

REAL ALGEBRAIC GEOMETRY LECTURE NOTES
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THE TARSKI-SEIDENBERG PRINCIPLE

Main Lemma. For any real closed field R and every sequence of polynomials $f_1, \dots, f_s \in R[X]$ of degrees $\leq m$, with f_s nonconstant and none of the f_1, \dots, f_{s-1} identically zero, we have $SIGN_R(f_1, \dots, f_s) \in W_{s,m}$ is completely determined by $SIGN_R(f_1, \dots, f_{s-1}, f'_s, g_1, \dots, g_s) \in W_{2s,m}$, where f'_s is the derivative of f_s , and g_1, \dots, g_s are the remainders of the euclidean division of f_s by $f_1, \dots, f_{s-1}, f'_s$, respectively.

Equivalently, the map $\varphi : W_{2s,m} \longrightarrow W_{s,m}$

$$SIGN_R(f_1, \dots, f_{s-1}, f'_s, g_1, \dots, g_s) \longmapsto SIGN_R(f_1, \dots, f_s)$$

is well defined.

In other words, for any $(f_1, \dots, f_s), (F_1, \dots, F_s) \in R[X]$,
 $SIGN_R(f_1, \dots, f_{s-1}, f'_s, g_1, \dots, g_s) = SIGN_R(F_1, \dots, F_{s-1}, F'_s, G_1, \dots, G_s)$
 $\Rightarrow SIGN_R(f_1, \dots, f_s) = SIGN_R(F_1, \dots, F_s)$.

Proof. Assume $w = SIGN_R(f_1, \dots, f_{s-1}, f'_s, g_1, \dots, g_s)$ is given.

Let $x_1 < \dots < x_N$, with $N \leq 2sm$, be the roots in R of those polynomials among $f_1, \dots, f_{s-1}, f'_s, g_1, \dots, g_s$ that are not identically zero. Extract from these the subsequence $x_{i_1} < \dots < x_{i_M}$ of the roots of the polynomials $f_1, \dots, f_{s-1}, f'_s$. By convention, let $x_{i_0} := x_0 = -\infty$; $x_{i_{M+1}} := x_{N+1} = +\infty$.

Note that the sequence $x_{i_1} < \dots < x_{i_M}$ depends only on w .

For $k = 1, \dots, M$ one of the polynomials $f_1, \dots, f_{s-1}, f'_s$ vanishes at x_{i_k} . This allows to choose a map (determined by w)

$$\theta : \{1, \dots, M\} \rightarrow \{1, \dots, s\}$$

such that $f_s(x_{i_k}) = g_{\theta(k)}(x_{i_k})$

(This goes via polynomial division $f_s = f_{\theta(k)}q_{\theta(k)} + g_{\theta(k)}$, where $f_{\theta(k)}(x_{i_k}) = 0$).

Claim I. The existence of a root of f_s in an interval $]x_{i_k}, x_{i_{k+1}}[$, for $k = 0, \dots, M$ depends only on w .

Proof of Claim I.

Case 1: f_s has a root in $] - \infty, x_{i_1}[$ (if $M \neq 0$) if and only if

$$\text{sign}(f'_s(] - \infty, x_1[)) \text{sign}(g_{\theta(1)}(x_{i_1})) = 1,$$

equivalently iff

$$\text{sign}(f'_s(] - \infty, x_1[)) = \text{sign}f_s(x_{i_1}).$$

(\Rightarrow) We want to show that if $\text{sign}(f'_s(] - \infty, x_1[)) = \text{sign}f_s(x_{i_1})$, then f_s has a root in $] - \infty, x_{i_1}[$.

Suppose on contradiction that f_s has no root in $] - \infty, x_{i_1}[$, then $\text{sign}f_s$ must be constant and nonzero on $] - \infty, x_{i_1}[$, so we get $0 \neq \text{sign}f_s(] - \infty, x_1[) = \text{sign}f_s(] - \infty, x_{i_1}[) = \text{sign}f_s(x_{i_1}) = \text{sign}f'_s(] - \infty, x_1[)$

$\Rightarrow \text{sign}f_s(] - \infty, x_1[) = \text{sign}f'_s(] - \infty, x_1[)$, a contradiction [because on $] - \infty, -D[: \text{sign}f(x) = (-1)^m \text{sign}(d)$ for $f = dx^m + \dots + d_0$ and $\text{sign}f'(x) = (-1)^{m-1} \text{sign}(md)$ for $f' = mdx^{m-1} + \dots$, see Corollary 2.1 of lecture 6 (05/11/09)].

(\Leftarrow) Assume that f_s has a root (say) $x \in] - \infty, x_{i_1}[$.

Note that $\text{sign}f_s(x_{i_1}) \neq 0$ [otherwise $f_s(x_{i_1}) = f(x_{i_1}) = 0$, so (by Rolle's theorem) f'_s has a root in $]x, x_{i_1}[$ and the only possibility is $x_1 \in]x, x_{i_1}[$ (by our listing), but then $x_1 = x_{i_1}$, a contradiction].

Note also that f_s cannot have two roots (counting multiplicity) in $] - \infty, x_{i_1}[$ [otherwise f'_s will be forced to have a root in $] - \infty, x_{i_1}[$, a contradiction as before].

So

$$-\text{sign}f_s(] - \infty, x[) = \text{sign}f_s(]x, x_{i_1}[) = \text{sign}f_s(x_{i_1}),$$

also (by same argument as before)

$$-\text{sign}f_s(] - \infty, x[) = \text{sign}f'_s(] - \infty, x_1[),$$

therefore, we get

$$\text{sign}f'_s(] - \infty, x_1[) = \text{sign}f_s(x_{i_1}). \quad \square \text{ (case 1)}$$

Case 2: Similarly one proves that: f_s has a root in $]x_{i_M}, +\infty[$ (if $M \neq 0$) if and only if

$$\text{sign}(f'_s(]x_N, +\infty[)) \text{sign}(g_{\theta(M)}(x_{i_M})) = -1,$$

$$\text{(i.e. iff } \text{sign}f'_s(]x_N, +\infty[) = -\text{sign}f_s(x_{i_M}) \neq 0 \text{)}.$$

Case 3: f_s has a root in $]x_{i_k}, x_{i_{k+1}}[$, for $k = 1, \dots, M - 1$, if and only if

$$\text{sign}(g_{\theta(k)}(x_{i_k})) \text{sign}(g_{\theta(k+1)}(x_{i_{k+1}})) = -1,$$

equivalently iff

$$\text{sign} f_s(x_{i_k}) = -\text{sign} f_s(x_{i_{k+1}}).$$

(Proof is clear because if f_s has a root in $]x_{i_k}, x_{i_{k+1}}[$, then this root is of multiplicity 1 and therefore a sign change must occur.)

Case 4: f_s has exactly one root in $] -\infty, +\infty[$ if $M = 0$. \square (claim I)

Claim II. $SIGN_R(f_1, \dots, f_s)$ depends only on w .

Proof of Claim II.

Notation: Let $y_1 < \dots < y_L$, with $L \leq sm$, be the roots in \mathbb{R} of the polynomials f_1, \dots, f_s . As before, let $y_0 := -\infty, y_{L+1} := +\infty$.

Set $I_k := (y_k, y_{k+1})$, $k = 0, \dots, L$.

Define

$$\begin{aligned} \rho : \{0, \dots, L+1\} &\longrightarrow \{0, \dots, M+1\} \cup \{(k, k+1) \mid k = 0, \dots, M\} \\ l &\longmapsto \begin{cases} k & \text{if } y_l = x_{i_k}, \\ (k, k+1) & \text{if } y_l \in]x_{i_k}, x_{i_{k+1}}[\end{cases} \end{aligned}$$

Note that by Claim I, L and ρ depends only on w . So, to prove claim II it is enough to show that $SIGN_R(f_1, \dots, f_s)$ depends only on ρ and w .

Also,

$$SIGN_R(f_1, \dots, f_s) := \begin{pmatrix} \text{sign} f_1(I_0) & \text{sign} f_1(y_1) & \dots & \text{sign} f_1(y_L) & \text{sign} f_1(I_L) \\ \vdots & \vdots & & \vdots & \vdots \\ \text{sign} f_{s-1}(I_0) & \text{sign} f_{s-1}(y_1) & \dots & \text{sign} f_{s-1}(y_L) & \text{sign} f_{s-1}(I_L) \\ \text{sign} f_s(I_0) & \text{sign} f_s(y_1) & \dots & \text{sign} f_s(y_L) & \text{sign} f_s(I_L) \end{pmatrix}$$

is an $s \times (2L+1)$ matrix with coefficients in $\{-1, 0, +1\}$.

Case 1: $j = 1, \dots, s-1$

For $l \in \{0, \dots, L+1\}$ we have

- if $\rho(l) = k \Rightarrow \text{sign}(f_j(y_l)) = \text{sign}(f_j(x_{i_k}))$,
- if $\rho(l) = (k, k+1) \Rightarrow \text{sign}(f_j(y_l)) = \text{sign}(f_j(]x_{i_k}, x_{i_{k+1}}[))$.

So, $\text{sign}(f_j(y_l))$ is known from w and ρ , for all $j = 1, \dots, s-1$ and $l \in \{0, \dots, L+1\}$.

We also have

- if $\rho(l) = k$ or $(k, k+1) \Rightarrow \text{sign}(f_j(]y_l, y_{l+1}[)) = \text{sign}(f_j(]x_{i_k}, x_{i_{k+1}}[))$.

So, $\text{sign}(f_j(]y_l, y_{l+1}[))$ is known from w and ρ , for all $j = 1, \dots, s - 1$ and $l \in \{0, \dots, L + 1\}$.

Thus one can reconstruct the first $s - 1$ rows of $\text{SIGN}_R(f_1, \dots, f_s)$ from w .

Case 2: $j = s$

For $l \in \{0, \dots, L + 1\}$ we have

- if $\rho(l) = k \Rightarrow \text{sign}(f_s(y_l)) = \text{sign}(g_{\theta(k)}(x_{i_k}))$,
- if $\rho(l) = (k, k + 1) \Rightarrow \text{sign}(f_s(y_l)) = 0$.

So, $\text{sign}(f_s(y_l))$ is known from w and ρ , for all $l \in \{0, \dots, L + 1\}$ and therefore can also be reconstructed from w .

Now remains the most delicate case that concerns $\text{sign}(f_s(]y_l, y_{l+1}[))$:

For $l \in \{0, \dots, L + 1\}$ we have

- if $l \neq 0, \rho(l) = k \Rightarrow$

$$\text{sign}(f_s(]y_l, y_{l+1}[)) = \begin{cases} \text{sign}(g_{\theta(k)}(x_{i_k})) & \text{if it is } \neq 0, \\ \text{sign}(f'_s(]x_{i_k}, x_{i_{k+1}}[)) & \text{otherwise.} \end{cases}$$

[This is because ($\rho(l) = k$ if $y_l = x_{i_k}$, so):

- if $g_{\theta(k)}(x_{i_k}) = f_s(x_{i_k}) \neq 0$, then by continuity sign is constant, and
- if $g_{\theta(k)}(x_{i_k}) = f_s(x_{i_k}) = 0$, then on $]x_{i_k}, x_{i_{k+1}}[$:

$$\begin{cases} f'_s \geq 0 \Rightarrow f_s(x_{i_k}) < f_s(y) \text{ for } y < x_{k+1}, \text{ so } f_s(y) > 0, \\ f'_s \leq 0 \Rightarrow -f_s(x_{i_k}) < -f_s(y) \text{ for } y < x_{k+1}, \text{ so } f_s(y) < 0 \end{cases}$$

(using lemma (Poizat): In a real closed ordered field, if P is a nonconstant polynomial s.t. $P' \geq 0$ on $[a, b]$, $a < b$, then $P(a) < P(b)$.)]

- if $l \neq 0, \rho(l) = (k, k + 1) \Rightarrow \text{sign}(f_s(]y_l, y_{l+1}[)) = \text{sign}(f'_s(]x_{i_k}, x_{i_{k+1}}[))$.

[We argue as follows (noting that $\rho(l) = (k, k + 1)$ if $y_l \in]x_{i_k}, x_{i_{k+1}}[$):

$\text{sign}(f_s(]y_l, y_{l+1}[))$ is constant so at any rate is equal to $\text{sign}(f_s(]y_l, x_{i_{k+1}}[))$, now using the fact that $f_s(y_l) = 0$ and the same lemma (stated above) we get, for any $a \in]y_l, x_{i_{k+1}}[$:

$$\begin{cases} f'_s \geq 0 \Rightarrow f_s(y_l) < f_s(a), \text{ so } f_s(a) > 0, \\ f'_s \leq 0 \Rightarrow -f_s(y_l) < -f_s(a), \text{ so } f_s(a) < 0 \end{cases}$$

i.e. f_s has same sign as f'_s .]

- if $l = 0 \Rightarrow \text{sign}(f_s(]-\infty, y_1[)) = \text{sign}(f'_s(]-\infty, x_1[))$ (as before). \square