AN ELEMENTARY PROOF OF HILBERT'S THEOREM ON TERNARY QUARTICS

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ABSTRACT. In 1888, Hilbert proved that every nonnegative quartic form f = f(x, y, z) with real coefficients is a sum of three squares of quadratic forms. His proof was ahead of its time and used advanced methods from topology and algebraic geometry. Up to now, no elementary proof is known. Here we present a completely new approach. Although our proof is not easy, it uses only elementary techniques. As a by-product, it gives information on the number of representations $f = p_1^2 + p_2^2 + p_3^2$ of f up to orthogonal equivalence. We show that this number is 8 for generically chosen f, and that it is 4 when f is chosen generically with a real zero. Although these facts were known, there was no elementary approach to them so far.

INTRODUCTION

In 1888, David Hilbert published an influential paper [3] which became fundamental for real algebraic geometry, and which remains an inspiring source for research even today. It addresses the problem whether a real form (homogeneous polynomial) $f(x_0, \ldots, x_n)$ which takes nonnegative values on all of \mathbb{R}^{n+1} is necessarily a sum of squares of real forms. Hilbert proves that the answer is negative in general. As is well-known, his results go much beyond this fact and contain a surprising positive aspect as well. Namely, for any pair (n, d) of integers with $n \ge 2$ and even $d \ge 4$, except for (n, d) =(2, 4), he shows that there exists a nonnegative form of degree d in n + 1variables which is not a sum of squares of polynomials. In the exceptional case, however, he proves that every nonnegative ternary quartic form is a sum of three squares of real quadratic forms.

It is the existence of a representation $f = p_1^2 + p_2^2 + p_3^2$ in this exceptional case that is the subject of the present article. Hilbert's original proof is brief and elegant, and it is ahead of its time in its topological arguments. For his contemporaries it must have been hard to grasp. Even today it is not easy to read, and it leaves a number of details to be filled in. Several authors have given fully detailed accounts of Hilbert's proof in recent years. We mention the approach due to Cassels, published in Rajwade's book ([8] chapter 7), and the two articles by Rudin [9] and Swan [11]. These approaches also show some characteristic differences.

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One of the first approaches to Hilbert's theorem along elementary and explicit lines was carried out by Powers and Reznick in [6], where complete answers were given in certain special cases. We would also like to point out the recent preprint [5] by Plaumann, Sturmfels and Vinzant which studies the computational side of Hilbert's theorem, and which contains a beautiful blend of the 19th century mathematics of ternary quartics.

So far, there seems to exist essentially only one proof different from Hilbert's. It comes out as a by-product of the quantitative analysis made in [7] and [10]. These papers had a different goal, namely to count the number of essentially distinct ways in which a positive semidefinite (or *psd*, for short) ternary quartic f can be written as a sum of three squares. The case where the plane projective curve f = 0 is non-singular is done in [7], the general irreducible case is in [10]. Both papers, and in particular the second, are using tools of modern algebraic geometry and can certainly not be called elementary.

We are convinced that Hilbert's original proof from [3] cannot claim an elementary character either. This can be seen from the following sketchy overview of its main steps:

- (1) The set of sums of three squares of quadratic forms is closed inside the space of all quartic forms. Therefore it suffices to prove the existence of a representation for all forms in some open dense subset of the psd forms, for example for all nonsingular such forms.
- (2) Hilbert proves that the map $(p_1, p_2, p_3) \mapsto \sum_{j=1}^3 p_j^2$ (from triples of real quadratic forms to quartic forms) is submersive (that is, its tangent maps are surjective), when restricted to the open set of triples for which the curve $\sum_j p_j^2 = 0$ is nonsingular. His elegant argument needs some non-trivial tool from algebraic geometry, like Max Noether's AF + BG theorem.
- (3) When the real form f is strictly positive definite and singular, the curve f = 0 has at least two different (complex conjugate) singular points.
- (4) The locus of quartic forms f for which the curve f = 0 has at least two different singularities has codimension ≥ 2 inside the space of all quartic forms.
- (5) Removing a subspace of codimension ≥ 2 from a connected topological space leaves the remaining space connected. Hence, by (3) and (4), the space of nonsingular positive forms is (path) connected.
- (6) There exist nonsingular positive forms which are sums of three squares, like $f^{(0)} = x^4 + y^4 + z^4$.
- (7) Given an arbitrary nonsingular positive form f there exists, by (5), a path $f^{(t)}$, $0 \le t \le 1$, joining $f^{(1)} = f$ to a sum of three squares $f^{(0)}$ such that $f^{(t)}$ is nonsingular and positive for every $0 \le t \le 1$.

(8) Using (1) and (2), and by the implicit function theorem, the representation (6) of $f^{(0)}$ can be extended continuously along the path $f^{(t)}$ to a representation of $f^{(1)} = f$ as a sum of three squares.

In view of (2), and certainly of (4) and (5), this proof does not have an elementary character. Also note that the existence of a path $f^{(t)}$ as in (7) is ensured only by the general topological fact (5). There is no concrete construction of such a path.

Our proof uses a variant of (1), plus applications of the implicit function theorem similar to (8). Otherwise it proceeds differently. In particular, we avoid the non-elementary steps (2), (4) and (5). Like Hilbert we are deforming representations along paths. Other than in Hilbert's proof, however, our paths are completely explicit, and are in fact simply straight line segments. Here is a road map:

- (a) By a limit argument (see 3.6), it suffices to prove the existence of a representation for generic psd f, i.e., for psd f satisfying a condition $\Psi(f) \neq 0$ where Ψ is a suitable nonzero polynomial in the coefficients of f.
- (b) When the form f has a non-trivial real zero, an elementary and constructive proof for the existence of a representation as a sum of three squares was given by the first author in [4]. We shall recall it in Sect. 2 below.
- (c) Assume that f has no non-trivial real zero. We find a psd form $f^{(0)}$ that has a non-trivial real zero such that the half-open interval $]f^{(0)}, f]$ (in the space of all quartic forms) consists of strictly positive forms.
- (d) Let $f^{(t)}$ $(0 \le t \le 1)$ denote the forms in the line segment constructed in (c), with $f^{(1)} = f$. Under generic assumptions on f we show that every representation of $f^{(0)}$ can be extended continuously to a representation of $f^{(t)}$ for $0 < t < \varepsilon$, with some $\varepsilon > 0$.
- (e) Under further generic assumptions on f we prove for every fixed $0 < t \leq 1$ that every representation of $f^{(t)}$ can be extended continuously and uniquely to a representation of $f^{(s)}$ for all s sufficiently close to t. Both in (d) and (e) we use the theorem on implicit functions.
- (f) Using the limit principle (a), it follows that $f = f^{(1)}$ has a representation as a sum of three squares.

All our "generic assumptions" on f are explicit. See 9.1 for the entire list and for a discussion of where they have been used. The exceptional cases that we have to exclude are given by the vanishing of invariants that are mostly discriminants or resultants of polynomials formed from (the coefficients of) f. Two of our invariants are of a more general nature, one of them having the amazing degree of 896 in the coefficients of f.

We believe that we have thus achieved a proof to Hilbert's theorem that only uses elementary tools. With only little extra effort, our arguments allow in fact to deduce substantial information on the number of essentially distinct representations, at least in generic cases. So far there has been no elementary approach to counting representations. Therefore we think it worthwile to include these parts.

Here is an overview of the structure of the paper. We start with the case where f has a real zero. By an explicit argument we show that f has a representation as a sum of three squares (Prop. 2.4). Refining the arguments vields the precise number of inequivalent representations, under suitable hypotheses of generic nature (Prop. 2.9). In Section 3 we turn to arbitrary psd quartic forms f. We show that f can be written as a sum of three squares, if and only if there exists a polynomial-valued rational point (with certain side conditions) on a certain elliptic curve associated with f (Prop. 3.3). No background or terminology on elliptic curves is used. Again we refine this by a result that permits to count representations (Prop. 3.8). Then we construct the linear path $f^{(t)}$ $(0 \le t \le 1)$ referred to in (d) above and study the extension of representations along this path. Extension around t = 0is studied in Section 4, around 0 < t < 1 in Sections 6 and 8. In between we insert two sections that provide the required background on symmetric functions. Section 5 has classical material on the discriminant. To handle the last case of the extension argument, we need an invariant $\Phi(f, g, h)$ of triples of polynomials which is less standard; it is introduced and discussed in Section 7. This invariant essentially decides if the pencil spanned by qand h contains a member that has a quadratic factor in common with f. We do not know whether this invariant has been considered before. Finally, in Section 9 we summarize our proof and give a systematic account of all the genericity conditions used. We also obtain the precise number of representations of f under (explicit) generic assumptions on f.

Basically, we consider techniques as "elementary" if they are accessible using undergraduate mathematics. The most advanced features that we use are the theorem on implicit functions and the theorem on symmetric functions. Only once (in the proof of Prop. 1.1(b)) are we using slightly more advanced algebraic techniques, namely basic facts about Dedekind domains. However, this part is only used for counting representations, and is not needed for the proof of Hilbert's theorem.

We believe that our approach to representations as sums of three squares is also "constructive", at least in a weak sense. It should be possible to follow our deformation argument for constructing such representations with arbitrary numeric precision, for example by using finite element methods.

1. The forms <1, q>

As usual, a polynomial $f(x_1, \ldots, x_n)$ with real coefficients is said to be *positive semidefinite* (or *psd* for short) if f takes nonnegative values on \mathbb{R}^n . It is said to be *positive definite* if f(x) > 0 for all $x \in \mathbb{R}^n$. When speaking of homogeneous polynomials (also called forms), one requires f(x) > 0 only for $x \neq (0, \ldots, 0)$, in order to call f positive definite.

We shall mostly be working with homogeneous polynomials, except when it becomes more convenient to dehomogenize. We start with univariate (inhomogeneous) real polynomials.

Proposition 1.1. Let $q \in \mathbb{R}[x]$ be a positive definite polynomial of degree two.

(a) Given any psd polynomial $f \in \mathbb{R}[x]$, there are polynomials $\xi, \eta \in \mathbb{R}[x]$ with

$$f = \eta^2 + q\xi^2. (1.1)$$

(b) Assume that $f \neq 0$ in (a) satisfies $\deg(f) = 2d$. Then the total number of solutions (ξ, η) to (1.1) is $\leq 2^{d+1}$, with equality if and only if $q \nmid f$ and f is square-free.

For the proof of Hilbert's theorem we only need part (a). The second statement will be used in our count of representations.

Proof. Clearly, q and f may be scaled by any positive real number. By changing the generator x of the polynomial ring if necessary, we may therefore assume $q = x^2 + 1$.

First assume that f is monic of degree 2, say $f = (x + a)^2 + b^2$ with real numbers a and b. Then ξ as in (1.1) has to be a constant, and we write $\xi^2 = \lambda$. Given $\lambda \in \mathbb{R}$, the polynomial

$$f - \lambda q = (1 - \lambda)x^2 + 2ax + (a^2 + b^2 - \lambda)$$

is a square if and only if either $\lambda = 1$, a = 0 and $b^2 \ge 1$, or else $\lambda < 1$ and

$$(1-\lambda)(a^2+b^2-\lambda) - a^2 = 0$$
 (1.2)

(vanishing of the discriminant of $f - \lambda q$). In any case, there is precisely one value of $\lambda \geq 0$ for which $f - \lambda q$ is a square: For a = 0, this is $\lambda = \min\{1, b^2\}$, while for $a \neq 0$ it is the unique $0 \leq \lambda < 1$ for which (1.2) vanishes. (Note that the left hand side of (1.2) is positive for $\lambda \gg 0$, is $b^2 \geq 0$ for $\lambda = 0$, and is $-a^2 < 0$ for $\lambda = 1$.) Hence $\xi^2 = \lambda$ and $\eta^2 = f - q\xi^2$ as in (1.2) exist and are unique. Note that there are exactly four possibilities for the pair (ξ, η) , except when f or fq is a square. (In these cases there exist precisely two possibilities, provided $f \neq 0$).

When f is an arbitrary psd polynomial, we can write f as a product of quadratic psd polynomials. Using the quadratic case just established, together with the multiplication formulæ

$$(a^{2} + b^{2}q)(c^{2} + d^{2}q) = (ac \pm bdq)^{2} + (ad \mp bc)^{2}q, \qquad (1.3)$$

we conclude that f has a representation (1.1). This proves (a).

For the proof of (b) we use some basic facts about prime ideal factorization in Dedekind domains. Let $L = \mathbb{R}(x, \sqrt{-q})$, a quadratic extension of the field $\mathbb{R}(x)$. The integral closure B of $\mathbb{R}[x]$ in L is a Dedekind domain. It consists of all elements in L whose norm and trace are in $\mathbb{R}[x]$, from which we see $B = \mathbb{R}[x, \sqrt{-q}]$. The behaviour of the primes in the extension $\mathbb{R}[x] \subset B$ is easy to see: The linear polynomials ℓ in $\mathbb{R}[x]$ are unramified in B and remain prime in B, having a quadratic extension of the residue field. The monic irreducible quadratic polynomials $p \neq q$ in $\mathbb{R}[x]$ are positive definite, hence they split into a product $p = p_1p_2$ of two primes in B not associated to each other, by (1.1), while the prime q of $\mathbb{R}[x]$ is ramified. Hence B is a principal ideal domain. Since $\eta^2 + q\xi^2 = (\eta + \xi\sqrt{-q})(\eta - \xi\sqrt{-q})$ is the norm of $\eta + \xi\sqrt{-q}$ in the extension $\mathbb{R}[x] \subset B$ (for $\xi, \eta \in \mathbb{R}[x]$), the number of representations (1.1) of f is equal to the number of elements in B of norm f.

The norms of the prime elements of B are $N(l) = l^2$, $N(p_1) = N(p_2) = p$ and $N(\sqrt{-q}) = q$. This shows that the number of elements in B of norm f is obtained as follows: Every factor p^m (for $p \neq q$ quadratic irreducible) contributes m + 1 solutions; multiply all these numbers, and multiply the result by 2. In other words, the precise number is (for $f \neq 0$)

$$2\prod_p (1+v_p(f)),$$

product over the monic irreducible polynomials $p \neq q$ of degree 2. From this the assertion in (b) is clear.

It would be possible to present the arguments for part (b) in a way that avoids using any theory of Dedekind rings. However we felt that trying this is not worth the effort.

Later it will be preferable for us to use Prop. 1.1 in a homogenized version. For convenience we state this version here:

Corollary 1.2. Let $q \in \mathbb{R}[x, y]$ be a positive definite quadratic form. Given any psd form $f \in \mathbb{R}[x, y]$ of degree 2d, there exist forms ξ , $\eta \in \mathbb{R}[x, y]$ with $\deg(\xi) = d - 1$, $\deg(\eta) = d$ and $f = \eta^2 + q\xi^2$. The number of such pairs (ξ, η) is $\leq 2^{d+1}$, with equality if and only if $q \nmid f$ and f is square-free. \Box

2. The case where f has a real zero

2.1. Let f = f(x, y, z) be a psd quartic form in $\mathbb{R}[x, y, z]$, and assume that f = 0 has a nontrivial real zero. Changing coordinates linearly we can assume f(0, 0, 1) = 0, hence

$$f = f_2(x, y) \cdot z^2 + f_3(x, y) \cdot z + f_4(x, y)$$
(2.1)

where $f_j = f_j(x, y)$ is a binary form of degree j (j = 2, 3, 4). That f is psd means that each of the three binary forms

$$f_2, f_4, 4f_2f_4 - f_3^2$$

is psd, that is, a sum of two squares. By an argument which is entirely elementary and explicit, we shall construct a representation of f as a sum of three squares (Proposition 2.4). For generically chosen f_2 , f_3 , f_4 , we shall in fact construct all such representations (Proposition 2.9). This second part is not needed for the proof of Hilbert's theorem.

2.2. Let us start by showing that f is a sum of three squares. If $f_2 = 0$ then also $f_3 = 0$, and hence $f = f_4$ is a psd binary form, therefore a sum of two squares. If $0 \neq f_2 = l^2$ is a square of a linear form, then $4l^2f_4 \geq f_3^2$ shows $l \mid f_3$, say $f_3 = 2lg_2$. Observe that $f_4 - g_2^2$ is a sum of two squares since $4l^2(f_4 - g_2^2) = 4f_2f_4 - f_3^2$ is a sum of two squares. Therefore $f = (lz + g_2)^2 + (f_4 - g_2^2)$ is a sum of three squares.

2.3. It remains to discuss the case where f_2 is strictly positive definite. From Cor. 1.2 we see that there exist binary forms $\xi = \xi(x, y)$ and $\eta = \eta(x, y)$ with $\deg(\xi) = 2$, $\deg(\eta) = 3$ and $\eta^2 + \xi^2 f_2 = 4f_2f_4 - f_3^2$, that is,

$$\eta^2 + f_3^2 = f_2(4f_4 - \xi^2). \tag{2.2}$$

On the other hand, since f_2 is psd, there are linear forms $l_1, l_2 \in \mathbb{R}[x, y]$ with $f_2 = l_1^2 + l_2^2 = (l_1 + il_2)(l_1 - il_2)$ $(i^2 = -1)$. By similarly factoring the left hand side of (2.2), it follows that $l_1 + il_2$ divides one of $\eta \pm if_3$. Replacing l_2 by $-l_2$ if necessary we can assume

$$(l_1 + il_2) \mid (\eta + if_3).$$

This implies that f_2 divides $(\eta + if_3)(l_1 - il_2) = (\eta l_1 + f_3 l_2) + i(f_3 l_1 - \eta l_2)$. Hence f_2 divides both real and imaginary part of the right hand form. So the fractions

$$h_1 := rac{f_3 l_1 - \eta l_2}{2f_2}, \qquad h_2 := rac{\eta l_1 + f_3 l_2}{2f_2}$$

are binary quadratic forms (with real coefficients), and (2.2) implies

$$h_1^2 + h_2^2 = \frac{(\eta^2 + f_3^2)(l_1^2 + l_2^2)}{4f_2^2} = \frac{\eta^2 + f_3^2}{4f_2} = f_4 - \frac{1}{4}\xi^2.$$

Moreover

$$h_1 l_1 + h_2 l_2 = \frac{f_3(l_1^2 + l_2^2)}{2f_2} = \frac{1}{2}f_3,$$

and so

$$f = \left(\frac{\xi}{2}\right)^2 + (h_1 + l_1 z)^2 + (h_2 + l_2 z)^2$$

is a sum of three squares of quadratic forms. We have thus proved:

Proposition 2.4. Let $f \in \mathbb{R}[x, y, z]$ be a psd quartic form which has a nontrivial real zero. Then f is a sum of three squares of quadratic forms in $\mathbb{R}[x, y, z]$.

Note that the proof was entirely explicit and constructive.

We now turn to the task of determining all representations of f, at least in the case when f_2 , f_3 , f_4 are chosen generically. For this, the following definition is useful.

Definition 2.5. Two representations

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$$f = \sum_{i=1}^{3} p_i^2 = \sum_{i=1}^{3} p_i'^2$$

with quadratic forms $p_i, p'_i \in \mathbb{R}[x, y, z]$ are said to be *(orthogonally) equivalent* if there exists an orthogonal matrix $S = (s_{ij}) \in \mathcal{O}_3(\mathbb{R})$ such that

$$p'_j = \sum_{i=1}^3 s_{ij} p_i \quad (j = 1, 2, 3).$$

2.6. Let $f = f_2 z^2 + f_3 z + f_4$ be a psd form as in (2.1). We assume that f_2 is not a square, hence is strictly positive definite. Assume

$$f = \sum_{i=1}^{3} (v_i z + w_i)^2 \tag{2.3}$$

where v_i resp. $w_i \in \mathbb{R}[x, y]$ are homogeneous of respective degrees 1 resp. 2 (i = 1, 2, 3). We first show how to associate with (2.3) a solution (ξ, η) of (2.2).

Consider the column vectors $v = (v_1, v_2, v_3)^t$ and $w = (w_1, w_2, w_3)^t$ with polynomial entries. Since the linear forms v_1, v_2, v_3 are linearly dependent, there is an orthogonal matrix $S \in \mathcal{O}_3(\mathbb{R})$ such that the first entry of the column Sv is zero. Replacing v resp. w by Sv resp. Sw yields an equivalent representation $f = \sum_{i=1}^3 (v'_i z + w'_i)^2$ in which $v'_1 = 0$. So up to replacing (2.3) by an equivalent representation we can assume $v_1 = 0$, and get accordingly

$$f_2 = v_2^2 + v_3^2$$
, $f_3 = 2(v_2w_2 + v_3w_3)$, $f_4 = w_1^2 + w_2^2 + w_3^2$.

Putting $\xi := 2w_1$ and $\eta := 2(v_2w_3 - v_3w_2)$ gives

$$\eta^{2} + f_{3}^{2} = 4(v_{2}w_{3} - v_{3}w_{2})^{2} + 4(v_{2}w_{2} + v_{3}w_{3})^{2}$$
$$= 4(v_{2}^{2} + v_{3}^{2})(w_{2}^{2} + w_{3}^{2})$$
$$= f_{2}(4f_{4} - \xi^{2})$$

so (ξ, η) solves (2.2).

Note that a different choice of S does not change ξ^2 and η^2 . Indeed, the first row of S is unique up to a factor ± 1 since v_1 , v_2 , v_3 span the space of linear forms in $\mathbb{R}[x, y]$. Therefore $\pm \xi$ does not change if S is chosen differently. The same argument shows that ξ^2 and η^2 depend only on the equivalence class of (2.3).

2.7. When f_2 is not a square, note that the number of solutions (ξ, η) of (2.2) was determined in Prop. 1.1(b). In particular, it was shown there that this number is ≤ 16 , and is equal to 16 if and only if $f_2 \nmid f_3$ and $4f_2f_4 - f_3^2$ is square-free. In this latter case, the pair (ξ^2, η^2) can therefore take precisely four different values.

2.8. Assume that f_2 is not a square, that $f_2 \nmid f_3$ and $4f_2f_4 - f_3^2$ is square-free. We show that inequivalent representations (2.3) give different solutions (ξ^2, η^2) to (2.2). Combined with 2.7, this will imply that f has precisely four different representations up to equivalence.

Let

$$f = w_1^2 + (v_2 z + w_2)^2 + (v_3 z + w_3)^2$$

= $w_1'^2 + (v_2' z + w_2')^2 + (v_3' z + w_3')^2$

be two representations with the same invariants ξ^2 , that is, with $w_1^2 = w_1'^2 = \frac{\xi^2}{4}$. Then $v_2w_3 - v_3w_2 = \pm (v_2'w_3' - v_3'w_2')$, and we can assume

$$v_2w_3 - v_3w_2 = v_2'w_3' - v_3'w_2'$$

by multiplying $v_2 z + w_2$ with -1 if necessary. Writing $v = v_2 + iv_3$, $w = w_2 + iw_3$ and $v' = v'_2 + iv'_3$, $w' = w'_2 + iw'_3$ this means $\Im(\overline{v}w) = \Im(\overline{v}'w')$. On the other hand we have

$$v\overline{v} = v'\overline{v}' = f_2, \quad \Re(\overline{v}w) = \Re(\overline{v}'w') = \frac{1}{2}f_3, \quad 4w\overline{w} = 4w'\overline{w}' = 4f_4 - \xi^2,$$

and we conclude

$$\overline{v}w = \overline{v}'w'. \tag{2.4}$$

Now \overline{v} does not divide w', because otherwise $v\overline{v} = f_2$ would divide $4w'\overline{w'} = 4f_4 - \xi^2$, and hence we would have

$$f_2^2 \mid (\eta^2 + f_3^2) = (\eta + if_3)(\eta - if_3),$$

whence $f_2 | f_3$, which was excluded. Comparing the two products (2.4) we see that there exist $\lambda, \mu \in \mathbb{C}$ with $v' = \lambda v$ and $w' = \mu w$, and clearly we must have $|\lambda| = |\mu| = 1$. Therefore (2.4) shows $\lambda = \mu$. This means that the two representations we started with are equivalent.

We summarize these discussions:

Proposition 2.9. Let $f = f_2 z^2 + f_3 z + f_4$ be psd (with $f_i \in \mathbb{R}[x, y]$ homogeneous of degree *i*, for i = 2, 3, 4), and assume that f_2 is not a square.

(a) Associated with each representation of f as a sum of three squares is a well-defined solution of

$$\eta^2 + f_3^2 = f_2(4f_4 - \xi^2)$$

such that ξ^2 and η^2 depend only on the orthogonal equivalence class of the representation.

(b) If $f_2 \nmid f_3$ and $4f_2f_4 - f_3^2$ is square-free, then any two representations of f with the same invariants ξ^2 , η^2 are equivalent. There exist precisely four different equivalence classes of representations of f.

Remark 2.10. Let $f = f_2 z^2 + f_3 z + f_4$ be psd, as in Proposition 2.9. The real zero (0,0,1) is a singularity of the projective curve f = 0. That f_2 is not a square means that this singularity is a node (with two complex conjugate tangents). When $f_2 \nmid f_3$ and $4f_2f_4 - f_3^2$ is square-free, one can show that (0,0,1) is the only singularity of the curve (the converse is not true). The fact that f has precisely four inequivalent representations is in agreement with the results of [10].

3. The case where f has no real zero

The following normalization lemma was proved in [4]:

Lemma 3.1. Let f = f(x, y, z) be a strictly positive definite form of degree four in $\mathbb{R}[x, y, z]$. Then, by a linear change of coordinates, f can be brought into the form

$$f = z^4 + f_2 z^2 + f_3 z + f_4 aga{3.1}$$

in which $f_j \in \mathbb{R}[x, y]$ is a form of degree j (j = 2, 3, 4), and such that the form $f - z^4$ is psd.

Proof. Let c > 0 be the minimum value taken by f on the unit sphere S^2 in \mathbb{R}^3 . Scaling f with a positive factor we may assume c = 1, and after an orthogonal coordinate change we get c = 1 = f(0, 0, 1). The form $\tilde{f} := f - (x^2 + y^2 + z^2)^2$ is nonnegative on \mathbb{R}^3 and vanishes at (0, 0, 1). Therefore \tilde{f} does not contain the term z^4 , in fact $\deg_z(\tilde{f}) \leq 2$. This means that f has the shape (3.1). The last assertion follows from $f - z^4 = \tilde{f} + (x^2 + y^2 + z^2)^2 - z^4 \geq \tilde{f} \geq 0$.

Remarks 3.2. 1. The form $f - z^4$ is psd and vanishes in (0, 0, 1), so the results of Sect. 2 apply to $f - z^4$. In particular, we can explicitly construct a representation of $f - z^4$ as a sum of three squares.

2. The minimum value of f on the unit sphere can be found by inspecting the solutions of the equation $\nabla f(x, y, z) = \lambda \cdot (x, y, z)$ with $\lambda \in \mathbb{R}$.

For f as in (3.1) we now study the question when f is a sum of three squares.

Proposition 3.3 ([4] Prop. 3.1). Let $f = z^4 + f_2 z^2 + f_3 z + f_4$ where $f_j \in \mathbb{R}[x, y]$ is a form of degree j (j = 2, 3, 4). Then f is a sum of three squares if, and only if, there exist binary forms ξ , $\eta \in \mathbb{R}[x, y]$ with $\deg(\xi) = 2$, $\deg(\eta) = 3$ and

$$\eta^2 + f_3^2 = (f_2 - \xi)(4f_4 - \xi^2), \qquad (3.2)$$

such that

$$f_2 - \xi \ge 0, \quad 4f_4 - \xi^2 \ge 0.$$
 (3.3)

Remark 3.4. If one of $f_2 - \xi$ and $4f_4 - \xi^2$ is psd, then so is the other by (3.2), except possibly in the case where $f_2 - \xi$ resp. $4f_4 - \xi^2$ was zero. The latter can happen only if $f_3 = 0$ and $\eta = 0$. Note that the psd conditions in (3.3) mean that the two forms are sums of two squares of linear resp. quadratic forms.

Proof of 3.3. First assume $f = \sum_{i=1}^{3} (u_i z^2 + v_i z + w_i)^2$, where $u_i, v_i, w_i \in \mathbb{R}[x, y]$ are forms of respective degrees 0, 1, 2 $(1 \leq i \leq 3)$. The vector $(u_1, u_2, u_3) \in \mathbb{R}^3$ has unit length, so by changing with an orthogonal real 3×3 matrix we can get $u_1 = 1$ and $u_2 = u_3 = 0$. This implies $v_1 = 0$,

 $v_2^2 + v_3^2 = f_2 - 2w_1$, $2(v_2w_2 + v_3w_3) = f_3$ and $w_2^2 + w_3^2 = f_4 - w_1^2$. One checks that (3.2) and (3.3) are satisfied with

$$\xi = 2w_1, \quad \eta = 2(v_2w_3 - v_3w_2)$$

Conversely assume that ξ , η satisfy (3.2) and (3.3). If $\xi = f_2$, then $f_3 = 0$, and by (3.3) there are quadratic forms $w_2, w_3 \in \mathbb{R}[x, y]$ with $f_4 - \frac{1}{4}f_2^2 = w_2^2 + w_3^2$, so

$$f = z^4 + f_2 z^2 + f_4 = \left(z^2 + \frac{f_2}{2}\right)^2 + w_2^2 + w_3^2.$$

Now assume $\xi \neq f_2$. By (3.3) there are linear forms $v_2, v_3 \in \mathbb{R}[x, y]$ with $f_2 - \xi = v_2^2 + v_3^2 = (v_2 + iv_3)(v_2 - iv_3)$ (where $i^2 = -1$). From (3.2) we see that the linear form $v_2 + iv_3$ divides one of the two forms $\eta \pm if_3$ (in $\mathbb{C}[x, y]$). Replacing v_3 with $-v_3$ if necessary we can assume $(v_2 + iv_3) \mid (\eta + if_3)$. This implies that $f_2 - \xi$ divides

$$(\eta + if_3)(v_2 - iv_3) = (f_3v_3 + \eta v_2) + i(f_3v_2 - \eta v_3).$$

Therefore,

$$\left(z^2 + \frac{\xi}{2}\right)^2 + \left(v_2 z + \frac{f_3 v_2 - \eta v_3}{2(f_2 - \xi)}\right)^2 + \left(v_3 z + \frac{f_3 v_3 + \eta v_2}{2(f_2 - \xi)}\right)^2$$

is a sum of three squares in $\mathbb{R}[x, y, z]$. A comparison of the coefficients shows that this sum is equal to f.

Remark 3.5. Consider $f = z^4 + f_2 z^2 + f_3 z + f_4$ as a monic polynomial in z, with coefficients $f_j \in \mathbb{R}[x, y]$ as in Prop. 3.3. Equation (3.2) says $\eta^2 = r_f(\xi)$ where

$$r_f(z) = (f_2 - z)(4f_4 - z^2) - f_3^2$$

is the cubic resolvent of f with respect to z (see 5.2 below).

The following lemma follows from the fact that the sum of squares map $(p_1, p_2, p_3) \mapsto \sum_j p_j^2$ is topologically proper (see (1) of the introduction). Avoiding this argument we give a direct proof based on Prop. 3.3:

Lemma 3.6. Let $f^{(1)}$, $f^{(2)}$, ... be a sequence of quartic forms as in 3.3 which converges coefficient-wise to a form f. If every $f^{(j)}$ is a sum of three squares, then the same is true for f.

Proof. For every index j there exist forms $\xi^{(j)}, \eta^{(j)} \in \mathbb{R}[x, y]$ satisfying the conditions of Prop. 3.3. From the inequality $(\xi^{(j)})^2 \leq 4f_4$ it follows that the sequence $\xi^{(j)}$ is bounded, and so the sequence $\eta^{(j)}$ is bounded as well. Hence there exists a limit point (ξ, η) of the sequence $(\xi^{(j)}, \eta^{(j)})$, and (ξ, η) satisfies the conditions of 3.3 for the form f.

The rest of this section is not needed for our proof of Hilbert's theorem. Similar as in the case where f has a real zero (Section 2), we try to find all representations of f as a sum of three squares. **Lemma 3.7.** Let f be as in Prop. 3.3. The construction in the proof of Prop. 3.3 associates with every representation

$$f = p_1^2 + p_2^2 + p_3^2 (3.4)$$

a pair (ξ, η) which solves (3.2) and (3.3). The form ξ is independent from the choices. In fact it depends only on the orthogonal equivalence class of the representation (3.4).

Proof. Consider the representation (3.4), and write

$$p_i = u_i z^2 + v_i z + w_i$$
 $(i = 1, 2, 3)$

where $u_i, v_i, w_i \in \mathbb{R}[x, y]$ are homogeneous of respective degrees 0, 1 and 2. Writing $u = (u_1, u_2, u_3)^t$, $v = (v_1, v_2, v_3)^t$, $w = (w_1, w_2, w_3)^t$, we choose $S \in$ $\mathcal{O}_3(\mathbb{R})$ with $Su = (1, 0, 0)^t$ as in the proof of Prop. 3.3. If $Sv = (v'_1, v'_2, v'_3)^t$ and $Sw = (w'_1, w'_2, w'_3)^t$, we have shown that

$$\xi = 2w_1', \quad \eta = 2(v_2'w_3' - v_3'w_2')$$

solve (3.2) and (3.3). If T is another orthogonal matrix with $Tu = (1, 0, 0)^t$, then T = US where U is orthogonal with first column and row (1, 0, 0). This shows that using T instead of S does not change ξ . The same argument shows that ξ depends only on the orthogonal equivalence class of (3.4).

Proposition 3.8. Let $f = z^4 + f_2 z^2 + f_3 z + f_4$ with $f_{j} \in \mathbb{R}[x, y]$ homogeneous of degree j (j = 2, 3, 4), and assume $gcd(f_3, 4f_4 - f_2^2) = 1$. Let

$$f = \sum_{i=1}^{3} p_i^2 = \sum_{i=1}^{3} p_i'^2$$

be two representations of f with associated invariants ξ and ξ' (see Lemma 3.7). If $\xi = \xi'$, the two representations are orthogonally equivalent.

Proof. Assuming $f_2 - \xi \neq 0$, we first show that $f_2 - \xi$ does not divide $4f_4 - \xi^2$. From

$$(f_2 - \xi)(4f_4 - \xi^2) = \eta^2 + f_3^2 = (\eta + if_3)(\eta - if_3)$$

we see that $(f_2 - \xi) \mid (4f_4 - \xi^2)$ would imply $(f_2 - \xi) \mid f_3$. On the other hand,

it would imply $(f_2 - \xi) | (4f_4 - f_2^2)$, thus contradicting the assumption. Write $p_i = u_i z^2 + v_i z + w_i$ and $p'_i = u'_i z^2 + v'_i z + w'_i$ (i = 1, 2, 3) as in the proof of Lemma 3.7. We can assume $u_1 = u'_1 = 1$ and $u_i = u'_i = 0$ for i = 2, 3. By hypothesis we have $w_1 = w'_1 = \frac{\xi}{2}$ and $v_2w_3 - v_3w_2 = \pm (v'_2w'_3 - v'_3w'_2);$ replacing p_3 with $-p_3$ if necessary we can assume

$$v_2w_3 - v_3w_2 = v'_2w'_3 - v'_3w'_2 = \frac{\eta}{2}.$$
 (3.5)

Since the coefficient of z^3 vanishes in f we have $v_1 = v'_1 = 0$, and so $p_1 =$ $p'_1 = z^2 + \frac{\xi}{2}$. Write $v := v_2 + iv_3$, $w := w_2 + iw_3$ and similarly $v' := v'_2 + iv'_3$, $w' := w'_2 + iw'_3$. Then (3.5) says $\Im(\overline{v}w) = \Im(\overline{v}'w') = \frac{1}{2}\eta$. A comparison of the other coefficients gives $v\overline{v} = v'\overline{v}' = f_2 - \xi$, $\Re(\overline{v}w) = \Re(\overline{v}'w') = \frac{1}{2}f_3$ and $4w\overline{w} = 4w'\overline{w}' = 4f_4 - \xi^2$. In particular, $\overline{v}w = \overline{v}'w' = \frac{1}{2}(f_3 + i\eta)$.

We clearly have $v = 0 \Leftrightarrow v' = 0$, and similarly $w = 0 \Leftrightarrow w' = 0$. In either of these cases, it is clear that the two representations are equivalent. Hence we can assume $v, w \neq 0$. Now \overline{v} does not divide w', because otherwise $v\overline{v} \mid w'\overline{w}'$, i.e., $(f_2 - \xi) \mid (4f_4 - \xi^2)$, which was ruled out at the beginning. So we conclude that there exist $\lambda, \mu \in \mathbb{C}$ with $|\lambda| = |\mu| = 1$ and $v' = \lambda v$, $w' = \mu w$. Then $\overline{v}w = \overline{v}'w'$ implies $\lambda = \mu$. Hence the two representations are orthogonally equivalent.

Corollary 3.9. If $gcd(f_3, 4f_4 - f_2^2) = 1$ the number of inequivalent representations of f equals the number of forms ξ solving (3.2) and (3.3) with suitable η .

4. Deforming the quartic, I

4.1. Let f = f(x, y, z) be a nonzero psd quartic form with real coefficients. We are trying to show that f is a sum of three squares. The case where f has a nontrivial real zero has already been solved completely. From now on we assume that f is strictly positive definite. We shall use a deformation to a suitable psd form with real zero to arrive at the desired conclusion, at least in a generic case.

As in Lemma 3.1 we use scaling by a positive number and an orthogonal coordinate change to bring f into the form

$$f = z^{4} + f_{2}(x,y)z^{2} + f_{3}(x,y)z + f_{4}(x,y)$$
(4.1)

with $\deg(f_i) = j$ (j = 2, 3, 4), such that the form

$$f - z^4 = f_2(x, y)z^2 + f_3(x, y)z + f_4(x, y)$$

is psd. The latter means that each of the binary forms f_2 , f_4 and $4f_2f_4 - f_3^2$ is psd.

4.2. Let t be a real parameter. Fixing f as in 4.1, we consider the family of quartic forms

$$f^{(t)} := t^2 f + (1 - t^2)(f - z^4)$$

= $t^2 z^4 + f_2(x, y) z^2 + f_3(x, y) z + f_4(x, y)$ (4.2)

 $(t \in \mathbb{R})$. For $0 < |t| \le 1$, the form $f^{(t)}$ is strictly positive definite, while $f^{(0)} = f - z^4$ has a zero at (0, 0, 1). When t runs from 0 to 1, the form $f^{(t)}$ covers the line segment between $f - z^4$ and f (inside the space of all real quartic forms). Note however that the time parameter is quadratic, not linear.

4.3. Let $0 \neq t \in \mathbb{R}$. By Prop. 3.3, $f^{(t)}$ is a sum of three squares if and only if there are forms $\tilde{\xi}$, $\tilde{\eta} \in \mathbb{R}[x, y]$ with $\tilde{\eta}^2 + t^{-4}f_3^2 = (t^{-2}f_2 - \tilde{\xi})(4t^{-2}f_4 - \tilde{\xi}^2)$, with both factors on the right psd. Multiplying with t^4 and substituting $\xi = t\tilde{\xi}$, $\eta = t^2\tilde{\eta}$, we see that this happens if and only if there are forms ξ , η in $\mathbb{R}[x, y]$ (of degrees 2 resp. 3) such that

$$\eta^2 + f_3^2 = (f_2 - t\xi)(4f_4 - \xi^2), \qquad (4.3)$$

$$f_2 - t\xi \ge 0, \quad 4f_4 - \xi^2 \ge 0.$$
 (4.4)

On the other hand, conditions (4.3), (4.4) have a solution (ξ_0, η_0) for t = 0, provided that f_2 is not a square, since $4f_2f_4 - f_3^2$ is then represented by $\langle 1, f_2 \rangle$ (Cor. 1.2, see also (2.2) above). The condition $4f_4 - \xi_0^2 \geq 0$ is automatic since $f_2 \geq 0$ and $f_2 \neq 0$. Keeping the assumption that f_2 is not a square, let us fix such forms ξ_0, η_0 with deg $(\xi_0) = 2$, deg $(\eta_0) = 3$ and

$$\eta_0^2 + f_2 \xi_0^2 = 4f_2 f_4 - f_3^2. \tag{4.5}$$

Proposition 4.4. In addition to the assumptions in 4.1, assume that f_2 is not a square, that $f_2 \nmid f_3$ and that $4f_2f_4 - f_3^2$ is square-free. Then there exist continuous families $(\xi^{(t)}), (\eta^{(t)}) (|t| < \varepsilon, \text{ for some } \varepsilon > 0)$ of forms such that $(\xi^{(0)}, \eta^{(0)}) = (\xi_0, \eta_0)$, and such that $(\xi^{(t)}, \eta^{(t)})$ solves (4.3), (4.4) for all $|t| < \varepsilon$.

For the proof we need the following simple lemma:

Lemma 4.5. Let k be a field, let f, $g \in k[t]$ be polynomials with $\deg(f) = m$, $\deg(g) = n$ and $m, n \ge 1$. The linear map

$$k[t]_{m-1} \oplus k[t]_{n-1} \to k[t]_{m+n-1}, \quad (p,q) \mapsto pg + qf$$

is bijective if and only if f and g are relatively prime. (Here $k[t]_d$ denotes the space of polynomials of degree $\leq d$.)

Proof. Both the source and the target vector space have the same dimension m + n. If f and g are relatively prime, then pg + qf = 0 implies $f \mid p$ and $g \mid q$, whence p = q = 0 by degree reasons. The reverse implication is obvious.

Note that if one uses the canonical linear bases to describe the map in 4.5 by a matrix, and takes its determinant, one obtains the resultant of f and g.

Proof of Prop. 4.4. We first exploit the assumption. The forms ξ_0 and η_0 are relatively prime since the square of any common divisor divides $4f_2f_4 - f_3^2$ by (4.5). Also, the irreducible form f_2 does not divide η_0 , since otherwise (4.5) would imply $f_2 \mid f_3$. We conclude that $f_2\xi_0$ and η_0 are relatively prime.

Let $V_d \subset \mathbb{R}[x, y]$ denote the space of binary forms of degree d, and consider the map

$$F: V_2 \times V_3 \times \mathbb{R} \to V_6, \quad (\xi, \eta, t) \mapsto \eta^2 + f_3^2 - (f_2 - t\xi)(4f_4 - \xi^2).$$

The partial derivative of F at $(\xi_0, \eta_0, 0)$ with respect to (ξ, η) is the linear map

 $V_2 \oplus V_3 \to V_6, \quad (\xi,\eta) \mapsto 2(\eta_0\eta - f_2\xi_0\xi).$

By Lemma 4.5, this map is bijective.

The theorem on implicit functions gives us therefore the existence of continuous families $(\xi^{(t)})$, $(\eta^{(t)})$, for $|t| < \varepsilon'$ and some $\varepsilon' > 0$, with $(\xi^{(0)}, \eta^{(0)}) =$ (ξ_0, η_0) and with $F(\xi^{(t)}, \eta^{(t)}, t) = 0$ (that is, (4.3)) for $|t| < \varepsilon'$. As for conditions (4.4), it suffices to verify the first of them since $f_3 \neq 0$. For t = 0, $f_2 - t\xi^{(t)} = f_2$ is strictly positive definite by assumption. Hence there is some $\varepsilon'' > 0$ such that $f_2 - t\xi^{(t)} \ge 0$ for all $|t| < \varepsilon''$, and we can take $\varepsilon = \min\{\varepsilon', \varepsilon''\}$.

Using Prop. 3.3, we conclude from Prop. 4.4:

Corollary 4.6. Assume that $f = z^4 + f_2 z^2 + f_3 z + f_4$ (with $f_j \in \mathbb{R}[x, y]$ and $\deg(f_j) = j$) is strictly positive definite and satisfies $f - z^4 \ge 0$. If f_2 is not a square, $f_2 \nmid f_3$ and $4f_2f_4 - f_3^2$ is square-free, then there exists $\varepsilon > 0$ such that $f^{(t)}$ is a sum of three squares for all $0 \le |t| < \varepsilon$.

Remarks 4.7. 1. It can be shown that a representation of $f^{(t)}$ as a sum of three squares can be chosen for every $|t| < \varepsilon$ such that the polynomials in this representation depend continuously on t, starting at t = 0 with an arbitrary representation of $f^{(0)} = f - z^4$.

2. Since the map F in the proof of 4.4 is polynomial, a suitable version of the implicit function theorem (see [2] 10.2.4, for example) shows that the families $(\xi^{(t)}), (\eta^{(t)})$ are not just continuous but even analytic.

5. The discriminant

Before proceeding to extend representations of $f^{(t)}$ over the entire interval $0 \le t \le 1$, we need to discuss the discriminant of $f^{(t)}$.

5.1. Here are some reminders about the classical discriminant. Let K be a field, let

$$f = a_0 z^n + a_1 z^{n-1} + \dots + a_n \in K[z]$$

with $a_0 \neq 0$. The discriminant of f is defined as

$$\operatorname{disc}(f) = \operatorname{disc}_n(f) = a_0^{2n-2} \prod_{i < j} (\alpha_i - \alpha_j)^2$$

if $\alpha_1, \ldots, \alpha_n$ are the roots of f in an algebraic closure of K. More precisely, this is the *n*-discriminant of f; if deg(f) = m < n - 1 then disc_n(f) = 0, while in general disc_m $(f) \neq 0$. If deg(f) = n then it follows directly from the definition that disc_n(f) = 0 if and only if f has a multiple root.

Using the theorem on symmetric functions one sees that $\operatorname{disc}_n(f)$ is an integral polynomial in the coefficients a_0, \ldots, a_n of f. Moreover, there exist universal polynomials $p, q \in \mathbb{Z}[a_0, \ldots, a_n, z]$ such that

$$\operatorname{disc}_n(f) = pf + qf$$

where f' is the derivative of f. One finds p and q by writing f with indeterminate coefficients and performing the Euclidean algorithm on f and f'.

Directly from the definition one sees that the polynomial $f(\lambda z)$ has discriminant

$$\operatorname{disc}_{n} f(\lambda z) = \lambda^{n(n-1)} \operatorname{disc}_{n} f(z), \qquad (5.1)$$

if $\lambda \in K$ is a parameter.

In the remainder of this section the degree n is always clear from the context, and we omit the index n of the discriminant.

5.2. Given a quartic polynomial

 $f(z) = a_0 z^4 + a_1 z^3 + a_2 z^2 + a_3 z + a_4,$

the cubic resolvent $r_f(z)$ of f(z) is defined to be the cubic polynomial

$$r_f(z) = a_0^3 z^3 - a_0^2 a_2 z^2 + a_0 (a_1 a_3 - 4a_0 a_4) z + (4a_0 a_2 a_4 - a_0 a_3^2 - a_1^2 a_4).$$

If $a_0 \neq 0$ and $\alpha_1, \ldots, \alpha_4$ are the roots of f(z) in an algebraic closure of K, a calculation with symmetric polynomials shows that $r_f(z)$ has the roots

$$\beta_1 = \alpha_1 \alpha_2 + \alpha_3 \alpha_4, \quad \beta_2 = \alpha_1 \alpha_3 + \alpha_2 \alpha_4, \quad \beta_3 = \alpha_1 \alpha_4 + \alpha_2 \alpha_3.$$

We will only use the case where the cubic coefficient a_1 of f vanishes, in which

disc $(f) = a_0 \left(-4a_2^3 a_3^2 - 27a_0 a_3^4 + 16a_2^4 a_4 - 128a_0 a_2^2 a_4^2 + 144a_0 a_2 a_3^2 a_4 + 256a_0^2 a_4^3 \right)$ and

$$r_f(z) = a_0 \Big((a_0 z - a_2)(a_0 z^2 - 4a_4) - a_3^2 \Big).$$

Lemma 5.3. Let $f = a_0 z^4 + a_1 z^3 + a_2 z^2 + a_3 z + a_4$. Then disc $r_f(z) = a_0^6$ disc f(z).

Proof. If β_1 , β_2 , β_3 are the roots of r_f as in 5.2, then

$$\beta_1 - \beta_2 = (\alpha_1 - \alpha_4)(\alpha_2 - \alpha_3), \beta_1 - \beta_3 = (\alpha_1 - \alpha_3)(\alpha_2 - \alpha_4), \beta_2 - \beta_3 = (\alpha_1 - \alpha_2)(\alpha_3 - \alpha_4),$$

from which one immediately sees

$$\operatorname{disc}(r_f) = a_0^{12} \prod_{1 \le k < l \le 3} (\beta_k - \beta_l)^2 = a_0^{12} \prod_{1 \le i < j \le 4} (\alpha_i - \alpha_j)^2 = a_0^6 \operatorname{disc}(f).$$

Remark 5.4. If $A = \mathbb{R}$, and if a quartic polynomial $f(z) = a_0 z^4 + a_2 z^2 + a_3 z + a_4 \in \mathbb{R}[z]$ with $a_0 \neq 0$ is known to be strictly positive definite, then f can have a multiple root only if f is a square. Therefore, $\operatorname{disc}(f) = 0$ is equivalent to $a_3 = a_2^2 - 4a_0a_4 = 0$ in this case.

5.5. Now let $t \neq 0$ be a real parameter. We consider

$$f^{(t)} = t^2 z^4 + f_2(x,y)z^2 + f_3(x,y)z + f_4(x,y)$$

as a quartic polynomial in the variable z over $\mathbb{R}[x, y]$ (see (4.2)). Let $r^{(t)}$ be the cubic resolvent of $f^{(t)}$ (with respect to z). We put

$$g_t(z) := \frac{1}{t^2} \cdot r^{(t)} \left(\frac{z}{t}\right) = (tz - f_2)(z^2 - 4f_4) - f_3^2,$$

and we define

$$D_t := \operatorname{disc} g_t(z) \in \mathbb{R}[x, y].$$

Using (5.1) and Lemma 5.3 we find

$$D_t = \operatorname{disc} g_t(z) = t^{-2} \operatorname{disc} f^{(t)}(z).$$

Explicitly, this gives

$$D_t := -4f_2^3 f_3^2 - 27t^2 f_3^4 + 16f_2^4 f_4 - 128t^2 f_2^2 f_4^2 + 144t^2 f_2 f_3^2 f_4 + 256t^4 f_4^3$$

= $16f_4 (4t^2 f_4 - f_2^2)^2 + 4f_2 f_3^2 (36t^2 f_4 - f_2^2) - 27t^2 f_3^4$

(a form of degree 12 in x and y). We further put

$$h_t(z) = \frac{\partial}{\partial z} g_t(z) = 3tz^2 - 2f_2z - 4tf_4$$
 (5.2)

and conclude:

Lemma 5.6. D_t lies in the ideal generated by g_t and h_t in $\mathbb{R}[x, y, z]$. \Box

6. Deforming the quartic, II: Case of a linear factor

6.1. For $t \in \mathbb{R}$ we continue to consider the form

$$f^{(t)} = t^2 z^4 + f_2(x, y) z^2 + f_3(x, y) z + f_4(x, y),$$

see (4.2). We know that $f^{(t)}$ is strictly positive definite for $0 < |t| \le 1$, and that $f^{(t)}$ is a sum of three squares for small |t| (Prop. 4.4).

Let $t_0 \neq 0$ be a fixed real number, and assume that the form $f^{(t_0)}$ is strictly positive definite and a sum of three squares. Under generic assumptions on f which do not depend on t_0 , we shall show that $f^{(t)}$ is a sum of three squares for all t sufficiently close to t_0 .

6.2. That $f^{(t_0)}$ is a sum of three squares means the following, by 4.3: There exist forms $\xi_0, \eta_0 \in \mathbb{R}[x, y]$ with $\deg(\xi_0) = 2, \deg(\eta_0) = 3$ such that

$$\eta_0^2 = (f_2 - t_0\xi_0)(4f_4 - \xi_0^2) - f_3^2 = g_{t_0}(\xi_0), \tag{6.1}$$

and

$$f_2 - t_0 \xi_0 \ge 0, \quad 4f_4 - \xi_0^2 \ge 0.$$
 (6.2)

For $d \ge 0$ we let again V_d denote the vector space of forms of degree d in $\mathbb{R}[x, y]$. As in the proof of Prop. 4.4 we consider the map $F: V_2 \times V_3 \times \mathbb{R} \to V_6$,

$$F(\xi,\eta,t) = \eta^2 + f_3^2 - (f_2 - t\xi)(4f_4 - \xi^2) = \eta^2 - g_t(\xi)$$

(see 5.5 for $g_t(\xi)$). The partial derivative of F in (ξ_0, η_0, t_0) with respect to (ξ, η) is the linear map

 $V_2 \oplus V_3 \to V_6$, $(\xi, \eta) \mapsto 2\eta_0 \cdot \eta - h_{t_0}(\xi_0) \cdot \xi$

where

$$h_{t_0}(\xi_0) = 3t_0\xi_0^2 - 2f_2\xi_0 - 4t_0f_4,$$

c. f. 5.5.

Proposition 6.3. Assume that the two forms $\eta_0 \in V_3$ and $h_{t_0}(\xi_0) \in V_4$ are relatively prime, and that $f_3 \neq 0$. Then there exist $\varepsilon > 0$ and solutions (ξ_t, η_t) to (4.3) and (4.4) for $|t - t_0| < \varepsilon$ such that $(\xi_{t_0}, \eta_{t_0}) = (\xi_0, \eta_0)$.

Proof. Indeed, by applying Lemma 4.5 as in the proof of Prop. 4.4, it follows from the theorem on implicit functions that there are (ξ_t, η_t) depending continuously (in fact analytically, see 4.7) on t and satisfying $(\xi_{t_0}, \eta_{t_0}) =$ (ξ_0, η_0) and $F(\xi_t, \eta_t, t) = 0$, for $|t - t_0| < \varepsilon'$ (with suitable $\varepsilon' > 0$). So equations (4.3) hold for $|t - t_0| < \varepsilon'$. We claim that conditions (4.4) hold as well for suitable $0 < \varepsilon \leq \varepsilon'$. Indeed, since $f_3 \neq 0$, this is clear if $f_2 - t_0\xi_0$ is strictly positive, see Remark 3.4. If $f_2 - t_0\xi_0$ is a square, it could a priori happen that the quadratic form $f_2 - t\xi_t$ is indefinite for t arbitrarily close to t_0 , say with real zeros $\alpha_t < \beta_t$. However, since $(f_2 - t\xi_t)(4f_4 - \xi_t^2) = f_3^2 + \eta_t^2$, this would imply that α_t and β_t are roots of f_3 for all these t, which is evidently impossible.

6.4. It remains to show, under suitable generic assumptions on f, that the following is true:

For every real number $t \neq 0$ such that $f^{(t)}$ is positive definite, and for every solution (ξ, η) of (4.3) and (4.4), the two forms η and $h_t(\xi)$ are relatively prime.

To analyze the problem, assume that η and $h_t(\xi)$ have a nontrivial common divisor p = p(x, y) in $\mathbb{R}[x, y]$. We can assume that p is irreducible, hence (homogeneous) of degree one or two. By (4.3), $\eta^2 = g_t(\xi)$, and so p divides $g_t(\xi)$ as well.

Below we will treat the case where p is linear. The quadratic case will be dealt with in Sect. 8.

6.5. So assume that $t \neq 0$ and $f^{(t)}$ is positive definite, and p is a linear common divisor of $g_t(\xi)$ and $h_t(\xi)$ in $\mathbb{R}[x, y]$. Let us denote equivalence in $\mathbb{R}[x, y]$ modulo the principal ideal (p) by \equiv . By Lemma 5.6, D_t lies in the ideal generated by $g_t(\xi)$ and $h_t(\xi)$. We conclude that $D_t \equiv 0$.

Since $f^{(t)}$ is strictly positive definite, and since disc $f^{(t)} = t^2 D_t$, Remark 5.4 implies $f_3 \equiv 4 t^2 f_4 - f_2^2 \equiv 0$. Since p^2 divides

$$g_t(\xi) = (f_2 - t\xi)(4f_4 - \xi^2) - f_3^2,$$

and since both factors $f_2 - t\xi$ and $4f_4 - \xi^2$ are psd, we conclude that p^2 divides $f_2 - t\xi$ or $4f_4 - \xi^2$. From $t^2(4f_4 - \xi^2) = (f_2^2 - t^2\xi^2) + (4t^2f_4 - f_2^2)$ we see that in fact p^2 divides $4f_4 - \xi^2$ unconditionally, and that p divides $f_2^2 - t^2\xi^2$. So we have

$$\eta \equiv f_3 \equiv f_2^2 - t^2 \xi^2 \equiv 0, \quad p^2 \mid (4f_4 - \xi^2).$$
(6.3)

From $f_2^2 - t^2 \xi^2 \equiv 0$ we see that one of the two conditions $f_2 \pm t\xi \equiv 0$ holds. When $f_2 - t\xi \equiv 0$, this implies $p^2 \mid (f_2 - t\xi)$ since $f_2 - t\xi$ is psd, and so the right hand side of

$$\eta^2 + f_3^2 = (f_2 - t\xi)(4f_4 - \xi^2)$$

is divisible by p^4 . This implies $p^2 | f_3$, and so f_3 is not square-free, which is a non-generic situation. When $f_2 + t\xi \equiv 0$, we combine this with $4f_4 \equiv \xi^2$ to get

$$0 \equiv h_t(\xi) = 3t\xi^2 - 2f_2\xi - 4tf_4 \equiv (3+2-1)t\xi^2 = 4t\xi^2.$$

This gives $\xi \equiv 0$, and hence $f_4 \equiv 0$, whence $(f_3, f_4) \neq 1$. Again this is a non-generic situation.

7. QUADRATIC COMMON DIVISORS IN PENCILS OF POLYNOMIALS

Proposition 7.1. Fix $m, n \ge 2$ and consider triples (f, g, h) of univariate polynomials with $\deg(f) \le m$ and $\deg(g)$, $\deg(h) \le n$. There exists a nonzero integral polynomial $\Psi_{m,n}(f, g, h)$ in the coefficients of f, g, h with the following property:

For any field k and any polynomials $f, g, h \in k[x]$ with $\deg(f) \leq m$ and $\deg(g), \deg(h) \leq n$, if there exists $(0,0) \neq (s,t) \in k^2$ with

$$\deg \gcd(f, sg + th) \ge 2$$

then $\Psi_{m,n}(f,g,h) = 0.$

Proof. Let k be algebraically closed and $f \in k[x]$. Assume deg(f) = m, let $\alpha_1, \ldots, \alpha_m$ be the roots of f, and assume that the α_i are pairwise distinct, i.e., that f is separable. Given g and h, there exists $(s,t) \neq (0,0)$ with deg gcd $(f, sg + th) \geq 2$ if and only if there exist $1 \leq i < j \leq m$ such that

$$sg(\alpha_i) + th(\alpha_i) = sg(\alpha_j) + th(\alpha_j) = 0$$

for some $(s,t) \neq (0,0)$, or equivalently, such that

$$g(\alpha_i)h(\alpha_j) = g(\alpha_j)h(\alpha_i)$$

So this holds if and only if

$$\tilde{\phi}(f,g,h) := \prod_{1 \le i < j \le m} \frac{g(\alpha_i)h(\alpha_j) - g(\alpha_j)h(\alpha_i)}{\alpha_i - \alpha_j}$$

vanishes. It is easy to see that ϕ is invariant under all permutations of the roots α_i . Hence when f is monic, $\tilde{\phi}$ is an integral polynomial in the coefficients of f, g and h. To cover the non-monic case as well, observe that $\tilde{\phi}$ has degree $\leq (m-1)(n-1)$ with respect to each α_i . Therefore, if a_0 denotes the leading coefficient of f, it follows that

$$\phi(f,g,h) := a_0^{(m-1)(n-1)} \cdot \prod_{1 \le i < j \le m} \frac{g(\alpha_i)h(\alpha_j) - g(\alpha_j)h(\alpha_i)}{\alpha_i - \alpha_j}$$

is an integral polynomial in the coefficients of f, g and h.

From $\phi(f, x, 1) = 1$ for monic f of degree m we see that ϕ does not vanish identically. To prove the proposition it suffices to put

$$\Psi_{m,n}(f,g,h) := \operatorname{disc}_m(f) \cdot \phi(f,g,h).$$

Definition 7.2. For polynomials $f, g, h \in k[x]$ with $\deg(f) \leq m$ and $\deg(g)$, $\deg(h) \leq n$, we define the Φ -invariant by

$$\Phi_{m,n}(f,g,h) := a_0^{(m-1)(n-1)} \cdot \prod_{1 \le i < j \le m} \frac{g(\alpha_i)h(\alpha_j) - g(\alpha_j)h(\alpha_i)}{\alpha_i - \alpha_j}$$

where $\alpha_1, \ldots, \alpha_m$ are the roots of f and a_0 is the coefficient of x^m in f. By the proof of Proposition 7.1, $\Phi_{m,n}(f,g,h)$ is an integral polynomial in the coefficients of f, g and h.

The proof of Proposition 7.1 has shown:

Corollary 7.3. In 7.1 we can take

$$\Psi_{m,n}(f,g,h) = \operatorname{disc}_m(f) \cdot \Phi_{m,n}(f,g,h).$$

If f is separable with $\deg(f) \ge m-1$, then $\Phi_{m,n}(f,g,h) = 0$ is equivalent to the existence of a pair $(0,0) \ne (s,t) \in \overline{k}^2$ with sg+th = 0 or $\deg \gcd(f,sg+th) \ge 2$.

Remarks 7.4. 1. The power of a_0 in the definition of $\Phi_{m,n}$ is the correct one, in the sense that $\Phi_{m,n}$ is not divisible by a_0 . Indeed, if $f = \sum_{i=0}^{m} a_i x^{m-i}$, and if one takes $g := x^{n-1}(b_0 x + b_1)$, $h := x^{n-1}(c_0 x + c_1)$, one finds

$$\Phi_{m,n}(f,g,h) = a_m^{(m-1)(n-1)} \cdot (b_0 c_1 - b_1 c_0)^{\binom{m}{2}}.$$

2. Write $f = \sum_{i=0}^{m} a_i x^{m-i}$, $g = \sum_{j=0}^{n} b_j x^{n-j}$ and $h = \sum_{j=0}^{n} c_j x^{n-j}$. As a polynomial in the a_i, b_j and $c_j, \Phi_{m,n}$ is homogeneous of degree (m-1)(n-1) in the a_i and of degree $\binom{m}{2}$ in the b_j and in the c_j . If we give degree i to a_i and degree j to b_j and c_j , then $\Phi_{m,n}$ is jointly homogeneous in all variables of degree $\binom{m}{2}(2n-1)$.

3. The Φ -invariant has some relations with resultants. For example, the rule

$$\Phi_{m,n+d}(f,pg,ph) = \operatorname{res}_{m,d}(f,p)^{m-1} \cdot \Phi_{m,n}(f,g,h)$$

holds, for $\deg(f) \le m$, $\deg(p) \le d$ and $\deg(g)$, $\deg(h) \le n$.

Example 7.5. Let a_i, b_j, c_j be the coefficients of f, g, h as before. In low degrees it is quite manageable to calculate Φ explicitly. For example we have

$$\Phi_{2,2}(f,g,h) = \det(f,g,h) = \begin{vmatrix} a_0 & b_0 & c_0 \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix}$$

or

$$\begin{split} \Phi_{2,3}(f,g,h) &= a_0^2 b_2 c_3 - a_0 a_2 b_2 c_1 + a_1 a_2 b_2 c_0 - a_0 a_1 b_1 c_3 + a_1^2 b_0 c_3 \\ &- a_0 a_2 b_0 c_3 + a_2^2 b_0 c_1 - a_0^2 b_3 c_2 + a_0 a_2 b_1 c_2 - a_1 a_2 b_0 c_2 \\ &+ a_0 a_1 b_3 c_1 - a_1^2 b_3 c_0 + a_0 a_2 b_3 c_0 - a_2^2 b_1 c_0. \end{split}$$

As the remarks on the degree of $\Phi_{m,n}$ show, the size of $\Phi_{m,n}$ grows quickly with m and n.

We do not know whether $\Phi_{m,n}(f,g,h)$ or some related invariant has been considered before.

As before we write

$$g_t(\xi) = t\xi^3 - f_2\xi^2 - 4tf_4\xi + f_6$$

where $f_6 := 4f_2f_4 - f_3^2$, and

$$h_t(\xi) = \frac{\partial}{\partial \xi} g_t(\xi) = 3t\xi^2 - 2f_2\xi - 4tf_4.$$

The hardest step in our proof is to show, for generically chosen f_i , that $g_t(\xi)$ and $h_t(\xi)$ have no common quadratic factor, whenever (ξ, η) is a solution of (4.3) and $t \neq 0$. This will be accomplished by the following result:

Proposition 8.1. Consider triples (f_2, f_3, f_4) of forms in $\mathbb{R}[x, y]$ (with $\deg(f_i) = i$ for i = 2, 3, 4) for which

$$\eta^2 = (f_2 - t\xi)(4f_4 - \xi^2) - f_3^2 = g_t(\xi)$$
(8.1)

has a solution (ξ, η) for some $0 \neq t \in \mathbb{R}$ such that $g_t(\xi)$ and $h_t(\xi)$ have a common irreducible quadratic factor. Then these triples are not Zariski dense.

In other words, there exists a nonzero polynomial $\Psi = \Psi(f_2, f_3, f_4)$ in the coefficients of f_2 , f_3 and f_4 which vanishes on the triples described in the proposition.

The plan of the proof is as follows. We will successively deduce six "exceptional" conditions on (f_2, f_3, f_4) , labelled $(S_1)-(S_6)$. We will show that, for generic choice of the f_i , none of these conditions holds. On the other hand, we'll show that the assumptions of 8.1 imply that at least one of $(S_1)-(S_6)$ is satisfied.

8.2. We dehomogenize all forms in $\mathbb{R}[x, y]$ by setting y = 1. So f_2 , f_3 , f_4 , ξ , η are polynomials in $\mathbb{R}[x]$ with deg $(f_i) \leq i$ (i = 2, 3, 4), deg $(\xi) \leq 2$ and deg $(\eta) \leq 3$. We assume that $t \neq 0$ is a real number and identity (8.1) holds, and that $p \in \mathbb{R}[x]$ is an irreducible quadratic polynomial with $p^2 \mid g_t(\xi)$ and $p \mid h_t(\xi)$. Denoting congruences modulo (p) in $\mathbb{R}[x]$ by \equiv , we therefore have

$$t\xi^3 - f_2\xi^2 - 4tf_4\xi + f_6 = (f_2 - t\xi)(4f_4 - \xi^2) - f_3^2 \equiv 0$$
 (8.2)

and

$$3t\xi^2 - 2f_2\xi - 4tf_4 \equiv 0. \tag{8.3}$$

Combining (8.2) and (8.3) we get

$$f_2\xi^2 + 8tf_4\xi - 3f_6 \equiv 0, \qquad (8.4)$$

and eliminating t from (8.3) and (8.4) we find

$$f_2\xi^4 - (8f_2f_4 - 3f_3^2)\xi^2 + 4f_4f_6 \equiv 0.$$
(8.5)

8.3. We use ' to denote the derivative $\frac{d}{dx}$ on polynomials in $\mathbb{R}[x]$. From $p^2 \mid g_t(\xi)$ we see that p divides $g_t(\xi)' = h_t(\xi)\xi' - (f'_2\xi^2 + 4tf'_4\xi - f'_6)$, and hence

$$f_2'\xi^2 + 4tf_4'\xi - f_6' \equiv 0.$$
(8.6)

From $h_t(\xi) \equiv 0$ and (8.6) we can again eliminate t and get

$$3f_2'\xi^4 + (8f_2f_4' - 4f_2'f_4 - 3f_6')\xi^2 + 4f_4f_6' \equiv 0.$$
(8.7)

8.4. For $i, j \in \{2, 3, 4\}$ we put

$$g_{ij} := if_i f'_j - jf_j f'_i = f_i f_j \frac{d}{dx} \log(f^i_j f^{-j}_i).$$

Note that $\deg(g_{ij}) \leq i + j - 2$, with equality for generic choice of the f_i . We observe the relation

$$2f_2g_{34} - 3f_3g_{24} + 4f_4g_{23} = 0$$

8.5. We now eliminate ξ . From (8.5) and (8.7) we can eliminate ξ^4 and get

$$(2f_2g_{24} - 3f_3g_{23})\xi^2 - 4f_4(2f_2g_{24} - f_3g_{23}) \equiv 0.$$
(8.8)

We can eliminate t from (8.4) and (8.6), getting

$$g_{24}\xi^2 + 2(f_3g_{34} - 2f_4g_{24}) \equiv 0.$$
(8.9)

Finally we can eliminate ξ from (8.8) and (8.9), getting

$$f_3^2 \cdot \left(g_{23}g_{34} - g_{24}^2\right) \equiv 0. \tag{8.10}$$

8.6. We introduce the following "exceptional" conditions (S1)–(S3). Clearly, none of them holds for generically chosen f_2 , f_3 , f_4 :

 $(S_1) \ \gcd(f_3, f_4) \neq 1,$ $(S_2) \ \gcd(g_{23}, g_{24}) \neq 1,$ $(S_3) \ \gcd(g_{34}, g_{24}) \neq 1.$

8.7. We show that $f_3 \equiv 0$ leads to an exceptional case. Assume that (S_1) is excluded and $f_3 \equiv 0$. From (8.2) we get $(f_2 - t\xi)(4f_4 - \xi^2) \equiv 0$, hence

$$f_2 - t\xi \equiv 0$$
 or $4f_4 - \xi^2 \equiv 0$.

 $f_2 \equiv t\xi$, together with (8.3), gives $4f_4 \equiv \xi^2$ since $t \neq 0$. Conversely, $4f_4 \equiv \xi^2$ and (8.4) imply $f_4(f_2 - t\xi) \equiv 0$, and $f_4 \neq 0$ since $\gcd(f_3, f_4) = 1$. So we see that $f_3 \equiv f_2 - t\xi \equiv 4f_4 - \xi^2 \equiv 0$ hold in any case, and therefore also $f_3 \equiv f_2^2 - 4t^2f_4 \equiv 0$. In particular, there exists a scalar λ such that $\deg \gcd(f_3, f_2^2 + \lambda f_4) \geq 2$. By Proposition 7.1 this means we are in the following exceptional case:

 $(S_4) \Psi_{3,4}(f_3, f_2^2, f_4) = 0.$

8.8. Excluding (S_1) and (S_4) we have $f_3 \neq 0$, and therefore get

$$g_{23}g_{34} - g_{24}^2 \equiv 0 \tag{8.11}$$

from (8.10). The assumption $g_{24} \equiv 0$ leads to one of (S_2) or (S_3) . Excluding those we have in addition $g_{24} \neq 0$.

8.9. We finally assume that $(S_1)-(S_4)$ are excluded, so (8.11) holds with $g_{24} \neq 0$. We show that this again leads to an exceptional case. Multiply (8.9) with g_{23} , rewrite using (8.11) and cancel the factor g_{24} to get

$$g_{23}\xi^2 + 2f_3g_{24} - 4f_4g_{23} \equiv 0.$$
(8.12)

Multiply (8.4) with g_{23} and use (8.12) to obtain

$$8tf_4g_{23}\xi \equiv (8f_2f_4 - 3f_3^2)g_{23} + 2f_2f_3g_{24}.$$

Squaring this congruence and using (8.12) once more we finally get

$$128t^2f_4^2g_{23}(2f_4g_{23} - f_3g_{24}) - \left((8f_2f_4 - 3f_3^2)g_{23} + 2f_2f_3g_{24}\right)^2 \equiv 0.$$
(8.13)

8.10. Consider

$$P := g_{23}g_{34} - g_{24}^2,$$

$$Q := f_4^2 g_{23} (2f_4 g_{23} - f_3 g_{24}),$$

$$R := (8f_2 f_4 - 3f_3^2)g_{23} + 2f_2 f_3 g_{24}$$

These are integral polynomials in the coefficients of f_2 , f_3 , f_4 . For generically chosen f_i we have $\deg(P) = 8$, $\deg(Q) = 18$ and $\deg(R) = 9$. We have shown that the assumption in Proposition 8.1 leads either to one of $(S_1)-(S_4)$, or to the existence of a pair $(\lambda, \mu) \neq (0, 0)$ of scalars with $\deg \gcd(P, \lambda Q + \mu R^2) \geq 2$. By Proposition 7.1 and Corollary 7.3, the latter implies one of the following two conditions:

(S₅) disc₈(P) = 0; (S₆) $\Phi_{8,18}(P, Q, R^2) = 0.$

8.11. We still need to show that

$$\Psi_{8,18}(P,Q,R^2) = \operatorname{disc}_8(P) \cdot \Phi_{8,18}(P,Q,R^2) \neq 0$$

for generically chosen f_i . Clearly it suffices to exhibit a single triple (f_2, f_3, f_4) where this number is nonzero. Unfortunately, it seems hard to do this by hand alone, due to the enormous size of the polynomial Φ . With the help of a computer algebra program, there is no difficulty: If we take

$$f_2 = x^2 - x + 1$$
, $f_3 = x^2 - 1$, $f_4 = x^4 + 1$,

then

$$P = g_{23}g_{34} - g_{24}^2 = -24x^8 + 60x^7 - 64x^5 + 56x^4 - 20x^3 - 144x^2 + 88x - 16x^4 - 20x^3 - 144x^2 + 88x - 16x^4 - 20x^3 - 144x^2 + 88x - 16x^4 - 20x^3 - 144x^2 - 16x^4 - 20x^3 - 144x^2 - 16x^4 $

is separable, and $\Phi_{8,18}(P,Q,R^2)$ is an integer with 372 digits that has the prime factorization

Remark 8.12. We can consider $\Phi_{8,18}(P,Q,R^2)$ as an integral polynomial in the coefficients of f_2 , f_3 , f_4 . To find the degree of this polynomial, note that $\Phi_{8,18}(P,Q,R^2)$ is homogeneous of degree $7 \cdot 17 = 119$ in the coefficients of P, and homogeneous of degree $\binom{8}{2} = 28$ in the coefficients of Q and in those of R^2 (Remark 7.4.2). Given that P (resp. Q, resp. R^2) is homogeneous of degree 4 (resp. 7, resp. 8) in (f_2, f_3, f_4) , we conclude that $\Phi_{8,18}(P, Q, R^2)$ is homogeneous of degree

$$119 \cdot 4 + 28 \cdot 7 + 28 \cdot 8 = 896$$

in (the coefficients of) f_2 , f_3 and f_4 .

Remark 8.13. The invariant $\Phi_{8,18}(P,Q,R^2)$ is enormous not only by its degree, but also in terms of the values it produces. If the f_i have small integral coefficients, then $\Phi(P,Q,R^2)$ typically has several hundreds of digits.

Based on the factorization of this invariant in several sample cases with integer coefficients, we suspect that the form $\Phi(P, Q, R^2)$ (of degree 896 in the coefficients of f_2 , f_3 and f_4) decomposes as a product of smaller degree forms.

9. Summary and complements

9.1. Let

$$f = z^4 + f_2 z^2 + f_3 z + f_4 (9.1)$$

where $f_i \in \mathbb{R}[x, y]$ is homogeneous of degree i (i = 2, 3, 4) and f_2 , f_4 , $4f_2f_4 - f_3^2$ are psd. In the course of our proof of Hilbert's theorem we have considered the following exceptional cases:

$$\begin{array}{ll} (E_1) \ \mathrm{disc}_2(f_2) = 0, \\ (E_2) \ f_2 \mid f_3, \\ (E_3) \ \mathrm{disc}_6(4f_2f_4 - f_3^2) = 0, \\ (E_4) \ \mathrm{disc}_3(f_3) = 0, \\ (E_5) \ \mathrm{gcd}(f_3, f_4) \neq 1, \\ (E_6) \ \mathrm{gcd}(g_{23}, g_{24}) \neq 1, \\ (E_7) \ \mathrm{gcd}(g_{24}, g_{34}) \neq 1, \\ (E_8) \ \Phi_{3,4}(f_3, f_2^2, f_4) = 0, \\ (E_9) \ \mathrm{disc}_8(g_{23}g_{34} - g_{24}^2) = 0, \\ (E_{10}) \ \Phi_{8,18}(P, Q, R^2) = 0. \end{array}$$

(Note that the conditions $gcd \neq 1$ can be rephrased as the vanishing of suitable resultants.) For counting inequivalent representations, we also needed to consider the following condition:

$$(E_{11}) \operatorname{gcd}(f_3, 4f_4 - f_2^2) \neq 1.$$

Let us summarize the role of these exceptional cases. For every real number t we considered the equation

$$C_t: \eta^2 + f_3^2 = (f_2 - t\xi)(4f_4 - \xi^2)$$

with the side conditions $f_2 - t\xi \ge 0$ and $4f_4 - \xi^2 \ge 0$.

We had to exclude (E_1) to ensure that C_0 has a solution (ξ_0, η_0) (for t = 0, Cor. 1.2).

We had to exclude (E_2) , (E_3) to extend any solution of C_0 to a solution of C_t for small |t| (Prop. 4.4).

We had to exclude $f_3 = 0$ (which is contained in (E_4)), and had to assume $gcd(g_t(\xi), h_t(\xi)) = 1$ for all 0 < |t| < 1 and all solutions (ξ, η) of C_t , to extend a solution of C_t for 0 < |t| < 1 into a neighborhood of t (see 6.3).

We had to exclude (E_4) and (E_5) to exclude a linear common divisor of $g_t(\xi)$ and $h_t(\xi)$ (see 6.5).

We had to exclude $(E_5)-(E_{10})$ to exclude an irreducible quadratic common divisor of $g_t(\xi)$ and $h_t(\xi)$ (see Sect. 8, these conditions were labelled $(S_1)-(S_6)$ there).

9.2. We have proved: If the quartic form

$$f = z^4 + f_2 z^2 + f_3 z + f_4$$

is strictly positive definite with $f - z^4 \ge 0$, and if f is sufficiently generic, then any solution of C_0 (for t = 0) can be extended in a unique continuous way to a solution of C_t , for $0 \le t \le 1$. Here "sufficiently generic" means that f avoids the exceptional cases $(E_1)-(E_{10})$. For $i = 1, \ldots, 10$, there exists a nonzero polynomial Ψ_i in (the coefficients of) f such that $\Psi_i(f) \ne 0$ if and only if f avoids (E_i) . Clearly, the set of strictly positive definite forms fwith $\prod_{i=1}^{10} \Psi_i(f) \ne 0$ is dense in the space of all psd forms of shape (9.2). By 3.6, it follows that any psd form (9.2) is a sum of three squares.

Example 9.3. An explicit example of a positive definite form f which is "sufficiently generic" is

$$f = z^4 + (x^2 - xy + y^2)z^2 + (x^2 - y^2)yz + (x^4 + y^4).$$

That is, f avoids all exceptional conditions $(E_1)-(E_{11})$. (See 8.11 for (E_9) and (E_{10}) ; the other conditions are readily checked except possibly (E_8) , which is avoided since $\Phi_{3,4}(f_3, f_2^2, f_4) = 56$.)

9.4. Along our proof of Hilbert's theorem, we needed only little extra effort to obtain partial information on the number of inequivalent representations of a psd form f as a sum of three squares. (See Definition 2.5 for the meaning of equivalence of representations.) Let us review and complete these results:

Theorem 9.5. Let f be a psd form.

- (a) When f has a real zero and is otherwise sufficiently generic, then f has precisely 4 inequivalent representations.
- (b) When f is strictly positive and sufficiently generic, then f has precisely 8 inequivalent representations.

Here, "sufficiently generic" means in (a) that f avoids $(E_1)-(E_3)$, assuming f(0,0,1) = 0. In (b) it means that f avoids $(E_1)-(E_{11})$ if f is normalized into the form $f = z^4 + f_2 z^2 + f_3 z + f_4$ with $f - z^4 \ge 0$.

Proof. (a) was proved in Prop. 2.9. For the proof of (b) assume that f is normalized as above (Lemma 3.1), and consider the linear pencil $f^{(t)}$ as in (4.2). When f avoids $(E_1)-(E_{10})$, we have proved that we can extend every solution (ξ_0, η_0) of C_0 (at time t = 0) along this pencil to a solution (ξ, η) of C_1 (at time t = 1), and that locally this extension is everywhere

unique. Hence, for t = 1 there are at least as many solutions (ξ, η) as for t = 0, namely 16 (see 2.7). If we also exclude (E_{11}) , then Corollary 3.9 shows that for f (i.e., for t = 1) these 16 pairs (ξ, η) correspond to precisely 8 inequivalent representations. In order to show that there are no further representations of f, we need to show that for $t \to 0$ the solutions $(\xi^{(t)}, \eta^{(t)})$ of C_t remain bounded, and thus converge to solutions for t = 0. But this is obvious since we have $4f_4 - (\xi^{(t)})^2 \ge 0$ for all t.

Remark 9.6. These findings are in agreement with the results of [7] and [10]. As far as we know, this is the first time that results on the number of inequivalent representations have been obtained by elementary methods.

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