on statistical learning theory introducing the notion of VC dimensions (for sets rather than formulas)



## Brief Historical Overview

- **Vapnik, Chervonenkis, 1971:** paper on statistical learning theory introducing the notion of VC dimensions (for sets rather than formulas)
- **Shelah, 1971:** paper on model theory introducing the independence property

## Brief Historical Overview

- **Vapnik, Chervonenkis, 1971:** paper on statistical learning theory introducing the notion of VC dimensions (for sets rather than formulas)
- **Shelah, 1971:** paper on model theory introducing the independence property
- **Pillay, Steinhorn, 1986:** proof that o-minimality implies NIP

## Brief Historical Overview

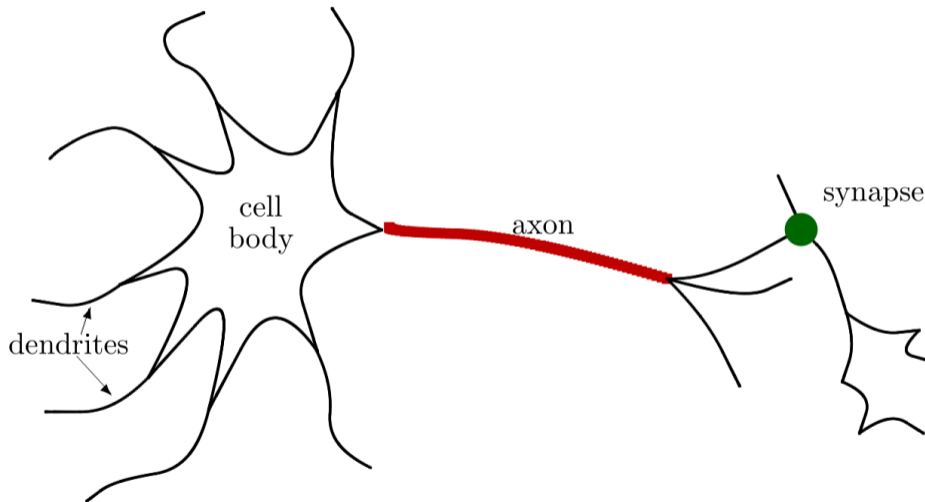
- **Vapnik, Chervonenkis, 1971:** paper on statistical learning theory introducing the notion of VC dimensions (for sets rather than formulas)
- **Shelah, 1971:** paper on model theory introducing the independence property
- **Pillay, Steinhorn, 1986:** proof that o-minimality implies NIP
- **Laskowski, 1992:** connecting the notion of VC dimension to the independence property

## Brief Historical Overview

- **Vapnik, Chervonenkis, 1971:** paper on statistical learning theory introducing the notion of VC dimensions (for sets rather than formulas)
- **Shelah, 1971:** paper on model theory introducing the independence property
- **Pillay, Steinhorn, 1986:** proof that o-minimality implies NIP
- **Laskowski, 1992:** connecting the notion of VC dimension to the independence property
- **Wilkie, 1996:** proof that  $\mathbb{R}_{\text{an,exp}}$  is o-minimal

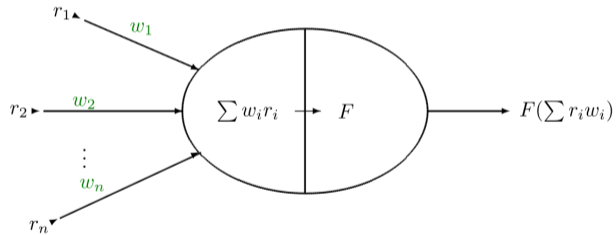
# Neurons

# Neurons



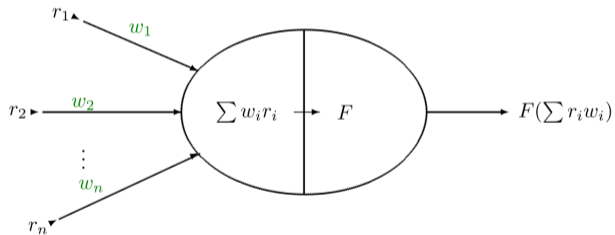
# Artificial Neurons

# Artificial Neurons



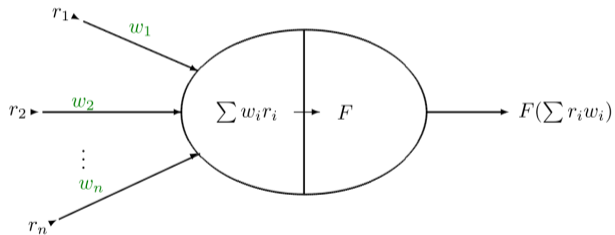


# Artificial Neurons



$r_i$ : real numbers, **input**

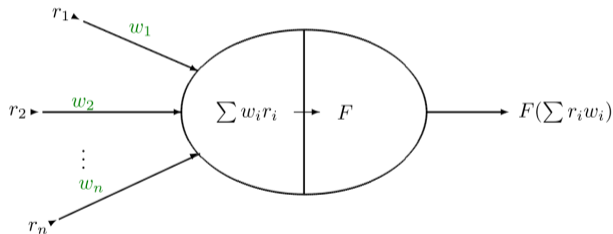
# Artificial Neurons



$r_i$ : real numbers, **input**

$w_i$ : real numbers, **weights**

# Artificial Neurons

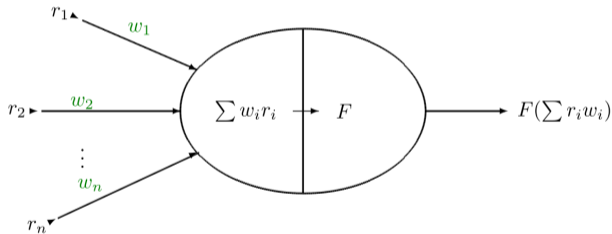


$r_i$ : real numbers, **input**

$w_i$ : real numbers, **weights**

$\sum w_i r_i$ : weighted sum

# Artificial Neurons



$r_i$ : real numbers, **input**

$w_i$ : real numbers, **weights**

$\sum w_i r_i$ : weighted sum

$F$ : real valued function,  
**activation function**

# Activation Functions

Typical activation functions  $F$ :

# Activation Functions

Typical activation functions  $F$ :

- characteristic functions on intervals  $(a, \infty)$

# Activation Functions

Typical activation functions  $F$ :

- characteristic functions on intervals  $(a, \infty)$
- piecewise linear functions

# Activation Functions

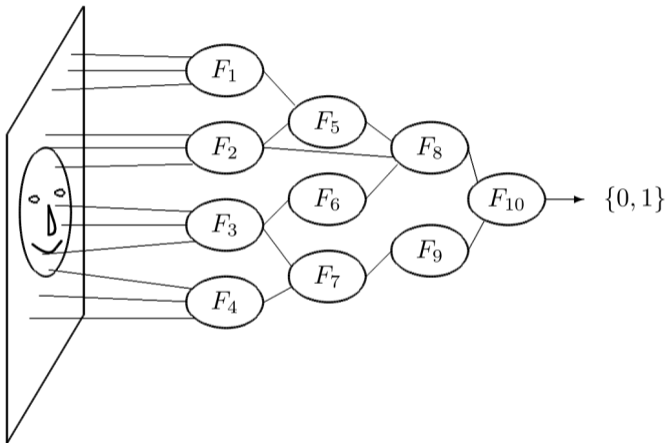
Typical activation functions  $F$ :

- characteristic functions on intervals  $(a, \infty)$
- piecewise linear functions
- sigmoid function  $F(t) = \frac{1}{1+\exp(-t)}$



# Artificial Neural Network

# Artificial Neural Network



(10 neurons, 4 layers)

# Artificial Neural Network

$X$ : input space, e.g.  $(\mathbb{R}^2 \times \{0, \dots, 255\})^{12}$

# Artificial Neural Network

$X$ : input space, e.g.  $(\mathbb{R}^2 \times \{0, \dots, 255\})^{12}$

$Y$ : output space, e.g.  $\{0, 1\}$

# Artificial Neural Network

$X$ : input space, e.g.  $(\mathbb{R}^2 \times \{0, \dots, 255\})^{12}$

$Y$ : output space, e.g.  $\{0, 1\}$

$F_i(\underline{x}, \underline{w})$ : activation functions

# Artificial Neural Network

$X$ : input space, e.g.  $(\mathbb{R}^2 \times \{0, \dots, 255\})^{12}$

$Y$ : output space, e.g.  $\{0, 1\}$

$F_i(\underline{x}, \underline{w})$ : activation functions

The network computes a class of functions  $X \rightarrow Y$ .

# Learning Cycle

# Learning Cycle

- 1 network is in an initial state  $h$  coded by the weights



# Learning Cycle

- 1 network is in an initial state  $h$  coded by the weights
- 2 training sample  $(x, y) \in X \times Y$  is chosen

# Learning Cycle

- 1 network is in an initial state  $h$  coded by the weights
- 2 training sample  $(x, y) \in X \times Y$  is chosen
- 3  $h(x)$  is computed

# Learning Cycle

- 1 network is in an initial state  $h$  coded by the weights
- 2 training sample  $(x, y) \in X \times Y$  is chosen
- 3  $h(x)$  is computed
- 4 the weights are adjusted depending on  $h(x) = y$  or  $h(x) \neq y$  (also considering previous training samples)

# Learning Cycle

- 1 network is in an initial state  $h$  coded by the weights
- 2 training sample  $(x, y) \in X \times Y$  is chosen
- 3  $h(x)$  is computed
- 4 the weights are adjusted depending on  $h(x) = y$  or  $h(x) \neq y$  (also considering previous training samples)

**Goal:** After finitely many training samples the network is in a state  $h$  which gives a good approximation to recognising the pattern.

# Formal Learning

Neural network  $H$ : set of all possible functions depending on the weights

# Formal Learning

Neural network  $H$ : set of all possible functions depending on the weights

Sample space  $Z = X \times Y$

# Formal Learning

Neural network  $H$ : set of all possible functions depending on the weights

Sample space  $Z = X \times Y$

**Learning algorithm  $L$ :**

$$L : \bigcup_{m=1}^{\infty} Z^m \rightarrow H.$$

# Learning Algorithm

$p$  – probability measure on  $Z$  measuring the probability that a sample is chosen as training sample



# Learning Algorithm

$p$  – probability measure on  $Z$  measuring the probability that a sample is chosen as training sample

$er_p(h) = p\{(x, y) \in Z \mid h(x) \neq y\}$  – error of  $h \in H$

# Learning Algorithm

$p$  – probability measure on  $Z$  measuring the probability that a sample is chosen as training sample

$er_p(h) = p\{(x, y) \in Z \mid h(x) \neq y\}$  – error of  $h \in H$

$opt_p(H) = \inf_{h \in H} er_p(h)$  – best approximation in  $H$  for given  $p$

# Learning Algorithm

## Definition

# Learning Algorithm

## Definition

Let  $H$  be a collection of functions  $X \rightarrow Y$  for a given sample space  $Z = X \times Y$ . A **learning algorithm**  $L$  is a map

$$L : \bigcup_{m=1}^{\infty} Z^m \rightarrow H$$

such that it has the following property:

# Learning Algorithm

## Definition

Let  $H$  be a collection of functions  $X \rightarrow Y$  for a given sample space  $Z = X \times Y$ . A **learning algorithm**  $L$  is a map

$$L : \bigcup_{m=1}^{\infty} Z^m \rightarrow H$$

such that it has the following property:

$$\forall \varepsilon, \delta \in (0, 1) \exists m_0 \in \mathbb{N} \forall m \geq m_0 :$$

# Learning Algorithm

## Definition

Let  $H$  be a collection of functions  $X \rightarrow Y$  for a given sample space  $Z = X \times Y$ . A **learning algorithm**  $L$  is a map

$$L : \bigcup_{m=1}^{\infty} Z^m \rightarrow H$$

such that it has the following property:

$\forall \varepsilon, \delta \in (0, 1) \exists m_0 \in \mathbb{N} \forall m \geq m_0 :$

for any probability measure  $p$  on  $Z$  we have

$$p^m \{z \in Z^m \mid \text{er}_p(L(z)) < \text{opt}_p(H) + \varepsilon\} \geq 1 - \delta,$$

where  $p^m$  is the product measure on  $Z^m$ .

# Learning Algorithm

## Definition

Let  $H$  be a collection of functions  $X \rightarrow Y$  for a given sample space  $Z = X \times Y$ . A **learning algorithm**  $L$  is a map

$$L : \bigcup_{m=1}^{\infty} Z^m \rightarrow H$$

such that it has the following property:

$$\forall \varepsilon, \delta \in (0, 1) \exists m_0 \in \mathbb{N} \forall m \geq m_0 :$$

for any probability measure  $p$  on  $Z$  we have

$$p^m \{z \in Z^m \mid \text{er}_p(L(z)) < \text{opt}_p(H) + \varepsilon\} \geq 1 - \delta,$$

where  $p^m$  is the product measure on  $Z^m$ .

$H$  is called **learnable** if there exists a learning algorithm for  $H$ .

# NIP Implies Learnability



## NIP Implies Learnability

### Theorem

Let  $\mathcal{R} = (\mathbb{R}, +, \cdot, <, \dots)$  be an expansion of  $(\mathbb{R}, +, \cdot, <)$ ,  $X \subseteq \mathbb{R}^d$  a (parametrically) definable set over  $\mathcal{R}$  and let  $H$  be a collection of activation functions of a neural network  $X \rightarrow \{0, 1\}$  (parametrically) definable over  $\mathcal{R}$ . Suppose that the complete theory of  $\mathcal{R}$  is NIP. Then  $H$  is learnable.

## NIP Implies Learnability

### Theorem

Let  $\mathcal{R} = (\mathbb{R}, +, \cdot, <, \dots)$  be an expansion of  $(\mathbb{R}, +, \cdot, <)$ ,  $X \subseteq \mathbb{R}^d$  a (parametrically) definable set over  $\mathcal{R}$  and let  $H$  be a collection of activation functions of a neural network  $X \rightarrow \{0, 1\}$  (parametrically) definable over  $\mathcal{R}$ . Suppose that the complete theory of  $\mathcal{R}$  is NIP. Then  $H$  is learnable.

Since  $\mathbb{R}_{\text{an,exp}}$  is o-minimal and thus NIP, a set  $H$  of  $\mathbb{R}_{\text{an,exp}}$ -definable activation functions of a neural network is learnable.

## References

- [1] A. YA. CHERVONENKIS and V. N. VAPNIK, 'The uniform convergence of frequencies of the appearance of events to their probabilities', *Teor. Veroyatnost. i Primenen.* 16 (1971) 264–279 (Russian), *Theor. Probability Appl.* 16 (1971) 264–280 (English).
- [2] M. C. LASKOWSKI, 'Vapnik–Chervonenkis classes of definable sets', *J. London Math. Soc.* (2) 45 (1992) 377–384.
- [3] A. PILLAY and C. STEINHORN, 'Definable sets in ordered structures', I, *Trans. Amer. Math. Soc.* 295 (1986) 565–592.
- [4] S. SHELAH, 'Stability, the f.c.p., and superstability; model theoretic properties of formulas in first order theory', *Ann. Math. Logic* 3 (1971) 271–362.

Graphics from:

- [5] M. TRESSL, 'Introduction to o-minimal structures and an application to neural network learning', Preprint, 2010.